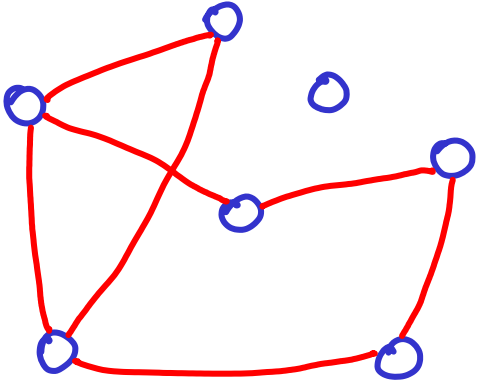
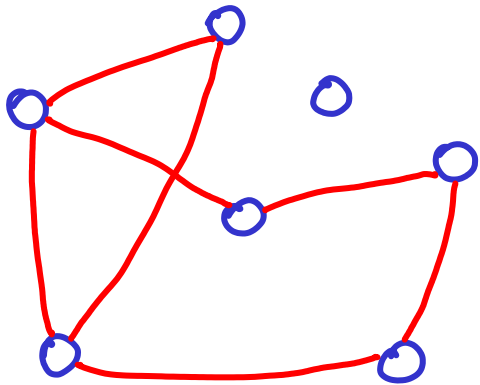


GRAPHS

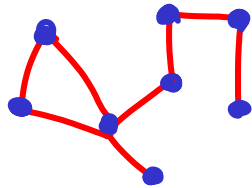


GRAPHS

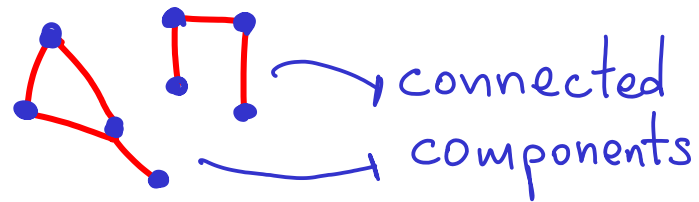


& vertices
& edges

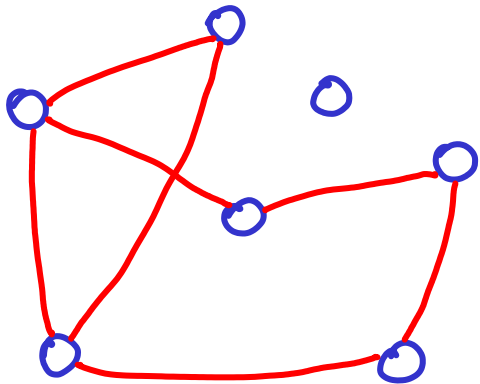
connected



not connected

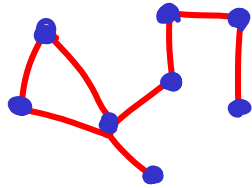


GRAPHS

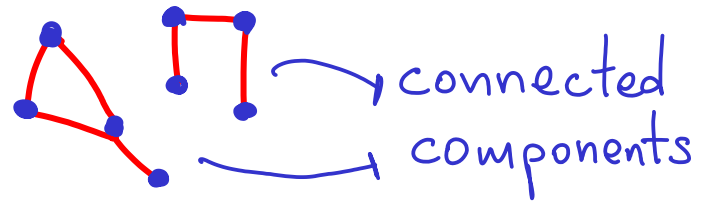


& vertices
& edges

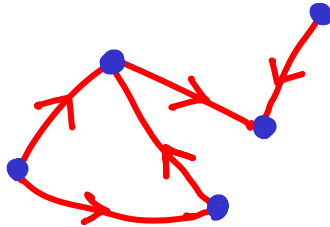
connected



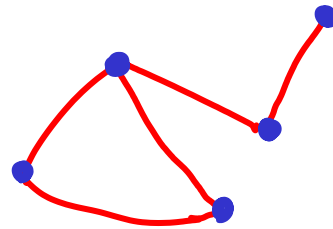
not connected



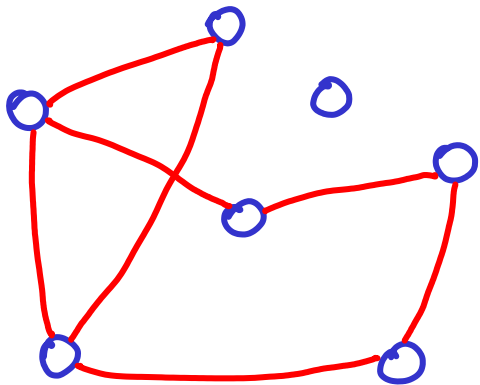
directed



not directed

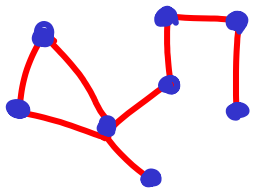


GRAPHS

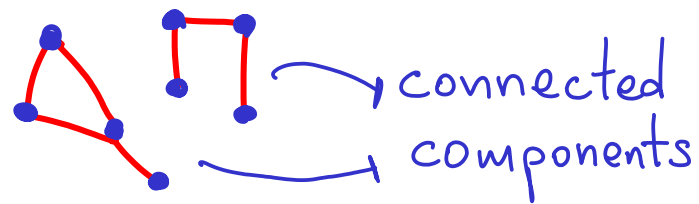


& vertices
& edges

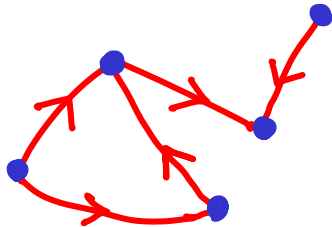
connected



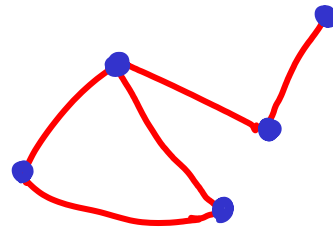
not connected



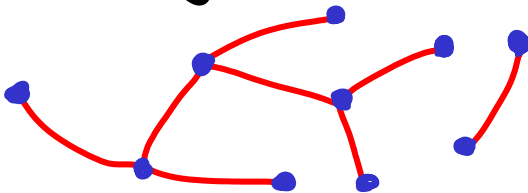
directed



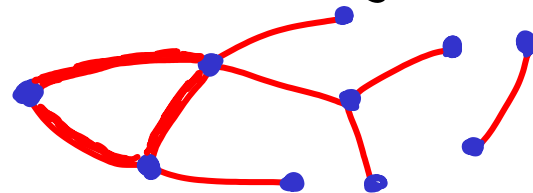
not directed



acyclic

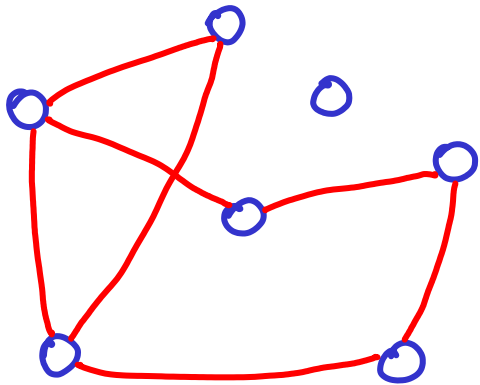


not acyclic



etc

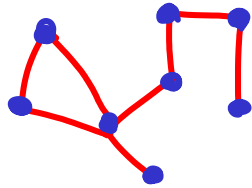
GRAPHS



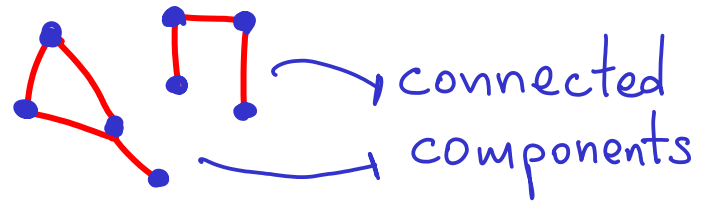
$$G = \{V, E\}$$

& vertices
& edges

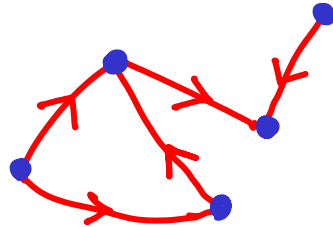
connected



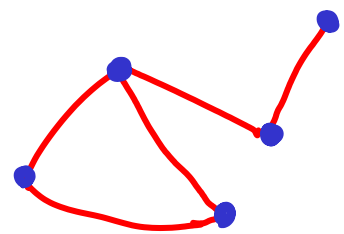
not connected



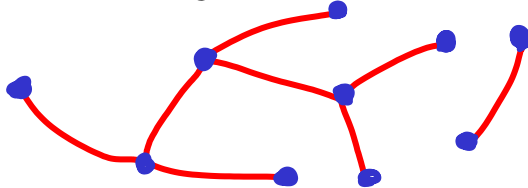
directed



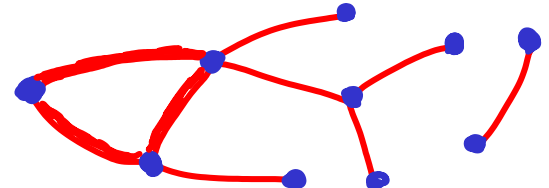
not directed



acyclic

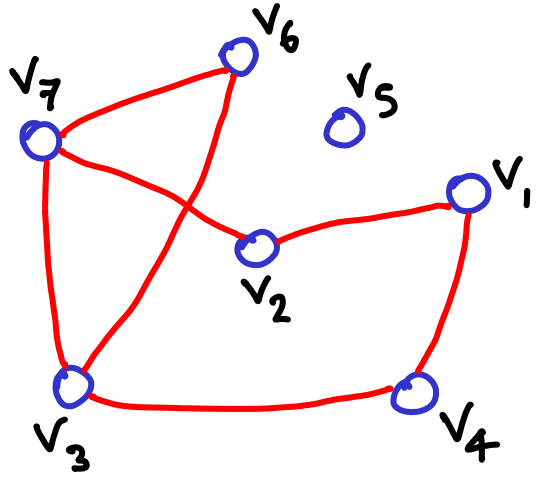


not acyclic



etc

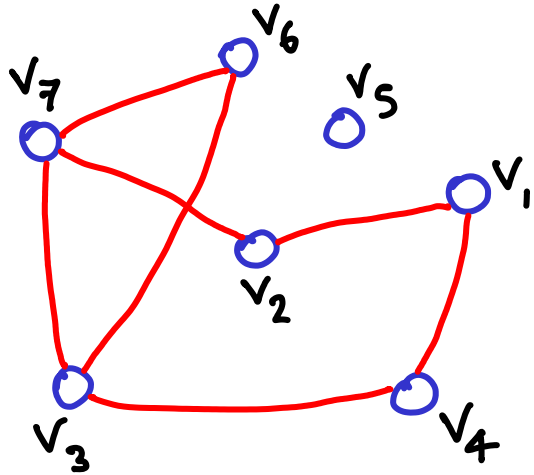
GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

