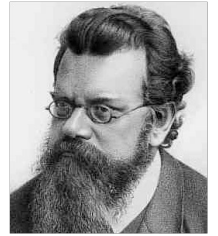


04a. Entropy in Statistical Mechanics: Boltzmann

1. Boltzmann Entropy S_{Boltz}
2. Max-Boltz Distribution
3. S_{Boltz} vs. S_{TD}

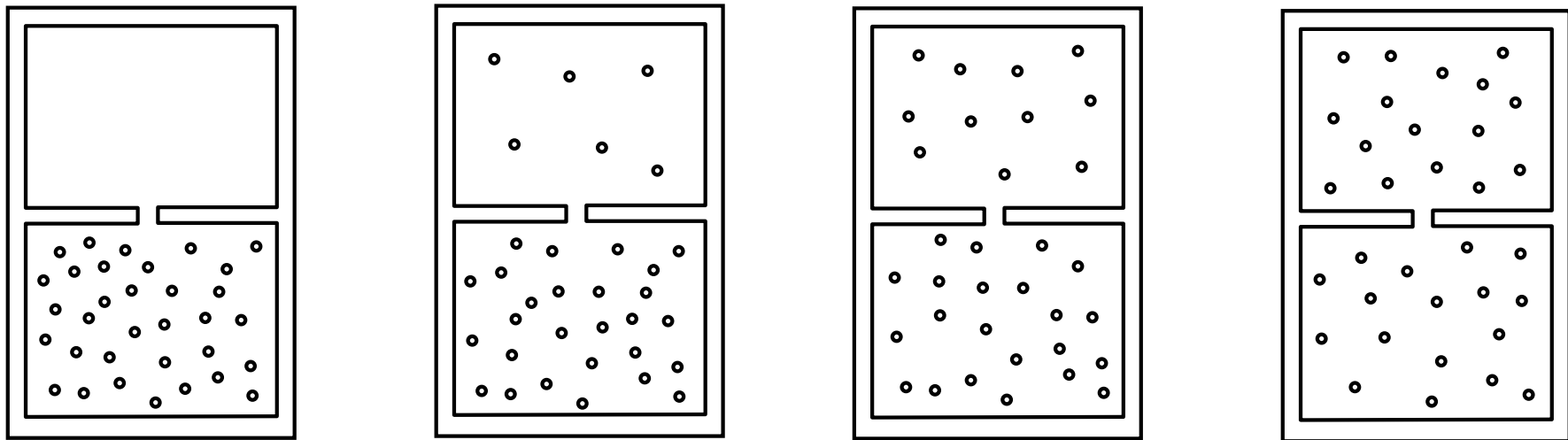
- Goal: To explain the behavior of *macroscopic* systems in terms of the dynamical laws governing their *microscopic* constituents.
 - To provide a micro-dynamical explanation of the Minus 1st and 2nd Laws.



Ludwig Boltzmann
(1844-1906)

1. Boltzmann Entropy S_{Boltz}

- Consider different "macrostates" of a thermally isolated gas at constant energy:



- Why does the gas prefer to be in the equilibrium macrostate (last one)?

- Equilibrium macrostate = state characterized by thermodynamic properties (temp, volume, pressure, etc.) that do not change with time.
- Maximizes S_{TD} !

- Suppose the gas consists of N particles governed by Hamilton's equations of motion (the micro-dynamics).

Def. 1 (Microstate). A **microstate** x of an N -particle system is a specification of the position (3 values) and momentum (3 values) for each of its N particles.

Let $\Gamma = \textit{phase space} = 6N$ -dim space of all possible microstates.

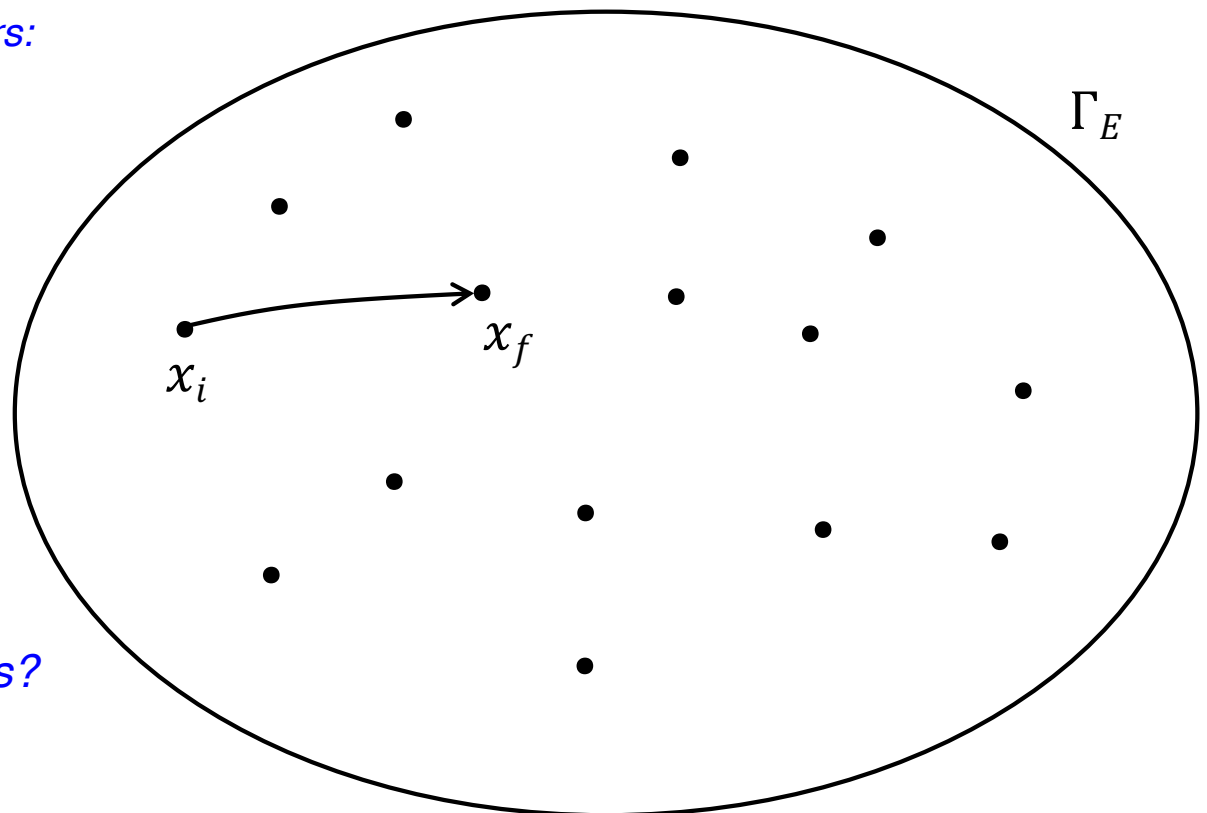
Let $\Gamma_E = \textit{region of } \Gamma \textit{ that consists of all microstates with constant energy } E$.

