

REDUCING ONE (DECISION) PROBLEM TO ANOTHER

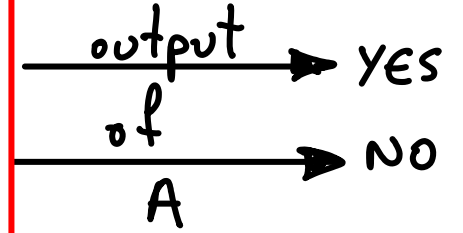
A

B

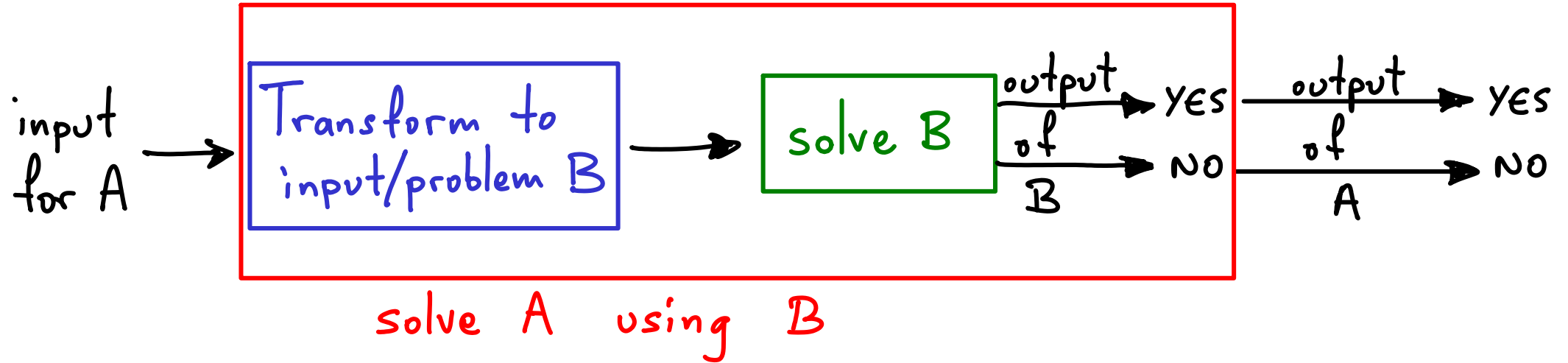
input
for A



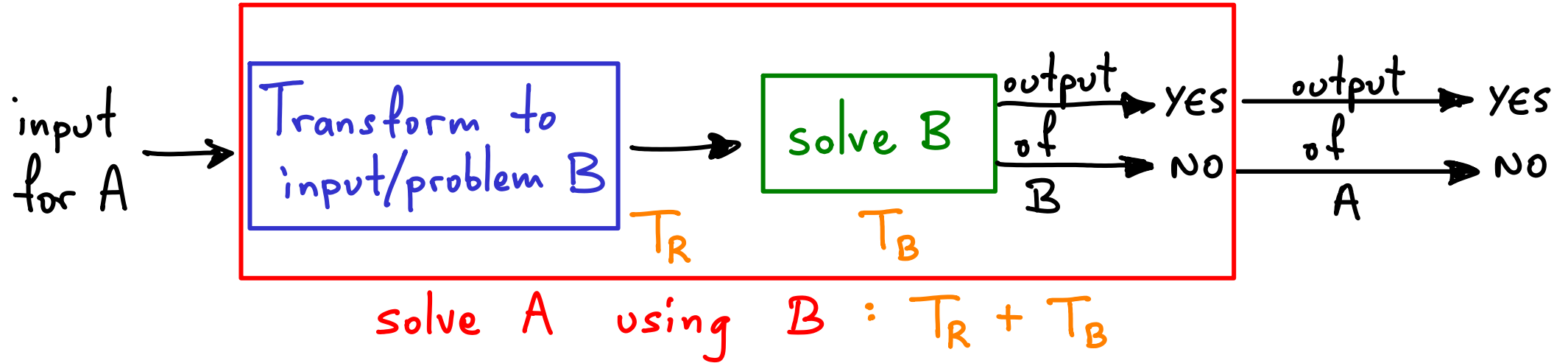
solve A



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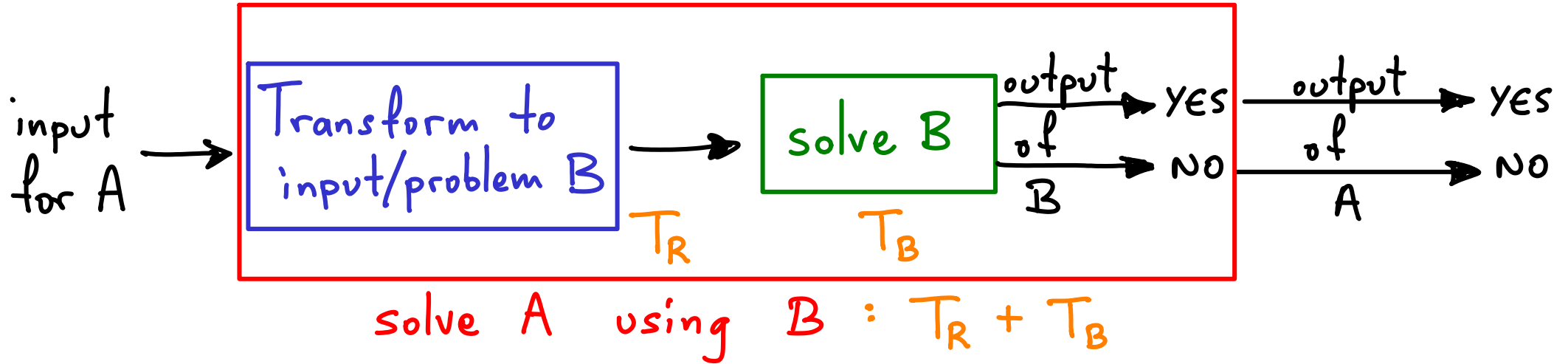