GRAPHS



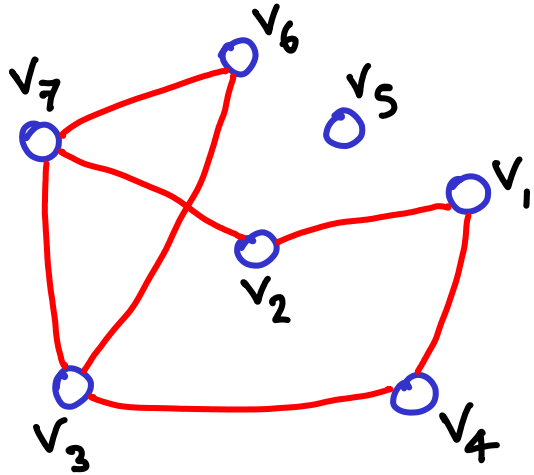
$$G = \{V, E\}$$

& vertices
& edges

	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	1	0	0	0	0	0	1
3	0	0	0	1	0	1	1
4	1	0	1	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	1	0	0	0	1
7	0	1	1	0	0	1	0

} Adjacency matrix

GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

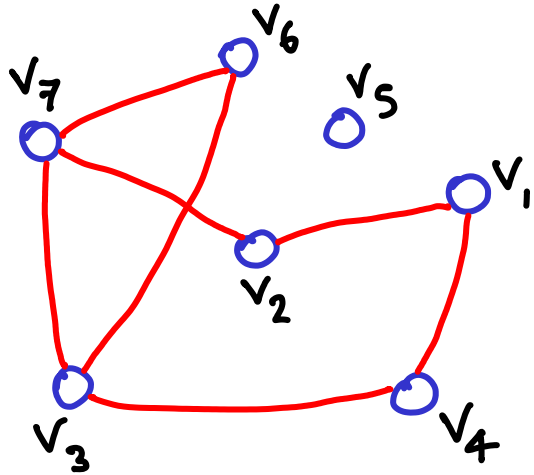
	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	1	0	0	0	0	0	1
3	0	0	0	1	0	1	1
4	1	0	1	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	1	0	0	0	1
7	0	1	1	0	0	1	0

Adjacency matrix

size: $|V|^2$

(symmetric for
undirected)

GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	1	0	0	0	0	0	1
3	0	0	0	1	0	1	1
4	1	0	1	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	1	0	0	0	1
7	0	1	1	0	0	1	0

Adjacency list

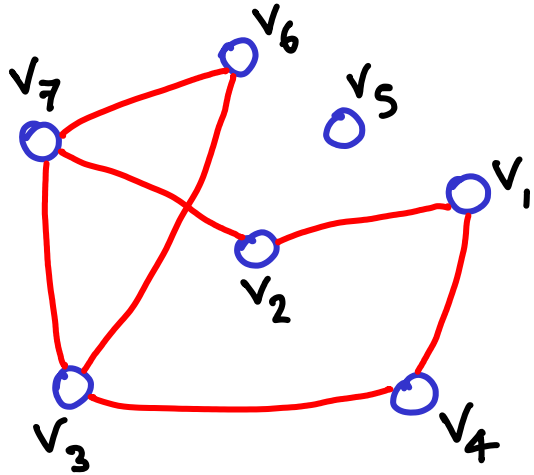
Adjacency matrix

size: $|V|^2$

(symmetric for
undirected)

1 \rightarrow 2 \rightarrow 4
2 \rightarrow 1 \rightarrow 7
3 \rightarrow 4 \rightarrow 6 \rightarrow 7
4 \rightarrow 1 \rightarrow 3
5
6 \rightarrow 3 \rightarrow 7
7 \rightarrow 2 \rightarrow 3 \rightarrow 6

GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	1	0	0	0	0	0	1
3	0	0	0	1	0	1	1
4	1	0	1	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	1	0	0	0	1
7	0	1	1	0	0	1	0

Adjacency matrix

size: $|V|^2$

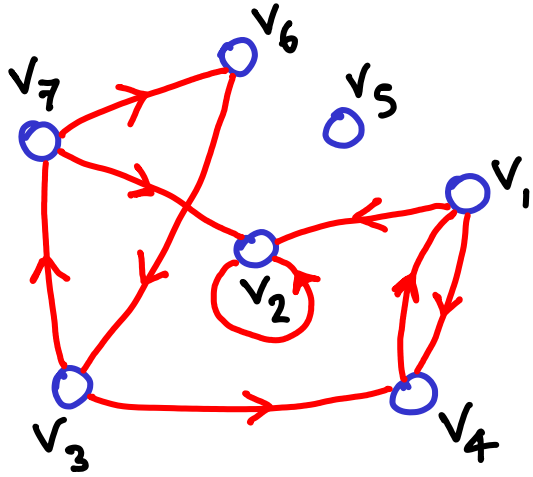
(symmetric for
undirected)

Adjacency list

size: $|V| + 2|E|$
(undirected)

1 \rightarrow 2 \rightarrow 4
2 \rightarrow 1 \rightarrow 7
3 \rightarrow 4 \rightarrow 6 \rightarrow 7
4 \rightarrow 1 \rightarrow 3
5
6 \rightarrow 3 \rightarrow 7
7 \rightarrow 2 \rightarrow 3 \rightarrow 6

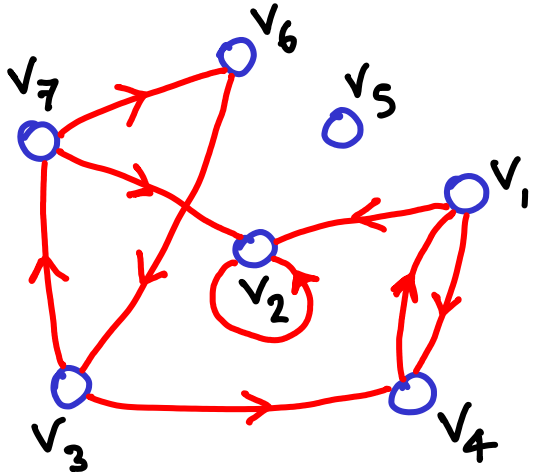
GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

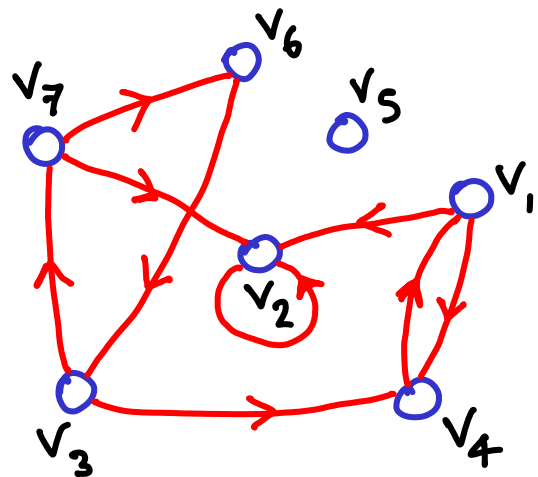
	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	0	1	0	0	0	0	0
3	0	0	0	1	0	0	1
4	1	0	0	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	1	0	0	0	0
7	0	1	0	0	0	1	0

Adjacency matrix

size: $|V|^2$

(directed or not)

GRAPHS



$$G = \{V, E\}$$

& vertices
& edges

	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	0	1	0	0	0	0	0
3	0	0	0	1	0	0	1
4	1	0	0	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	1	0	0	0	0
7	0	1	0	0	0	1	0

Adjacency matrix

size: $|V|^2$

(directed or not)

Adjacency list

size: $|V| + |E|$
(directed)

1 \rightarrow 2 \rightarrow 4

2 \rightarrow 2

3 \rightarrow 4 \rightarrow 7

4 \rightarrow 1

5

6 \rightarrow 3

7 \rightarrow 2 \rightarrow 6

Adjacency matrix size: $O(|V|^2)$

Adjacency list size: $O(|V| + |E|)$

} directed or not

Adjacency matrix size: $O(|V|^2)$ } directed or not
Adjacency list size: $O(|V| + |E|)$ }

Same for "dense" graphs, i.e. $|E| \sim |V|^2$

Adjacency matrix size: $O(|V|^2)$ } directed or not
Adjacency list size: $O(|V| + |E|)$ }

Same for "dense" graphs, i.e. $|E| \sim |V|^2$

Query adjacency : Matrix ?
(is v_j my neighbor ?) List ?

Adjacency matrix size: $O(|V|^2)$ } directed or not
Adjacency list size: $O(|V| + |E|)$ }

Same for "dense" graphs, i.e. $|E| \sim |V|^2$

Query adjacency : Matrix $O(1)$
(is v_j my neighbor ?) List $O(|V|)$

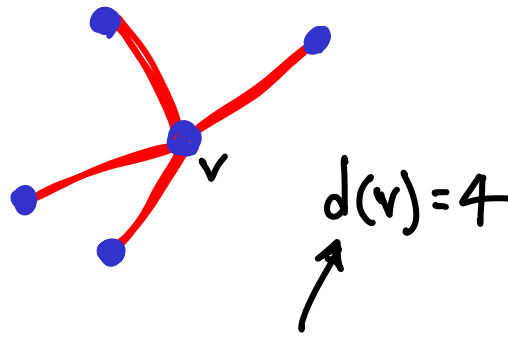
Adjacency matrix size: $O(|V|^2)$ } directed or not
Adjacency list size: $O(|V| + |E|)$ }

Same for "dense" graphs, i.e. $|E| \sim |V|^2$

Query adjacency :
(is v_j my neighbor ?)