A point x in Γ_E is labeled by $6N$ numbers:

$$x = (x^{(1)}, y^{(1)}, z^{(1)}, p_x^{(1)}, p_y^{(1)}, p_z^{(1)}, \dots, \\ x^{(N)}, y^{(N)}, z^{(N)}, p_x^{(N)}, p_y^{(N)}, p_z^{(N)})$$

Hamiltonian dynamics maps initial microstate x_i to final microstate x_f .

Can Minus 1st and 2nd Laws be explained in terms of this dynamics?



Def. 2 (Macrostate). A **macrostate** Γ_M of a physical system is a specification of the system in terms of macroscopic properties (pressure, temperature, volume, *etc.*).

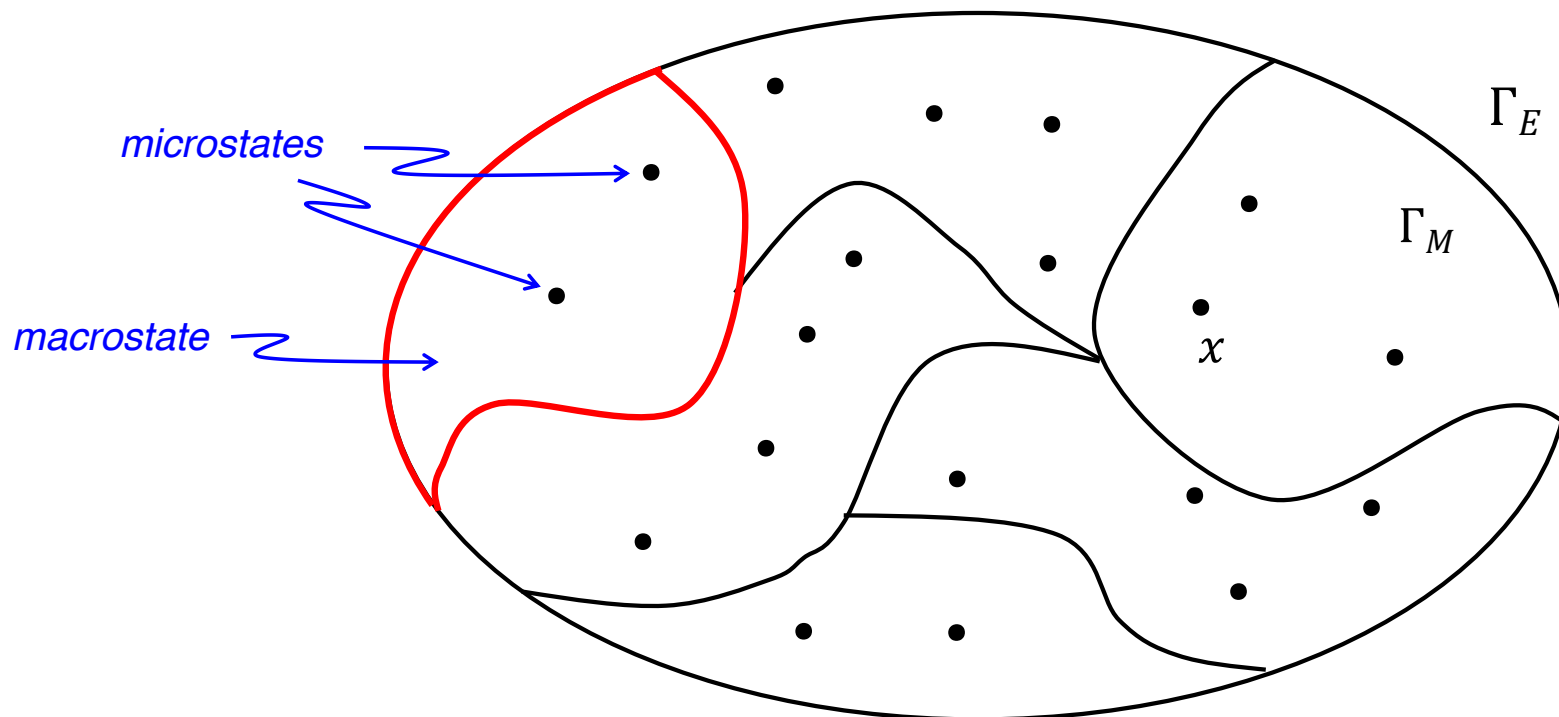
- Relation between microstates and macrostates:



Macrostates supervene
on microstates!

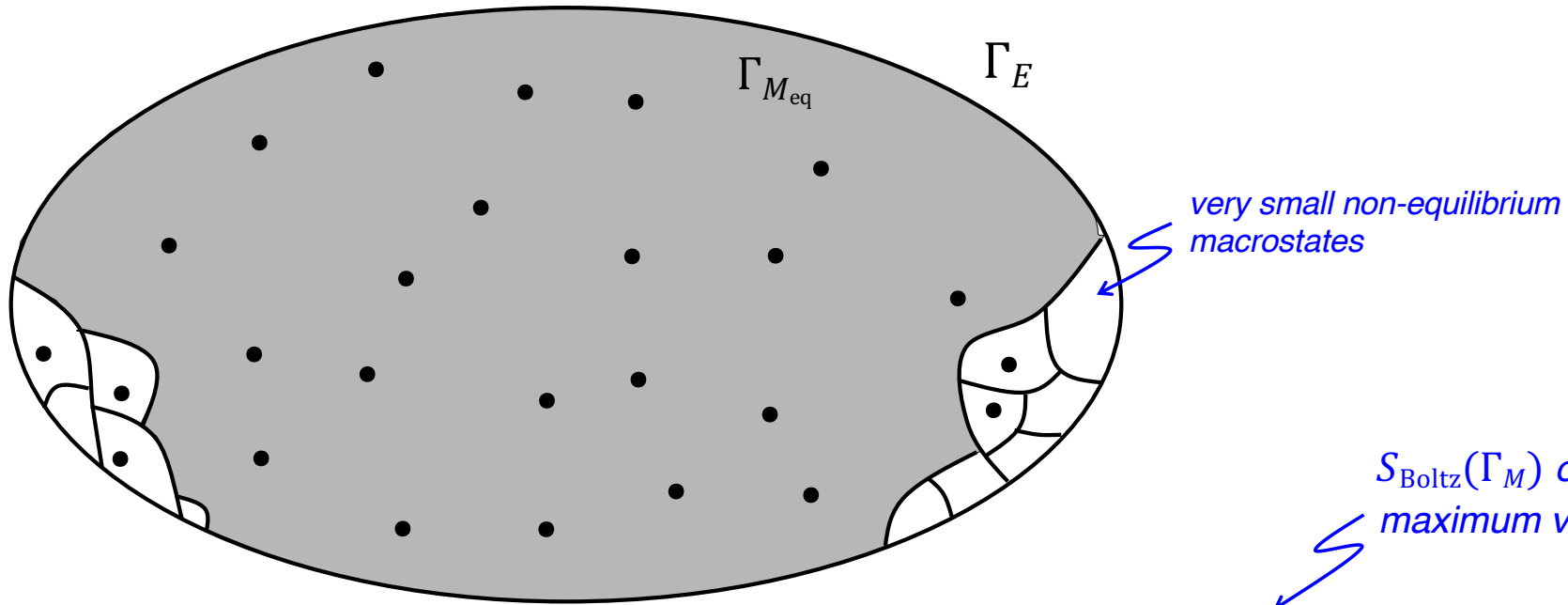
- To each microstate there corresponds exactly one macrostate.
- Many distinct microstates can correspond to the same macrostate.

- So: Γ_E is partitioned into a finite number of regions Γ_M corresponding to macrostates, with each microstate x belonging to one macrostate.



Assumption. The equilibrium macrostate $\Gamma_{M_{eq}}$ is *much larger* than any other macrostate.

↪ *But why?*



Def. 3 (Boltzmann entropy). The **Boltzmann entropy** $S_{Boltz}(\Gamma_M)$ of a macrostate Γ_M of a thermally isolated physical system at constant energy is given by $S_{Boltz}(\Gamma_M) \equiv k \ln |\Gamma_M|$, where $|\Gamma_M|$ is the size of Γ_M .

Claim. S_{Boltz} increases over time because, for any initial microstate x_i , the dynamics will map x_i into $\Gamma_{M_{eq}}$ very quickly, and then keep it there for an extremely long time.

↪ *But why?*

Two Ways to Explain the Approach to Equilibrium:

(a) Appeal to typicality of microstates Goldstein (2001)

Claim. A system approaches equilibrium because equilibrium microstates are *typical* and nonequilibrium microstates are *atypical*.

- Why? For large N , Γ is almost entirely filled up with equilibrium microstates. Hence they are "typical".

- But: What is it about the *dynamics* that evolves atypical states to typical states?
 - "If a system is in an atypical microstate, it does not evolve into an equilibrium microstate *just because* the latter is typical." (Frigg 2009)
 - Need to identify properties of the dynamics that guarantee atypical states evolve into typical states.
 - And: Need to show that these properties are typical.
 - Ex: If the dynamics is *chaotic* (in an appropriate "ergodic" sense), then (under certain conditions), any initial microstate x_i will quickly be mapped into Γ_{eq} and remain there for long periods of time. (Frigg 2009)

(b) Appeal to probability of macrostates

Claim. A system approaches equilibrium because it evolves from low probability macrostates to high probability macrostates, and the equilibrium macrostate has the highest probability.

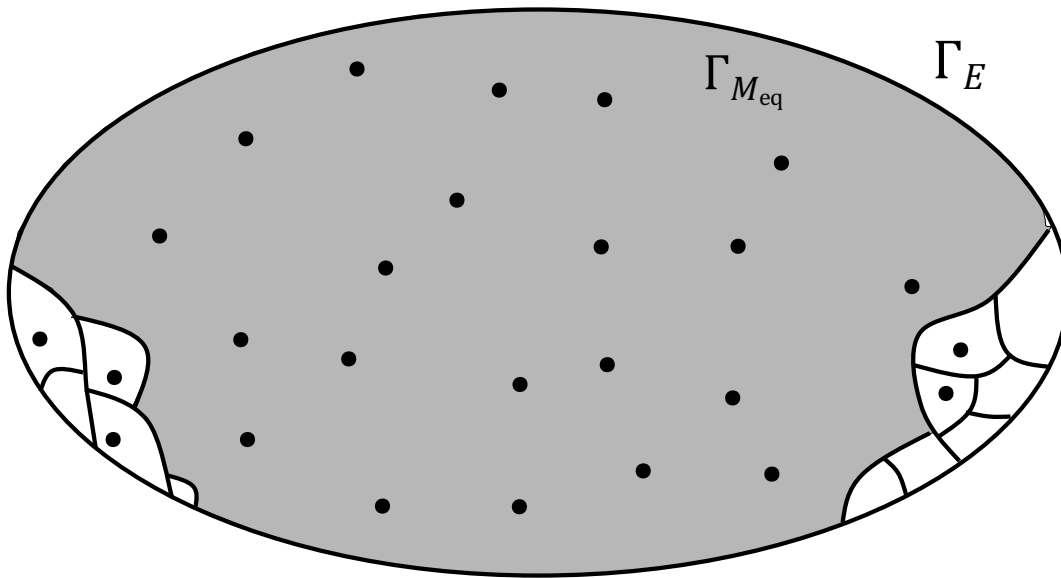
"In most cases, the initial state will be a very unlikely state. From this state the system will steadily evolve towards more likely states until it has finally reached the most likely state, i.e., the state of thermal equilibrium."