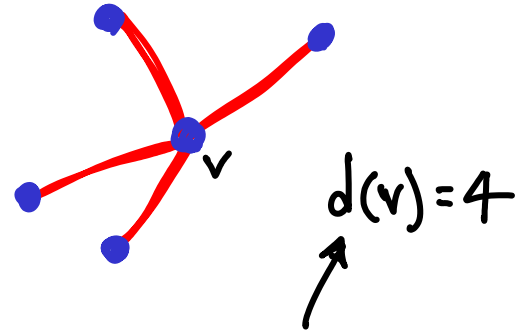
Matrix $O(1)$
List $O(|V|)$

but really $O(\text{degree}(v))$



Adjacency matrix size: $O(|V|^2)$
Adjacency list size: $O(|V| + |E|)$ } directed or not

Same for "dense" graphs, i.e. $|E| \sim |V|^2$



Query adjacency :
(is v_j my neighbor ?)

Matrix $O(1)$
List $O(|V|)$

but really $O(\text{degree}(v))$

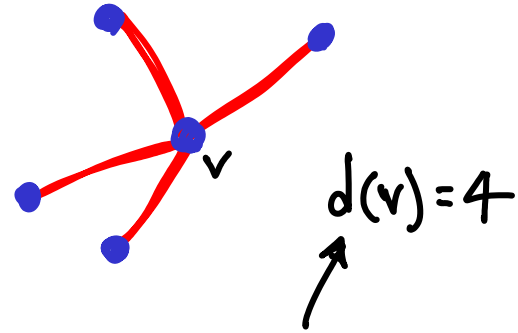
Enumerate neighbors :
(of one vertex)

List ?

Matrix ?

Adjacency matrix size: $O(|V|^2)$
Adjacency list size: $O(|V| + |E|)$ } directed or not

Same for "dense" graphs, i.e. $|E| \sim |V|^2$



Query adjacency :
(is v_j my neighbor ?)

Matrix $O(1)$

List $O(|V|)$

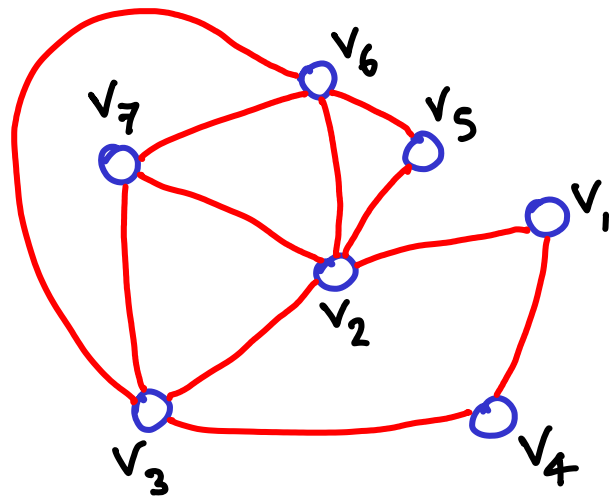
but really $O(\text{degree}(v))$

Enumerate neighbors :
(of one vertex)

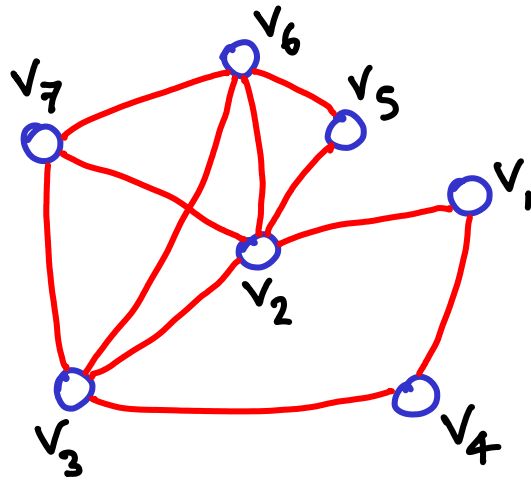
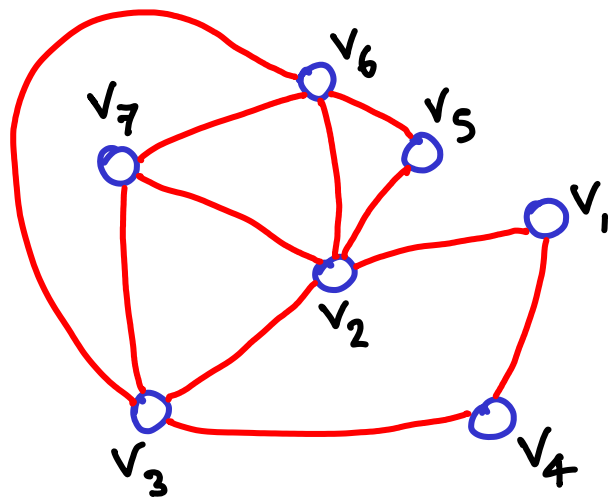
List $O(\text{degree})$

Matrix $O(|V|)$

PLANE GRAPH
no crossings

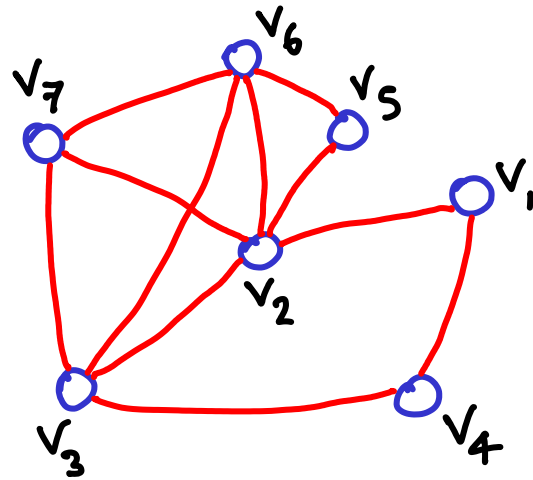
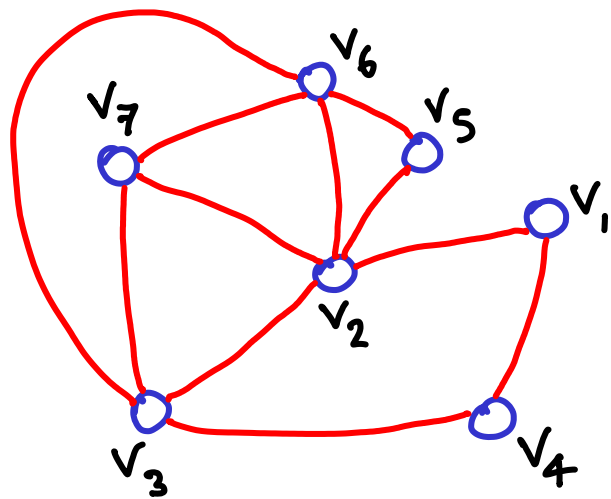


PLANE GRAPH
no crossings



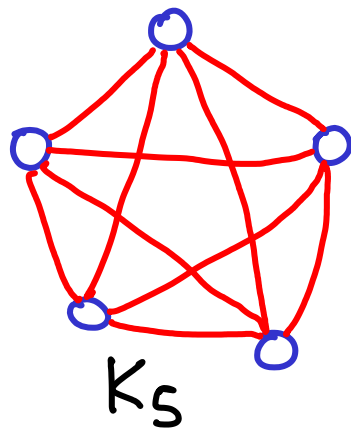
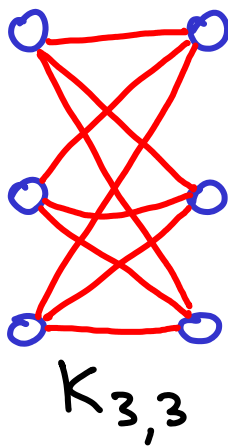
PLANAR GRAPH
can redraw
without crossings

PLANE GRAPH
no crossings

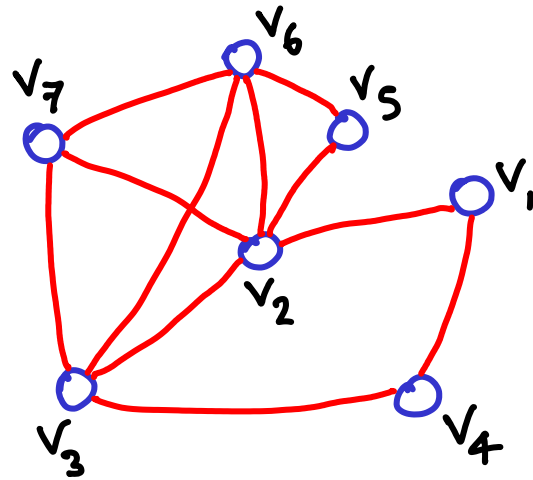
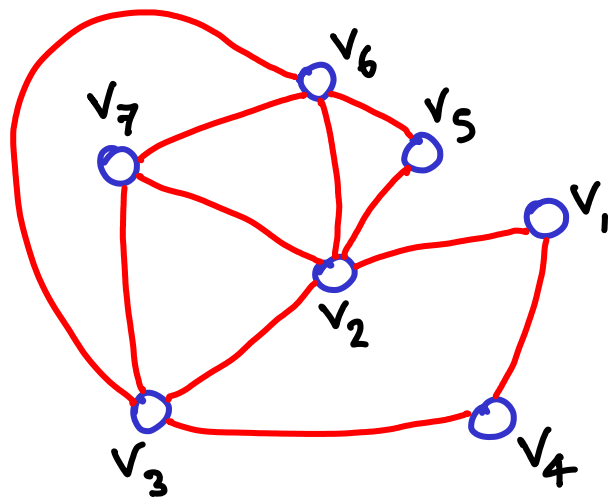


PLANAR GRAPH
can redraw
without crossings

Non-planar graphs
(can't redraw)