- Task: Come up with a way to assign probabilities to macrostates such that the larger the macrostate, the greater the probability of finding a microstate in it.

Story to come: Associate the probability of a macrostate with the number of microstates it contains!

But: What determines the number of microstates in a macrostate?



- If we had a measure function defined on Γ (i.e., a "density" function), then we could use it to calculate the number of points in a given macrostate region.

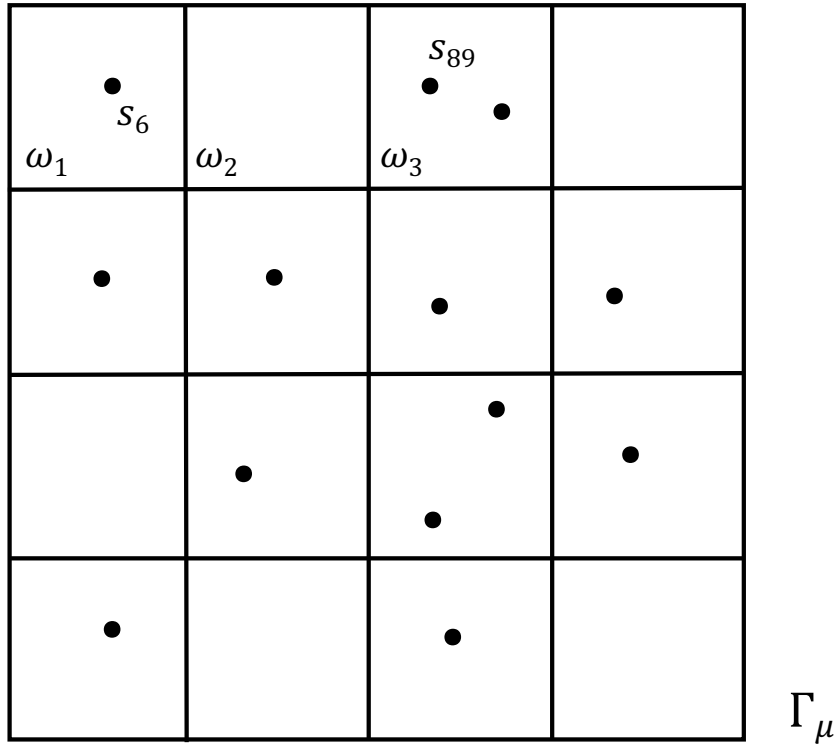
↙ Gibbs' approach!

• Boltzmann's approach:

- A point in a macrostate region of Γ_E is an N -particle microstate, and it corresponds to N points in a *single-particle phase space*, call it Γ_μ .
- A macrostate region of Γ_E corresponds to a *distribution* of N single-particle microstates.
- The number of points in a macrostate region then is the number of possible ways to arrange N single-particle microstates with respect to the corresponding *single-particle distribution!*

↙ To define this thing, Boltzmann coarse-grains the single-particle phase space...

Coarse-graining the single-particle phase space



Arrangement #1:

microstate s_6 in ω_1 , microstate s_{89} in ω_3 , etc.

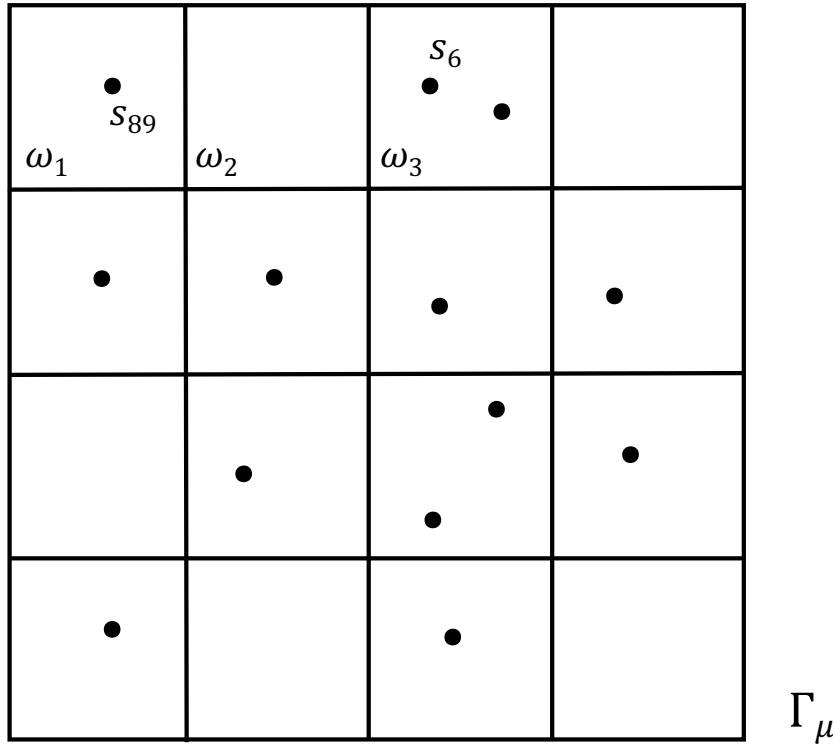
- Start with the 6-dim phase space Γ_μ of a single particle.
- Partition Γ_μ into ℓ cells $\omega_1, \dots, \omega_\ell$ of volume $\Delta\omega = \Delta x^3 \Delta p^3$.
- A microstate of an N -particle system is given by N points in Γ_μ .

← - A point in Γ_μ is a single-particle microstate.
 - $\Gamma_E = N$ copies of Γ_μ

← N points in Γ_μ correspond to one point in Γ_E

Def. 4. An **arrangement** is a specification of *which* single-particle microstates lie in which cells.

Coarse-graining the single-particle phase space



Arrangement #1:

microstate s_6 in ω_1 , microstate s_{89} in ω_3 , etc.

Arrangement #2:

microstate s_{89} in ω_1 , microstate s_6 in ω_3 , etc.

Distribution:

$$D = (1, 0, 2, 0, 1, 1, \dots)$$

1 state in ω_1 , 0 states in ω_2 , 2 states in ω_3 , etc.

- A point in Γ_μ is a single-particle microstate.

- $\Gamma_E = N$ copies of Γ_μ

N points in Γ_μ correspond to one point in Γ_E

- Start with the 6-dim phase space Γ_μ of a single particle.
- Partition Γ_μ into ℓ cells $\omega_1, \dots, \omega_\ell$ of volume $\Delta\omega = \Delta x^3 \Delta p^3$.
- A microstate of an N -particle system is given by N points in Γ_μ .

Def. 4. An **arrangement** is a specification of *which* single-particle microstates lie in which cells.

Def. 5. A **single-particle distribution** $D = (n_1, n_2, \dots, n_\ell)$ is a specification of *how many* single-particle microstates (regardless of *which* ones) lie in each cell.

More than one arrangement can correspond to the same distribution!

How many arrangements $G(D)$ are compatible with a given $D = (n_1, n_2, \dots, n_\ell)$?

• Answer:

$$G(D) = \frac{N!}{n_1! n_2! \dots n_\ell!} = \left(\begin{array}{l} \text{Number of ways to arrange } N \\ \text{distinguishable objects into } \ell \\ \text{bins with capacities } n_1, n_2, \dots, n_\ell. \end{array} \right)$$

$$\begin{aligned} n! &= n(n-1)(n-2)\dots 1 \\ &= \# \text{ of ways to arrange } n \\ &\quad \text{distinguishable objects} \\ 0! &= 1 \end{aligned}$$

Check: Let $D_1 = (N, 0, \dots, 0)$ and $D_2 = (N-1, 1, 0, \dots, 0)$.

$$G(D_1) = \frac{N!}{N!} = 1 \quad \leftarrow \text{Only one way for all } N \text{ particle states to be in } \omega_1.$$

$$G(D_2) = \frac{N!}{(N-1)!} = \frac{N(N-1)(N-2)\dots 1}{(N-1)(N-2)\dots 1} = N \quad \leftarrow \text{There are } N \text{ different ways } \omega_2 \text{ could have one state in it; namely, if } s_1 \text{ was in it, or if } s_2 \text{ was in it, or if } s_3 \text{ was in it, etc..}$$

How many arrangements $G(D)$ are compatible with a given $D = (n_1, n_2, \dots, n_\ell)$?

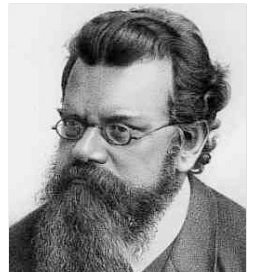
• Answer:

$$G(D) = \frac{N!}{n_1! n_2! \dots n_\ell!} = \left(\begin{array}{l} \text{Number of ways to arrange } N \\ \text{distinguishable objects into } \ell \\ \text{bins with capacities } n_1, n_2, \dots, n_\ell. \end{array} \right)$$

$$\begin{array}{l} n! = n(n-1)(n-2)\dots 1 \\ = \# \text{ of ways to arrange } n \\ \text{distinguishable objects} \\ 0! = 1 \end{array}$$

Assumption 1. The probability of a single-particle distribution D is given by $G(D)$.

"The probability of this distribution $[D]$ is then given by the number of permutations of which the elements of this distribution are capable, that is by the number $[G(D)]$. As the most probable distribution, i.e., as the one corresponding to thermal equilibrium, we again regard that distribution for which this expression is maximal..."



In other words:

Claim. The equilibrium distribution is the distribution that maximizes $G(D)$.

Assumption 2. Each single-particle distribution D corresponds to a macrostate Γ_{M_D} .

← *Why? A system's macroscopic properties (volume, pressure, temp, etc) only depend on how many particles are in particular microstates, and not on which particles are in which microstates.*

What is the size of this macrostate?

- A point (multi-particle microstate) in Γ_E corresponds to an arrangement of single-particle microstates in Γ_μ .
- The size of a macrostate Γ_{M_D} in Γ_E is given by the number of points it contains (the number of arrangements compatible with D) multiplied by a *volume element* of Γ_E .
- A volume element of Γ_E is given by N copies of a volume element $\Delta\omega$ of Γ_μ .

• So: The size of Γ_{M_D} is $|\Gamma_{M_D}| = \left[\begin{array}{l} \# \text{ arrangements} \\ \text{compatible with } D \end{array} \right] \times \left[\begin{array}{l} \text{volume} \\ \text{element of } \Gamma_E \end{array} \right]$

$$= G(D)\Delta\omega^N$$

← *The probability $G(D)$ of D is proportional to the size of Γ_{M_D}*

• Hence: $S_{\text{Boltz}}(\Gamma_{M_D}) = k\ln(G(D)\Delta\omega^N)$

$$= k\ln(G(D)) + Nk\ln(\Delta\omega)$$

$$= \boxed{k\ln(G(D)) + \text{const.}}$$

← *S_{Boltz} as a measure of how probable a macrostate is.*

Other formulations of S_{Boltz} :

$$S_{\text{Boltz}}(\Gamma_{M_D}) = k \ln(G(D)) + \text{const.}$$

$$= k \ln \left(\frac{N!}{n_1! \cdots n_\ell!} \right) + \text{const.}$$

$$= k \ln(N!) - k \ln(n_1!) - \cdots - k \ln(n_\ell!) + \text{const.}$$

$$\approx (Nk \ln N - N) - (n_1 k \ln n_1 - n_1) - \cdots - (n_\ell k \ln n_\ell - n_\ell) + \text{const.}$$

$$= \boxed{-k \sum_{i=1}^{\ell} n_i \ln n_i + \text{const.}}$$

S_{Boltz} in terms of single-particle microstate numbers n_i .

Stirling's approx:

$$\ln n! \approx n \ln n - n$$

$$n_1 + \cdots + n_\ell = N$$

• Let: $p_i = n_i/N = \left(\begin{array}{l} \text{probability of finding a} \\ \text{randomly chosen single-} \\ \text{particle microstate in cell } \omega_i \end{array} \right)$

Probabilities for single-particle microstates (not macrostates)!