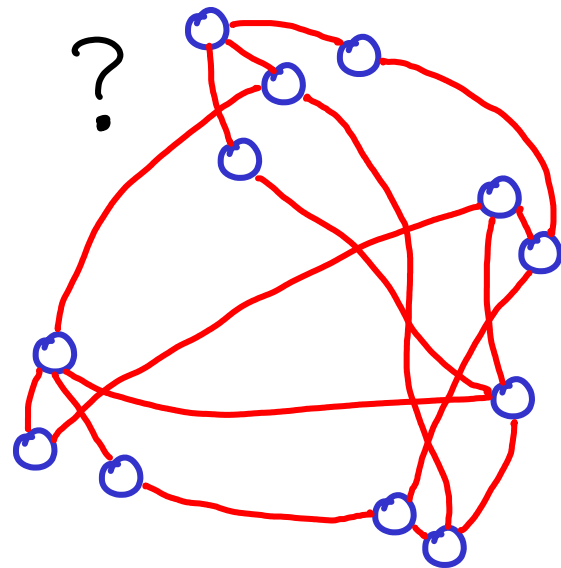
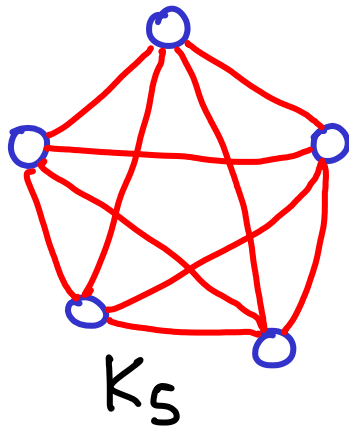
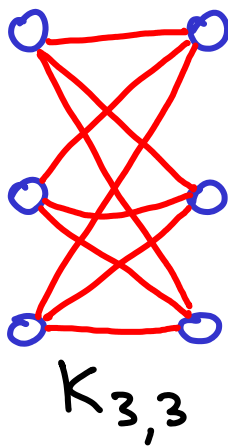


PLANE GRAPH
no crossings

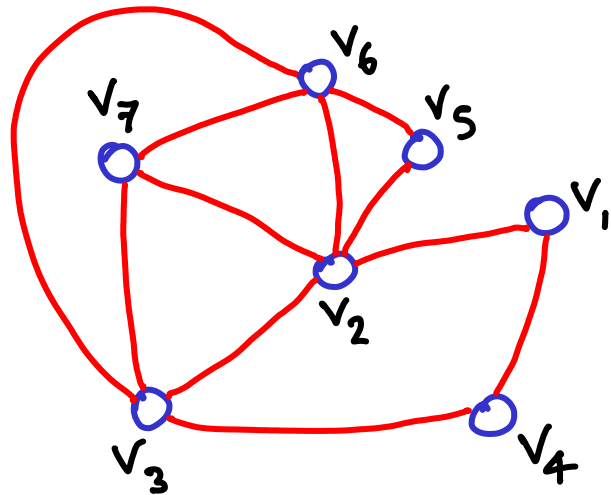


PLANAR GRAPH
can redraw
without crossings

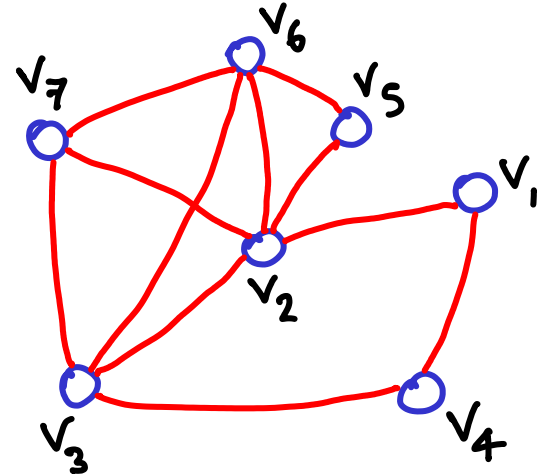
Non-planar graphs
(can't redraw)



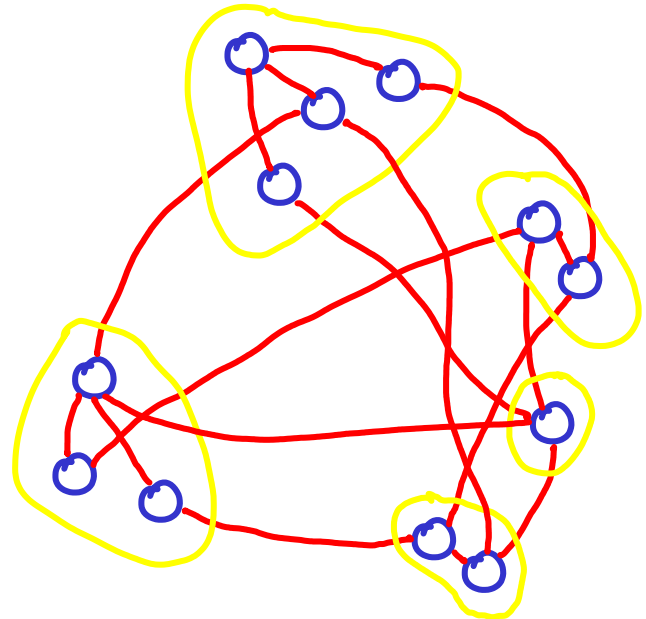
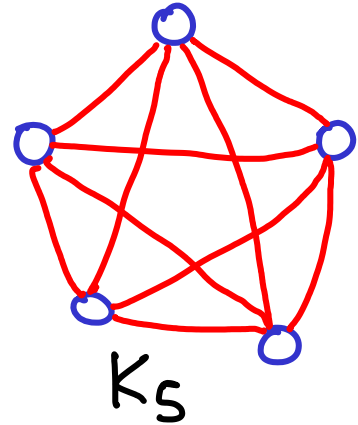
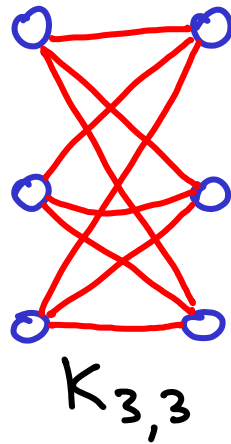
PLANE GRAPH
no crossings



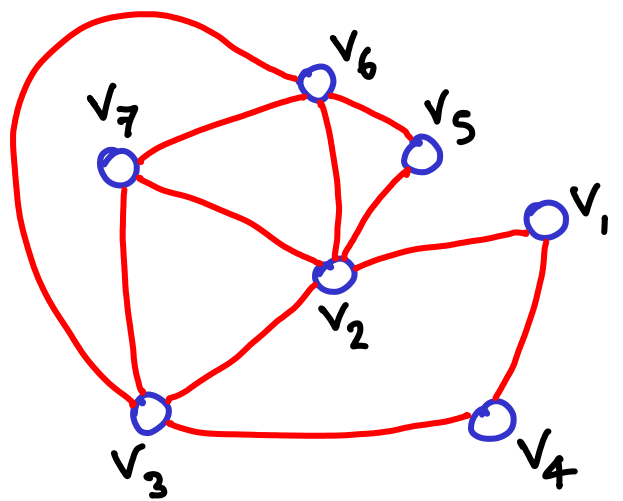
PLANAR GRAPH
can redraw
without crossings



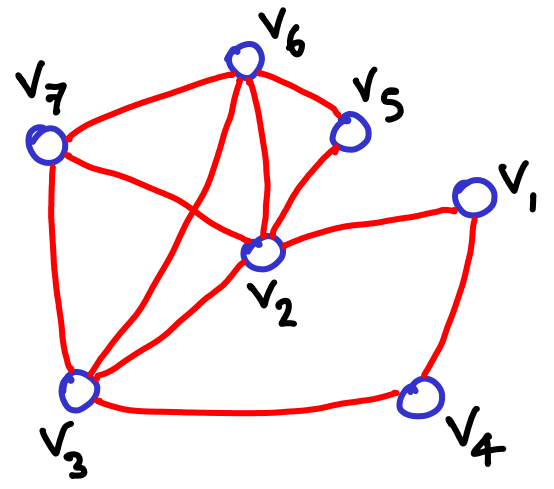
Non-planar graphs
(can't redraw)



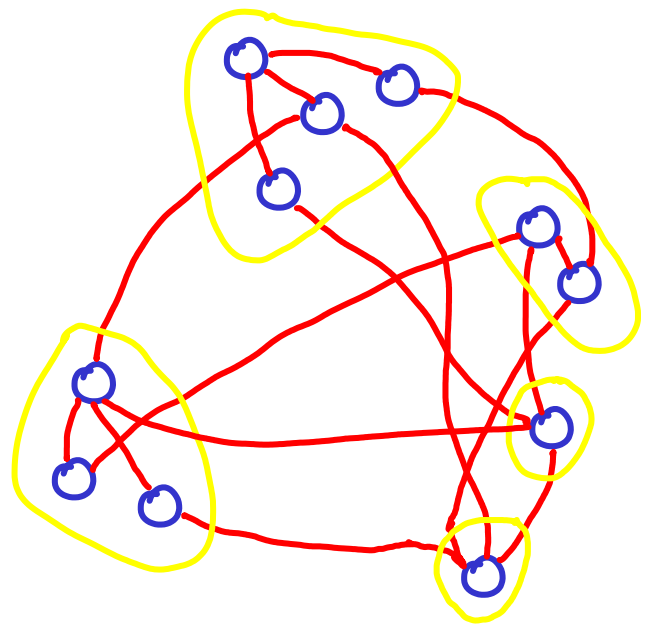
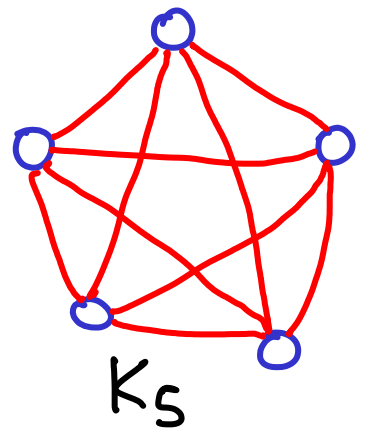
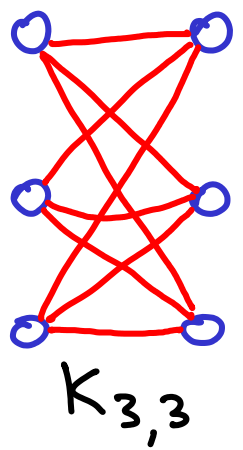
PLANE GRAPH
no crossings