• Then: $S_{\text{Boltz}}(\Gamma_{M_D}) = \boxed{-Nk \sum_{i=1}^{\ell} p_i \ln p_i + \text{const.}}$

S_{Boltz} in terms of single-particle microstate probabilities p_i .

• Or: $S_{\text{Boltz}}(\Gamma_{M_D}) = -Nk \int_{\Gamma_\mu} \rho_\mu(x_\mu) \ln \rho_\mu(x_\mu) dx_\mu$

single-particle probability distribution over Γ_μ

2. The Maxwell-Boltzmann Equilibrium Distribution

- What distribution $D^* = (n_1^*, \dots, n_\ell^*)$ maximizes $S_{\text{Boltz}}(n_i)$?

Assume: The n_i are constrained by

$$(a) \sum_{i=1}^{\ell} n_i = N \quad (b) \sum_{i=1}^{\ell} \varepsilon_i n_i = U$$

*Weak interaction assumption:
The total internal energy U = sum of the energies ε_i of single-particle microstates*

- To maximize $S_{\text{Boltz}}(n_i)$, set its derivative to zero and solve for n_i :

$$(d/dn_i)S_{\text{Boltz}}(n_i) = -k \sum_i (d/dn_i)(n_i \ln n_i + \text{const.}) = -k \sum_i (\ln n_i + 1)$$

- Or: $dS_{\text{Boltz}} = -k \sum_i (\ln n_i + 1) dn_i$ *Small changes to S_{Boltz} due only to small changes to n_i*

- Now find values n_i^* that solve:

$$dS_{\text{Boltz}} = -k \sum_i (\ln n_i^* + 1) dn_i = 0$$

subject to constraints $\begin{cases} dN = \sum_i dn_i = 0 \\ dU = \sum_i \varepsilon_i dn_i = 0 \end{cases}$

- Can add arbitrary multiples of the constraints and still get zero:

$$dS_{\text{Boltz}} = \sum_i (-k \ln n_i^* - \alpha - \beta \varepsilon_i) dn_i = 0$$

- So: $k \ln n_i^* + \alpha + \beta \varepsilon_i = 0$ or $n_i^* = e^{-(\alpha + \beta \varepsilon_i)/k} = e^{-\alpha/k} e^{-\beta \varepsilon_i/k}$

Now put this into a (slightly) nicer form...

$$n_i^* = e^{-(\alpha + \beta \epsilon_i)/k} = e^{-\alpha/k} e^{-\beta \epsilon_i/k}$$

$$(a) \sum_{i=1}^{\ell} n_i = N \quad (b) \sum_{i=1}^{\ell} \epsilon_i n_i = U$$

• Enforce (a) on n_i^*

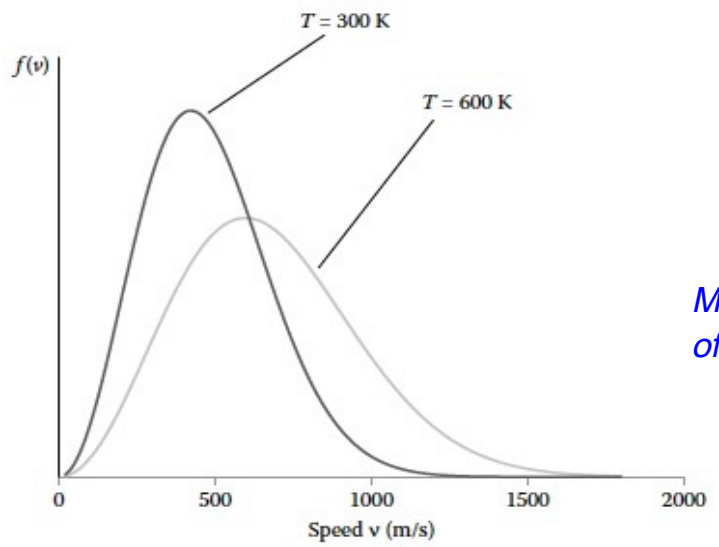
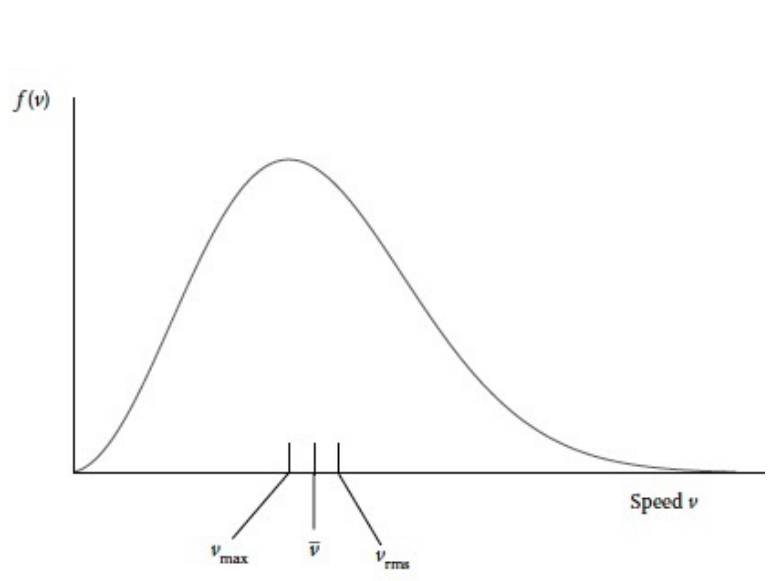
$$\sum_i n_i^* = N = e^{-\alpha/k} \sum_i e^{-\beta \epsilon_i/k} \quad \text{or} \quad e^{-\alpha/k} = N/Z, \quad Z \equiv \sum_i e^{-\beta \epsilon_i/k}$$

• So: $n_i^* = (N/Z) e^{-\beta \epsilon_i/k}$

The "Maxwell-Boltzmann distribution"

• Hence: $D^* = (n_1^*, \dots, n_{\ell}^*) = \left(\frac{N}{Z} e^{-\beta \epsilon_1/k}, \dots, \frac{N}{Z} e^{-\beta \epsilon_{\ell}/k} \right)$

Boltzmann's claim: D^ is the equilibrium distribution*



M-B distribution in terms of velocity (with $\beta = 1/T$)

3. Boltzmann Entropy S_{Boltz} vs. Thermodynamic Entropy S_{TD}

Attempt #1

- Consider: Small changes in internal energy of a reversible process:

<u>Macroscopic point of view</u>	<u>Microscopic point of view</u>
$dU = \delta Q + \delta W$	$dU = d(\sum_i \varepsilon_i n_i)$
$= TdS_{\text{TD}} - PdV$	$= \sum_i \varepsilon_i dn_i + \sum_i n_i d\varepsilon_i$

Assume:

- A change in V is related to a change in single-particle energies ε_i .
- A change in S_{TD} is related to a change in microstate number n_i .