PLANAR GRAPH
can redraw
without crossings

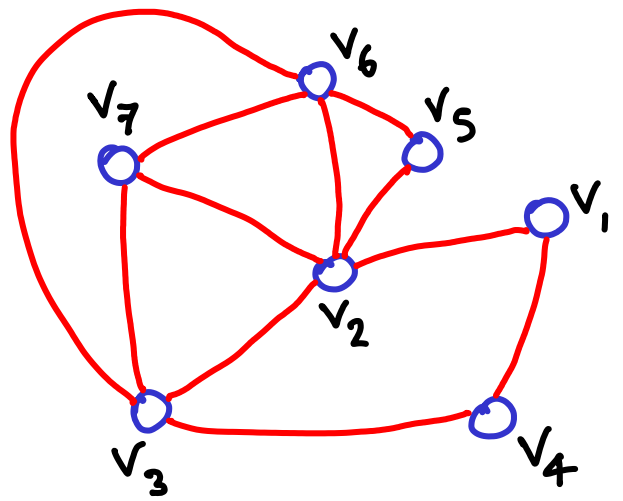


Non-planar graphs
(can't redraw)



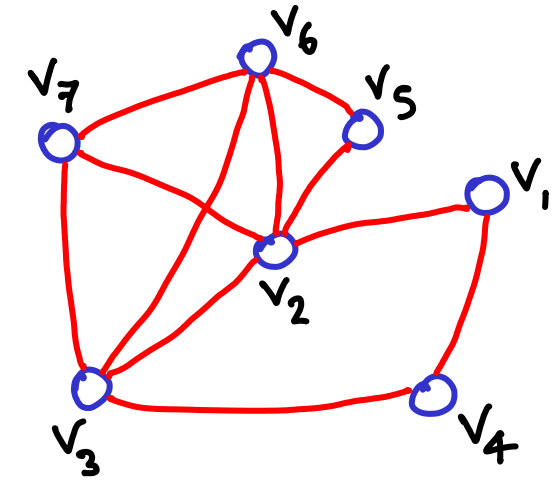
PLANE GRAPH

no crossings

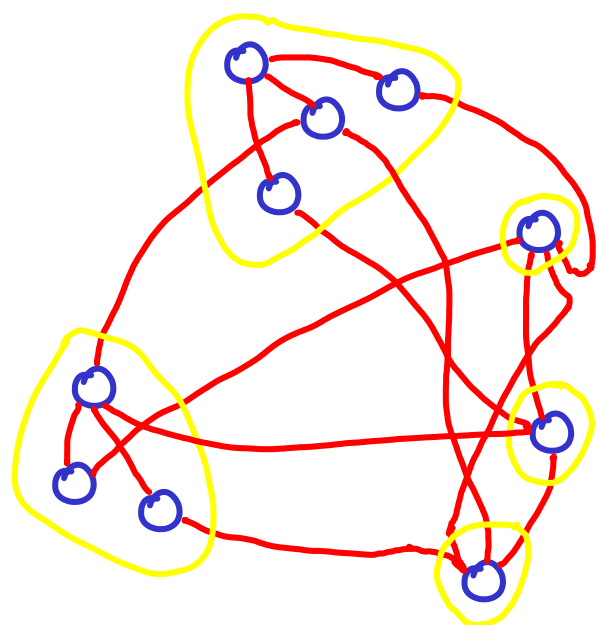
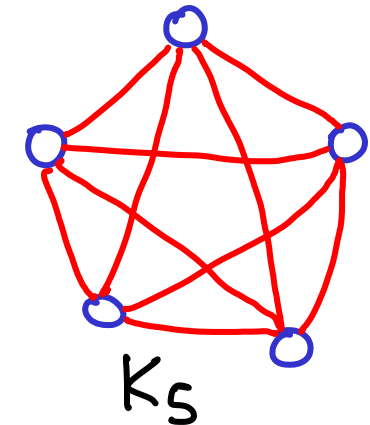
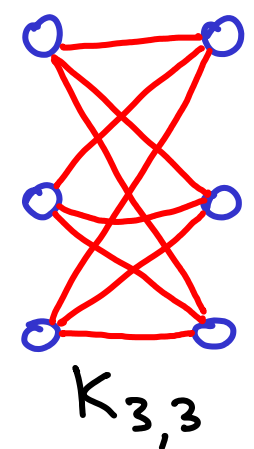


PLANAR GRAPH

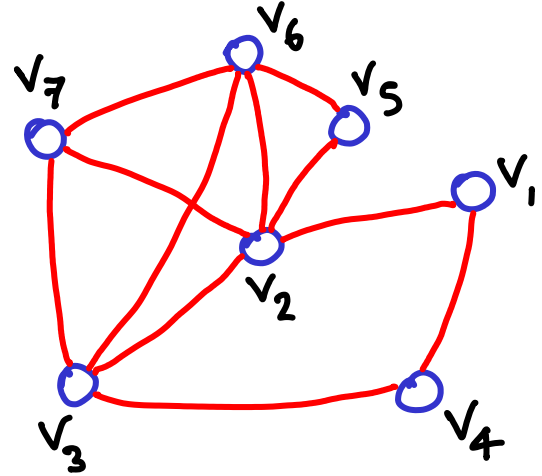
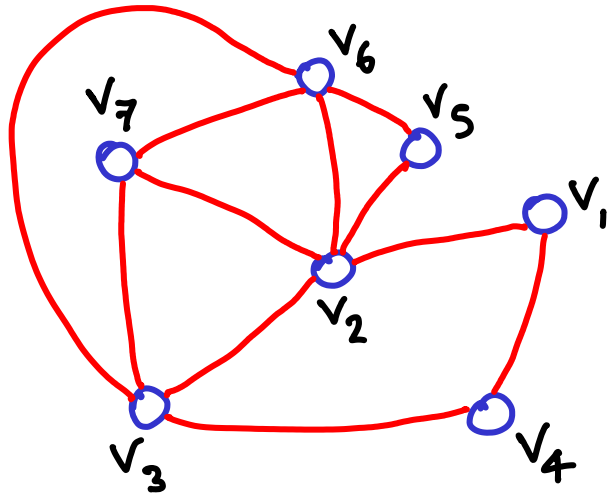
can redraw without crossings



Non-planar graphs
(can't redraw)

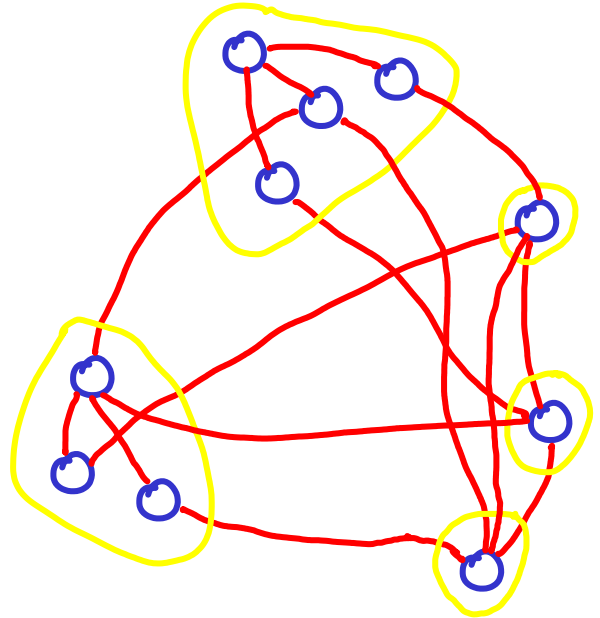
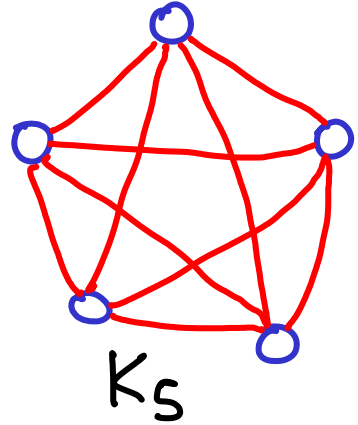
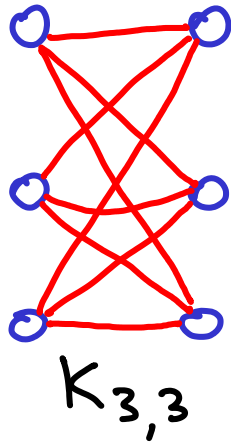


PLANE GRAPH
no crossings

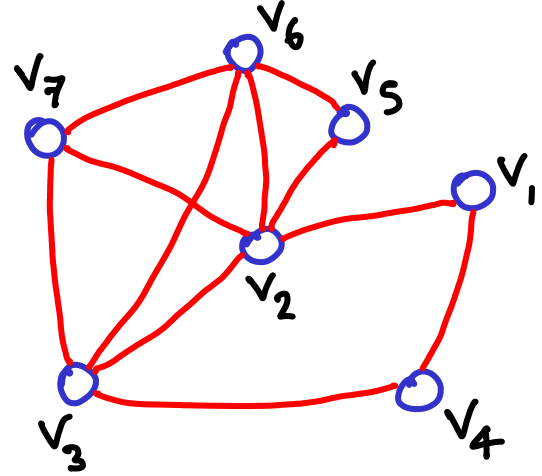
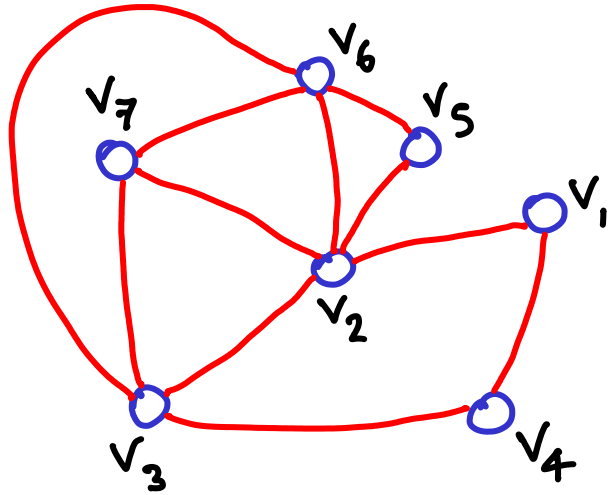


PLANAR GRAPH
can redraw
without crossings

Non-planar graphs
(can't redraw)