- Suggests: $PdV = -\sum_i n_i d\varepsilon_i$ and $dS_{\text{TD}} = (1/T)\sum_i \varepsilon_i dn_i$

- Note: For the Max-Boltz equilibrium distribution $n_i^* = \frac{N}{Z} e^{-\beta \varepsilon_i/k}$:

$$\begin{aligned}
 dS_{\text{Boltz}}(n_i^*) &= -k \sum_i (\ln n_i^* + 1) dn_i = -k \sum_i \left\{ \ln \frac{N}{Z} + 1 - \beta \varepsilon_i/k \right\} dn_i \\
 &= \beta \sum_i \varepsilon_i dn_i
 \end{aligned}$$

↙ $(\ln \frac{N}{Z} + 1) \sum_i dn_i = 0$

- So: For the M-B equilibrium distribution, $S_{\text{Boltz}} = S_{\text{TD}}$, provided $\beta = 1/T$.

What this shows:

- For a *large number of weakly interacting* particles in an equilibrium state, it is *consistent* to identify the Boltzmann entropy S_{Boltz} with the thermodynamic entropy S_{TD} .

- But:

- Assumes the Maxwell-Boltzmann distribution D^* that maximizes S_{Boltz} is the equilibrium distribution.

Just another way of assuming that the largest macrostate is the equilibrium macrostate.

- Assumes a change in S_{TD} is related to a change in microstate number n_i .

Isn't this what we're trying to show (i.e., $S_{\text{TD}} = S_{\text{Boltz}}$)?

- For thermally isolated processes, S_{TD} absolutely increases or remains constant; whereas there is no absolute law that requires S_{Boltz} to increase or remain constant.

What about the dynamics of a system entails that it will evolve:

- *to the largest macrostate?*
- *to the most typical macrostate?*
- *to the most probable macrostate?*

Attempt #2

Claim. $\Delta S_{\text{Boltz}} = \Delta S_{\text{TD}}$ for free expansion of an ideal gas.

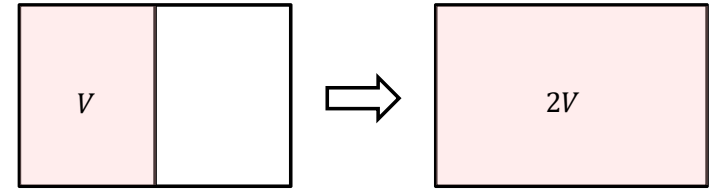
- Macroscopic point of view

- Irreversible: $W = 0, T = \text{const.}, \Delta U = 0.$
- Reversible: $\delta W = -PdV, T = \text{const.}, \Delta U = 0.$

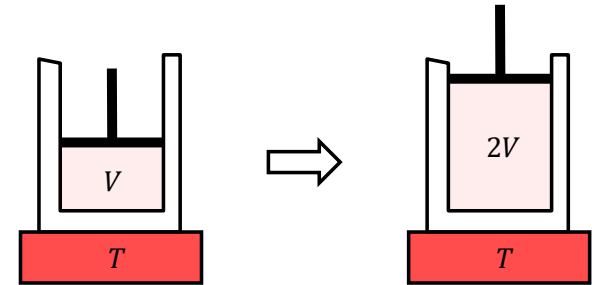
$$\begin{aligned} dS_{\text{TD}} &= \delta Q/T \\ &= (P/T)dV \quad \leftarrow \delta Q = dU - \delta W \\ &= (nR/V)dV \quad \leftarrow PV = nRT \end{aligned}$$

$n = \text{\#moles}$
 $R = \text{const.}$

$$\Delta S_{\text{TD}} = nR \int_V^{2V} \frac{dV}{V} = nR \ln 2$$



irreversible free expansion



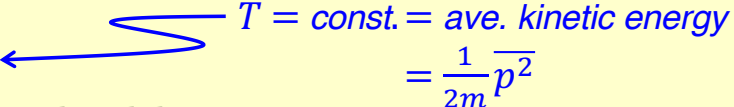
reversible free expansion

- Microscopic point of view

- N = number of gas particles.
- Ω = # arrangements of single-particle microstates before expansion.

Claim. $2^N \Omega$ = # arrangements of single-particle microstates after expansion.

Why?

- Each cell in coarse-grained Γ_μ has volume $\Delta p^3 \Delta x^3$.
- During expansion:
 - Momentum part doesn't change. 
 - Position part changes, since volume doubles.
- After expansion:
 - Each particle has twice as many possible single-particle position microstates it can be in; so for N particles, there are 2^N as many possible single-particle position microstates.

- So:

$$\Delta S_{\text{Boltz}} = k \ln(2^N \Omega) - k \ln \Omega = k \ln 2^N = N k \ln 2 = n R \ln 2$$

 Same expression as ΔS_{TD} !

What this shows:

- For the free expansion of an ideal gas, it is consistent to identify ΔS_{TD} with ΔS_{Boltz} .

- But:

- For this particular physical system, ΔS_{TD} and ΔS_{Boltz} take the same value.

↪ Does this necessarily entail they measure the same quantity?

- For thermally isolated processes, S_{TD} absolutely increases or remains constant; whereas there is no absolute law that requires S_{Boltz} to increase or remain constant.

↪ What about the dynamics of a system entails that it will evolve:

- to the largest macrostate?
- to the most typical macrostate?
- to the most probable macrostate?

Attempt #3

Claim. $S_{\text{Boltz}} = S_{\text{TD}}$ for an ideal gas.

- Macroscopic point of view

$$dU = \delta Q + \delta W = TdS_{\text{TD}} - PdV \quad \leftarrow \text{1st Law for reversible process}$$

$$\begin{aligned} dS_{\text{TD}} &= dU/T + (P/T)dV \\ &= (C_V/T)dT + (nR/V)dV \end{aligned} \quad \leftarrow \begin{array}{l} \text{Constant volume heat capacity} \\ C_V \equiv (\partial U/\partial T)_V \\ = dU/dT, \text{ for } U = U(T) \end{array}$$

- Or:

$$ds_{\text{TD}} = (c_v/T)dT + (R/v)dv \quad \leftarrow \begin{array}{l} \text{Molar quantities} \\ s_{\text{TD}} = S_{\text{TD}}/n \\ c_v = C_V/n \\ v = V/n \end{array}$$

- So:

$$s_{\text{TD}} = c_v \ln T + R \ln v + \text{const.}$$

Def. The **heat capacity** C of a physical system is the amount of absorbed heat δQ needed to change the temperature of the system by dT : $C \equiv \delta Q/dT$.

- Microscopic point of view


- What is S_{Boltz} of a macrostate of an ideal gas with N particles at temp T , heat capacity C_V , volume V ?
- Need to first determine number of possible microstates Ω it can be in.

Claim. $\Omega = \Omega_{\text{position}} \Omega_{\text{momentum}} = [V/\Delta x^3]^N [p_{\text{rms}}^3/\Delta p^3]^N$

Position multi-particle microstates Ω_{position}

- $V =$ region in Γ_{μ} .
- $V/\Delta x^3 =$ # occupied cells in V .
= coarse-grained # position single-particle microstates in V .
- $[V/\Delta x^3]^N =$ coarse-grained # position multi-particle microstates.

Momentum multi-particle microstates Ω_{momentum}

- $p_{\text{rms}} \equiv (\overline{p^2})^{1/2} =$ root mean square momentum.  What gets measured:
Ave. kinetic energy $= \frac{1}{2m} \overline{p^2} = \frac{1}{2m} p_{\text{rms}}^2$
- $p_{\text{rms}}^3/\Delta p^3 =$ # occupied cells in region of single-particle momentum phase space.
= coarse-grained # momentum single-particle microstates.
- $[p_{\text{rms}}^3/\Delta p^3]^N =$ coarse-grained # momentum multi-particle microstates.

- Now simplify Ω

$$\Omega_{\text{pos}}\Omega_{\text{mo}} = [V/\Delta x^3]^N [p_{\text{rms}}^3/\Delta p^3]^N = [p_{\text{rms}}^3 V/\Delta x^3 \Delta p^3]^N$$

$$= \frac{1}{N!} \left[\frac{p_{\text{rms}}^3 V}{(\Delta x \Delta p)^3} \right]^N$$

← Assume indistinguishable particles, so need "overcount" correction factor $1/N!$

$$\approx \left[\frac{eV p_{\text{rms}}^3}{N(\Delta x \Delta p)^3} \right]^N$$

← Stirling's approx: $N! \approx (N/e)^N$, for large N

$$= \left[\frac{eV(2mU)^{3/2}}{N^{5/2}(\Delta x \Delta p)^3} \right]^N$$

← $p_{\text{rms}} = (\overline{p^2})^{1/2}$
 $= (\sum_i p_i^2 / N)^{1/2}$
 $= (2mU/N)^{1/2}$ ← Assume weakly interacting: Total $U = \text{sum of single-particle } U\text{'s.}$

$$= \left[\frac{eV(2mU)^{3/2}}{N^{5/2} h^3} \right]^N$$

← quantum hypothesis: $\Delta x \Delta p = h$

$$= \left[\frac{eV(2mU)^{3/2}}{(nN_A)^{5/2} h^3} \right]^{nN_A}$$

← $N = nN_A$, $n = \text{\# moles}$, $N_A = \text{Avogadro's number}$

$$= \left\{ \left(\frac{V}{n} \right) \left(\frac{U}{n} \right)^{3/2} \left[\frac{e(2m)^{3/2}}{N_A^{5/2} h^3} \right] \right\}^{nN_A}$$

- Can now calculate S_{Boltz} !

$$S_{\text{Boltz}} = k \ln \Omega = k \ln \left\{ \left(\frac{V}{n} \right) \left(\frac{U}{n} \right)^{3/2} \left[\frac{e(2m)^{3/2}}{N_A^{5/2} h^3} \right] \right\}^{n N_A}$$

$$= nk N_A \left[\ln \left(\frac{V}{n} \right) + \frac{3}{2} \ln \left(\frac{U}{n} \right) + \text{const.} \right]$$

- Or:

$$S_{\text{Boltz}} = R \left[\ln v + \frac{3}{2} \ln u + \text{const.} \right]$$

$$= R \ln v + \frac{3}{2} R \ln T + \text{const.}$$

$$= R \ln v + c_v \ln T + \text{const.}$$

Molar quantities
 $S_{\text{Boltz}} = S_{\text{Boltz}}/n, v = V/n, u = U/n$

Ideal monatomic gas
 $u = \frac{3}{2} R T$
 $c_v = \frac{3}{2} R$

- So:

$$S_{\text{Boltz}} = R \ln v + c_v \ln T + \text{const.}$$

Same expression as s_{TD} !

What this shows:

- S_{TD} and S_{Boltz} take the same value for an N particle gas under the following assumptions:
 - (i) The gas particles are indistinguishable.
 - (ii) N is very large (Stirling's approx.).
 - (iii) The gas particles are weakly interacting.
 - (iv) The gas particles obey the (quantum) uncertainty relation $\Delta x \Delta p = h$.
 - (v) The gas is monatomic.
 - (vi) The gas obeys the ideal gas law.

- But (again):
 - Does this mean S_{TD} and S_{Boltz} measure the same quantity?
 - S_{TD} absolutely obeys 2nd Law, while S_{Boltz} does not.