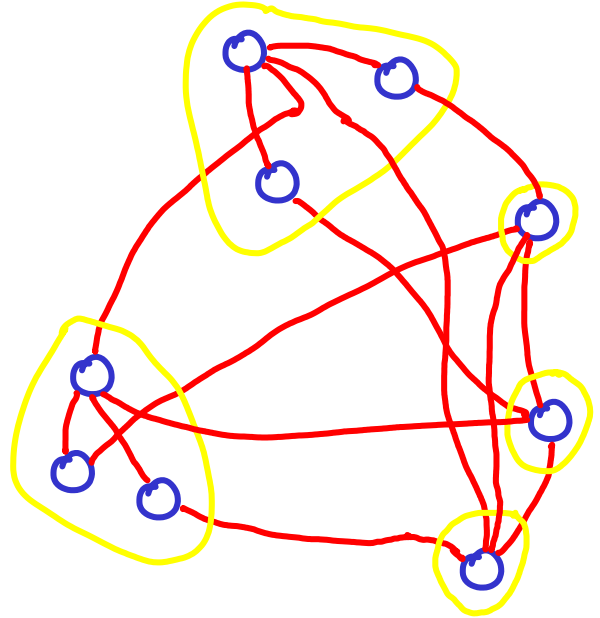
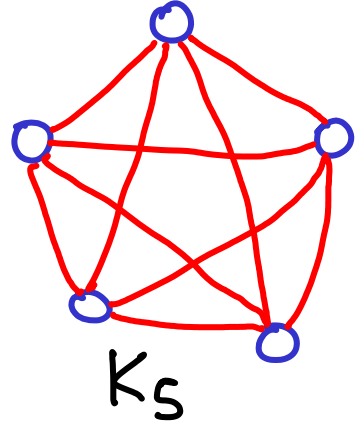
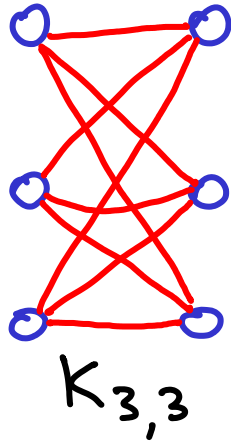


PLANE GRAPH
no crossings

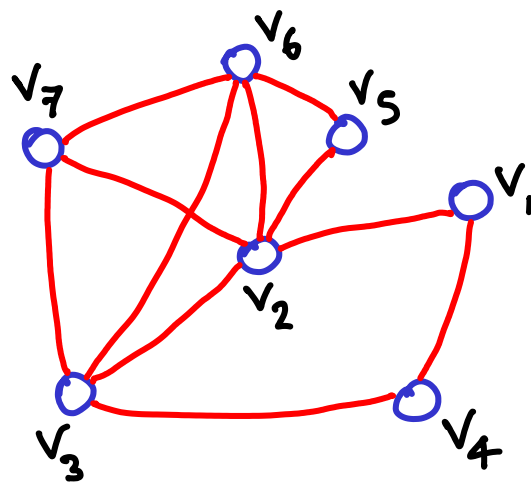
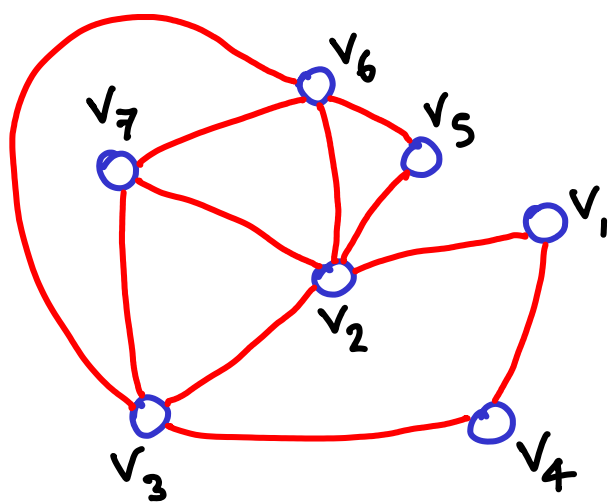


PLANAR GRAPH
can redraw
without crossings

Non-planar graphs
(can't redraw)

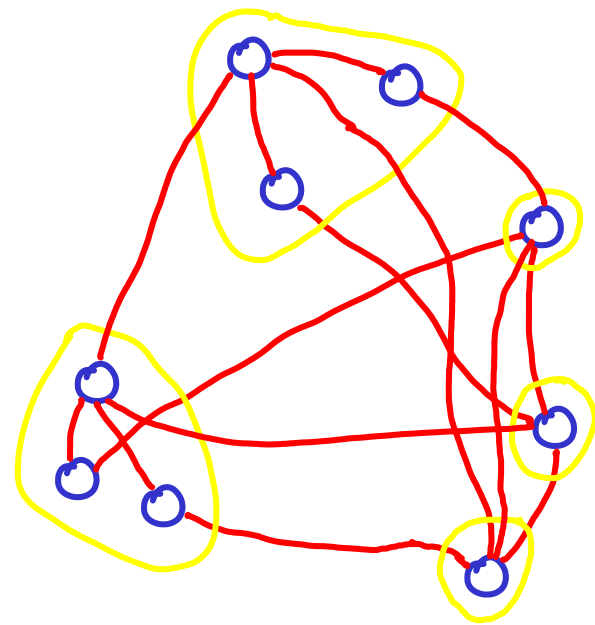
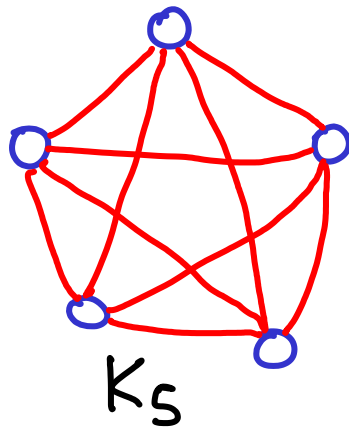
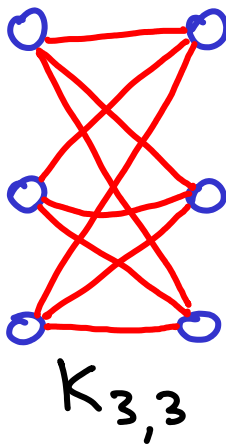


PLANE GRAPH
no crossings

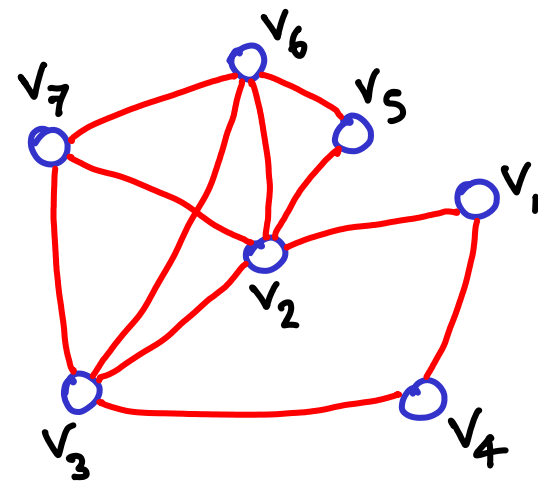
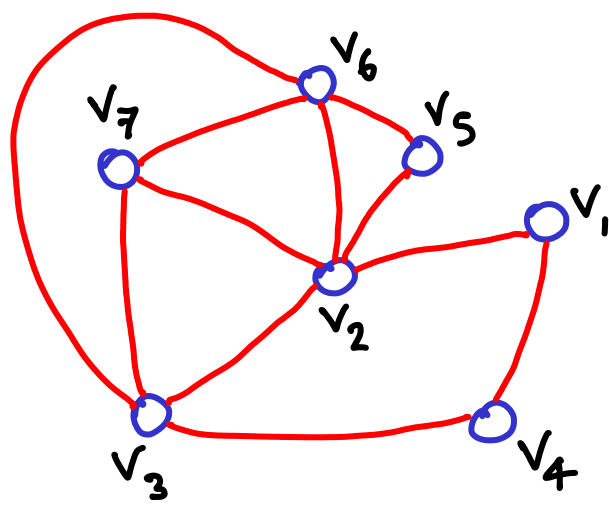


PLANAR GRAPH
can redraw
without crossings

Non-planar graphs
(can't redraw)

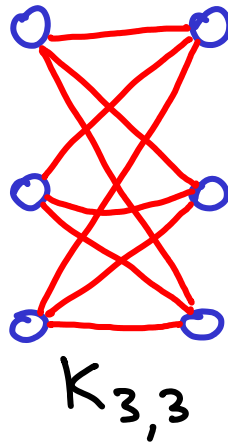


PLANE GRAPH
no crossings

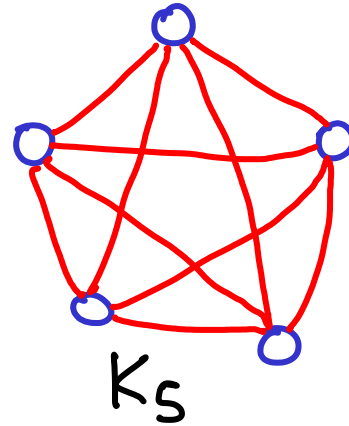


PLANAR GRAPH
can redraw
without crossings

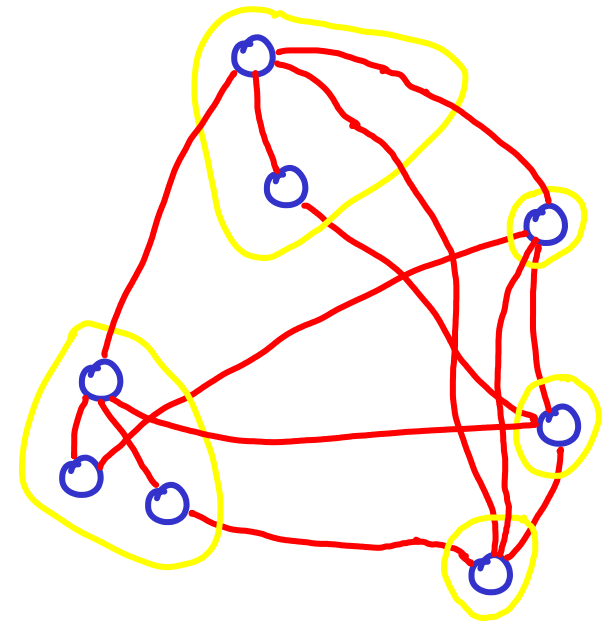
Non-planar graphs
(can't redraw)



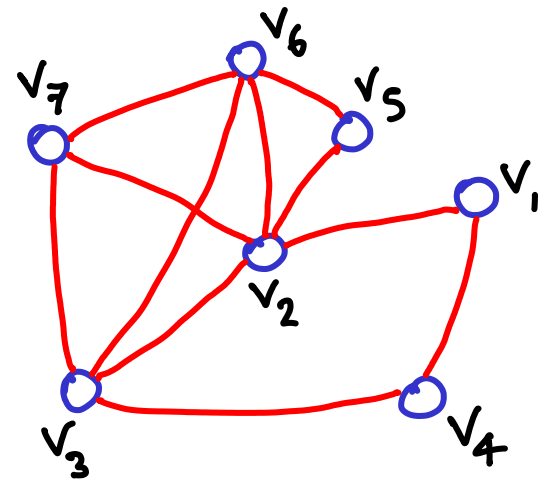
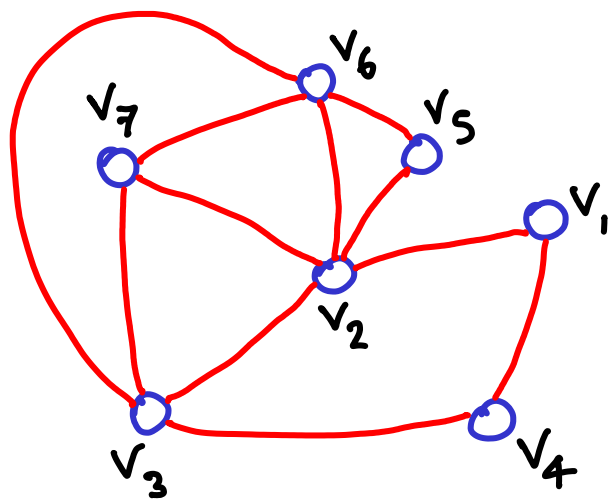
$K_{3,3}$



K_5

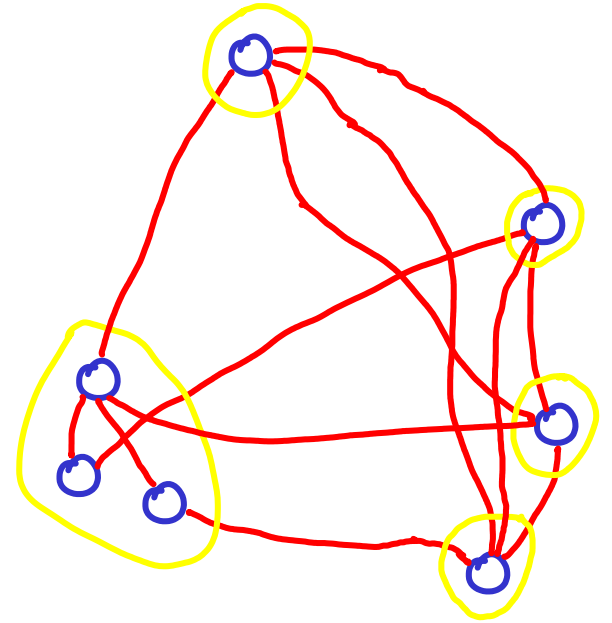
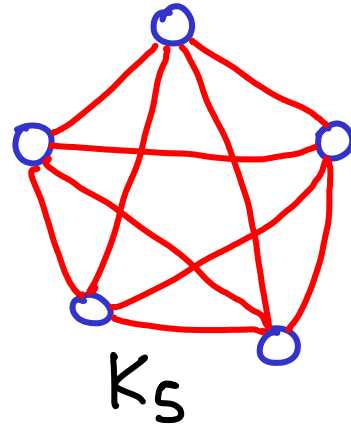
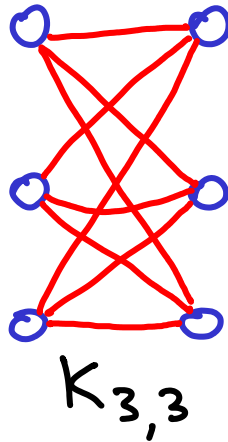


PLANE GRAPH
no crossings

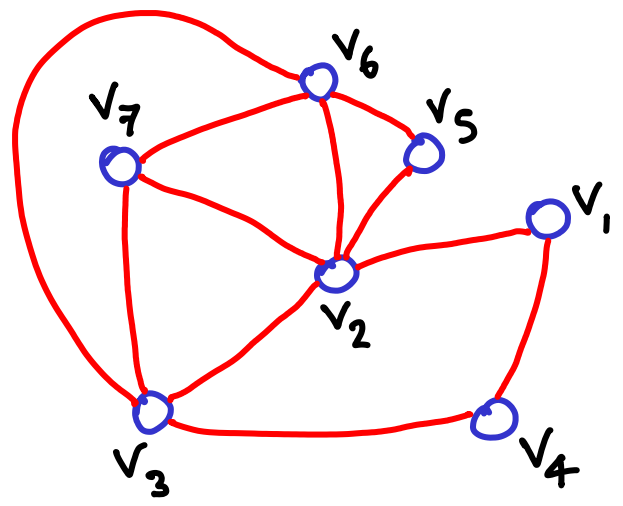


PLANAR GRAPH
can redraw
without crossings

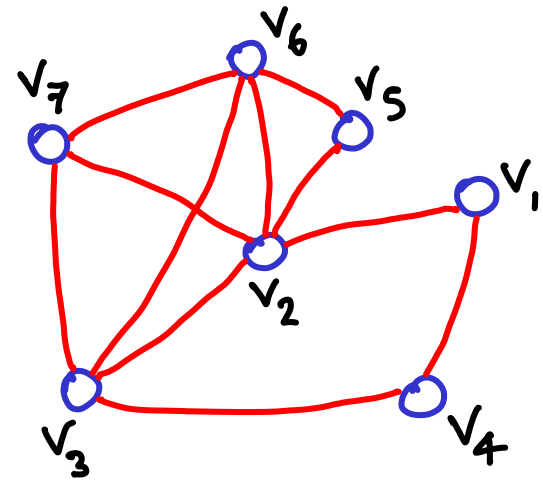
Non-planar graphs
(can't redraw)



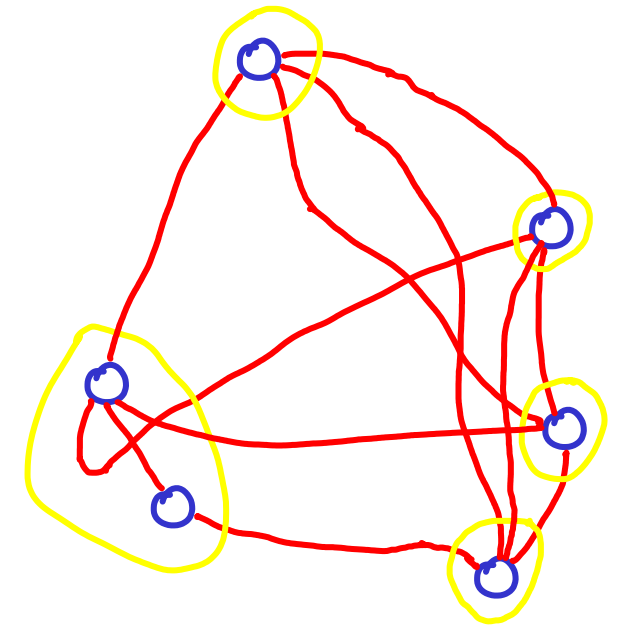
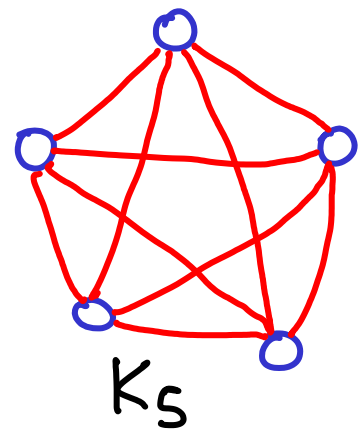
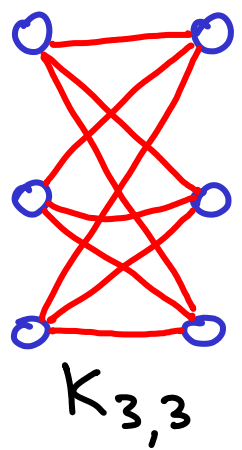
PLANE GRAPH
no crossings



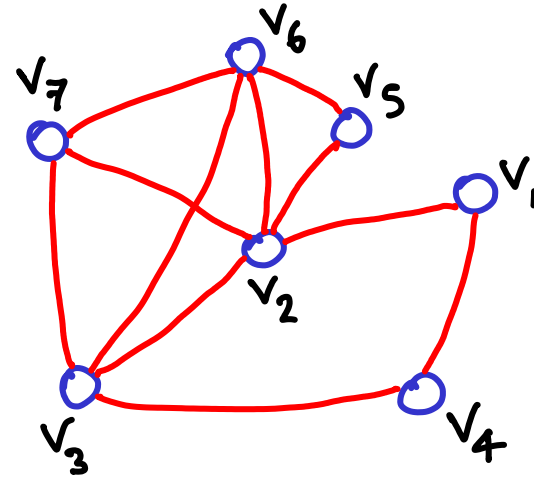
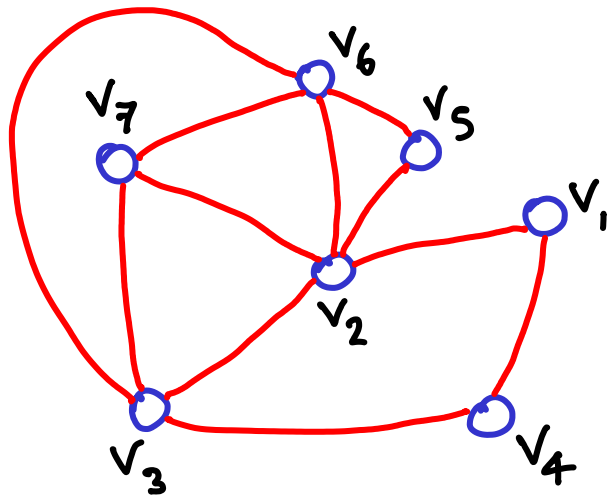
PLANAR GRAPH
can redraw
without crossings



Non-planar graphs
(can't redraw)

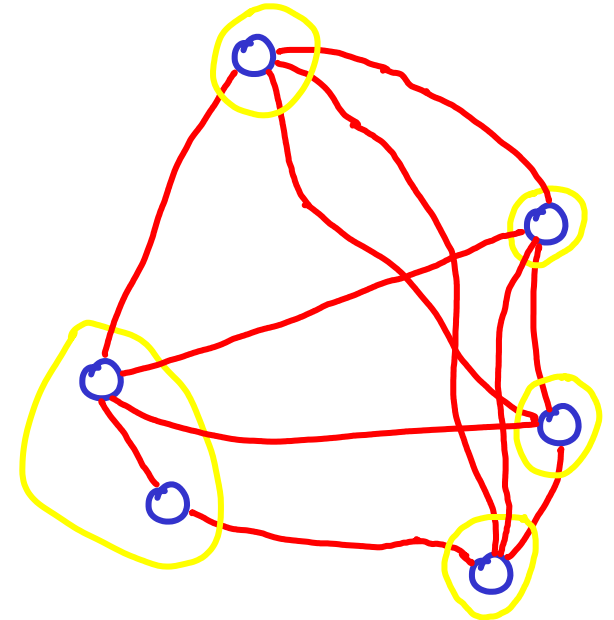
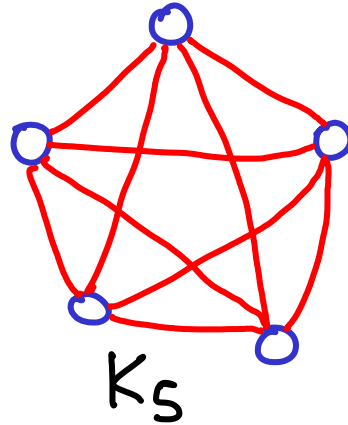
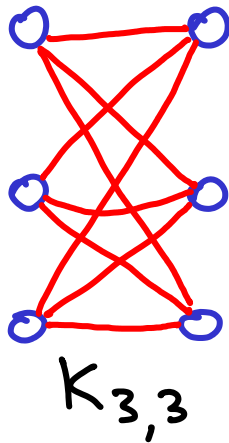


PLANE GRAPH
no crossings

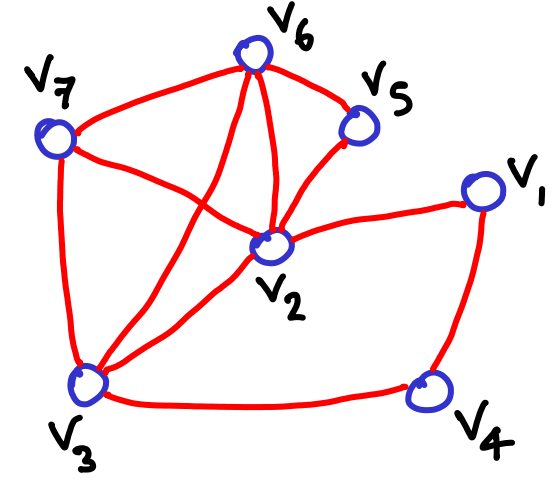
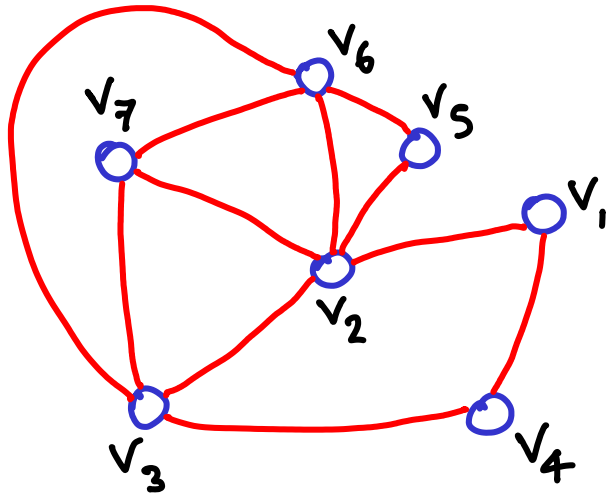


PLANAR GRAPH
can redraw
without crossings

Non-planar graphs
(can't redraw)

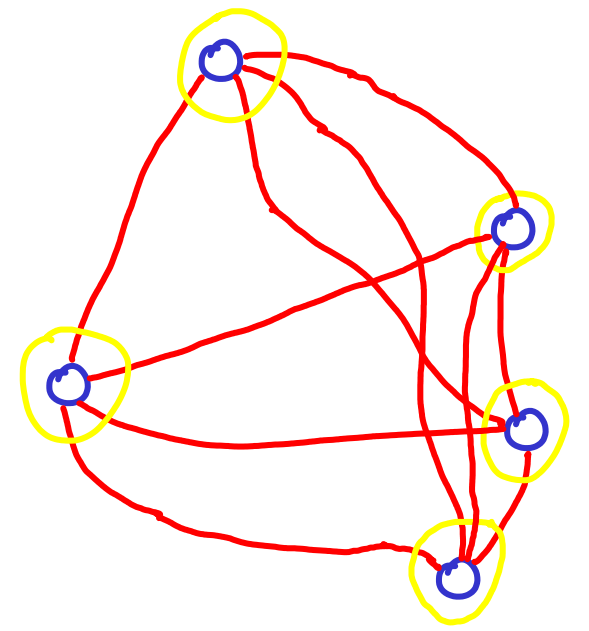
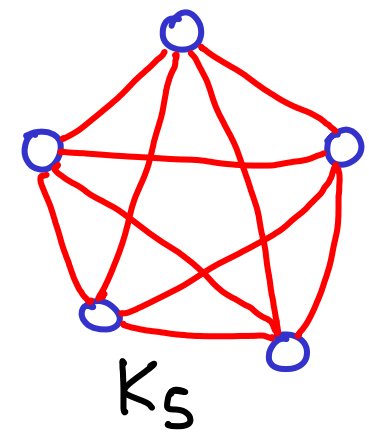
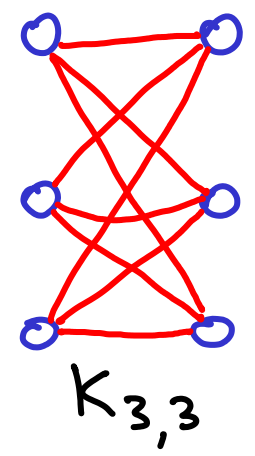


PLANE GRAPH
no crossings

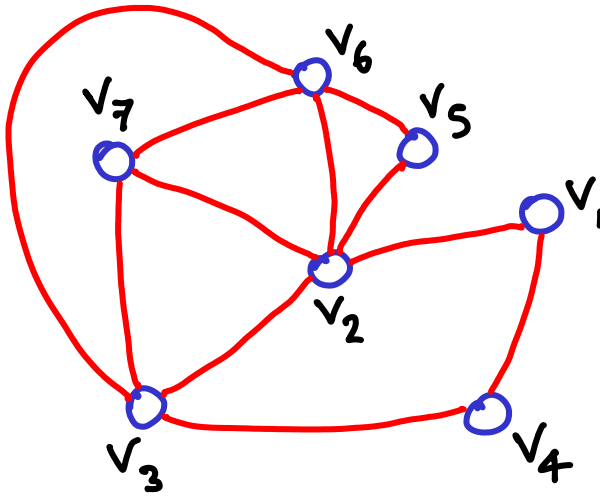


PLANAR GRAPH
can redraw
without crossings

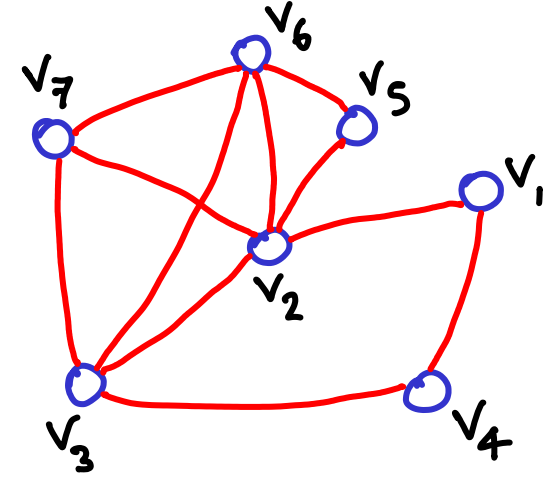
Non-planar graphs
(can't redraw)



PLANE GRAPH
no crossings

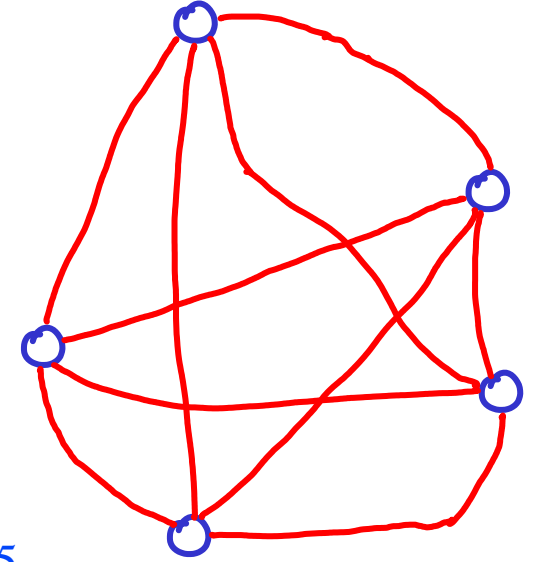
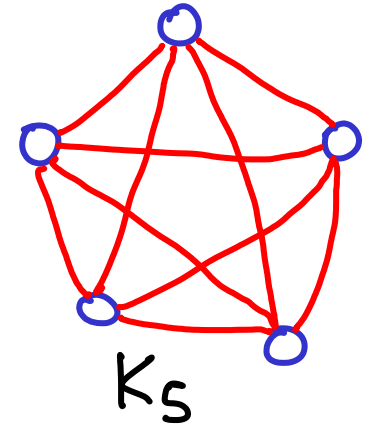
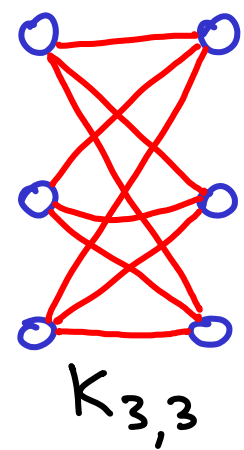


PLANAR GRAPH
can redraw
without crossings



obtained by successive contractions

Non-planar graphs
(can't redraw)



A graph is non-planar if and only if it "contains" a $K_{3,3}$ or K_5