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A

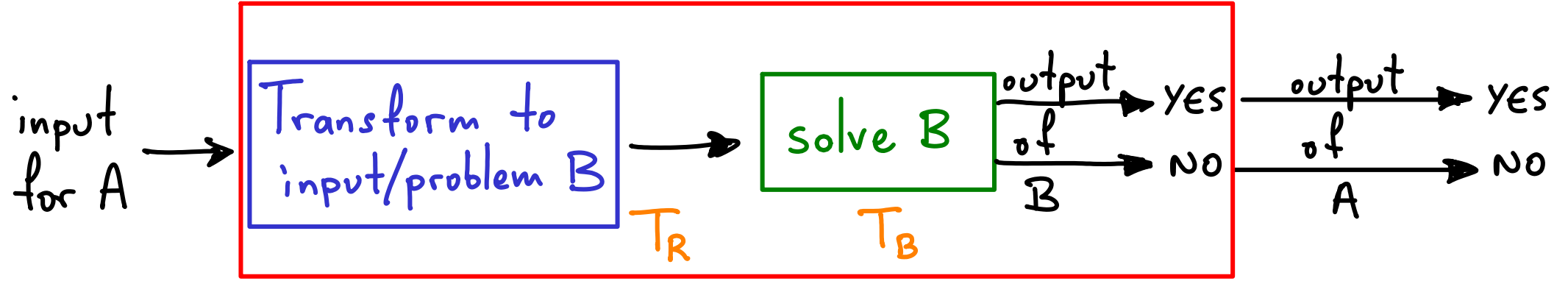
B



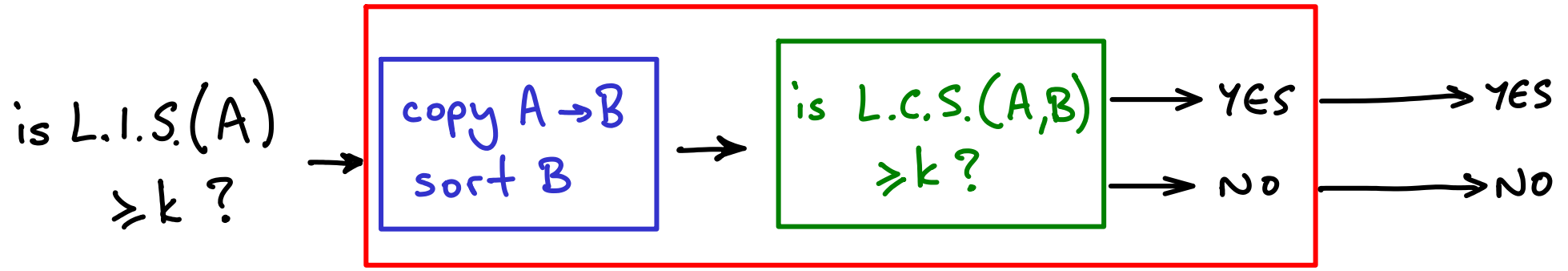
REDUCING ONE (DECISION) PROBLEM TO ANOTHER

A

B



solve A using B : $T_R + T_B$

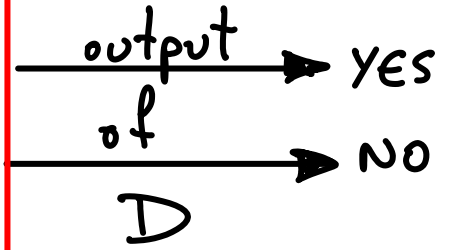


LOWER BOUND FOR ONE (DECISION) PROBLEM VIA ANOTHER

C

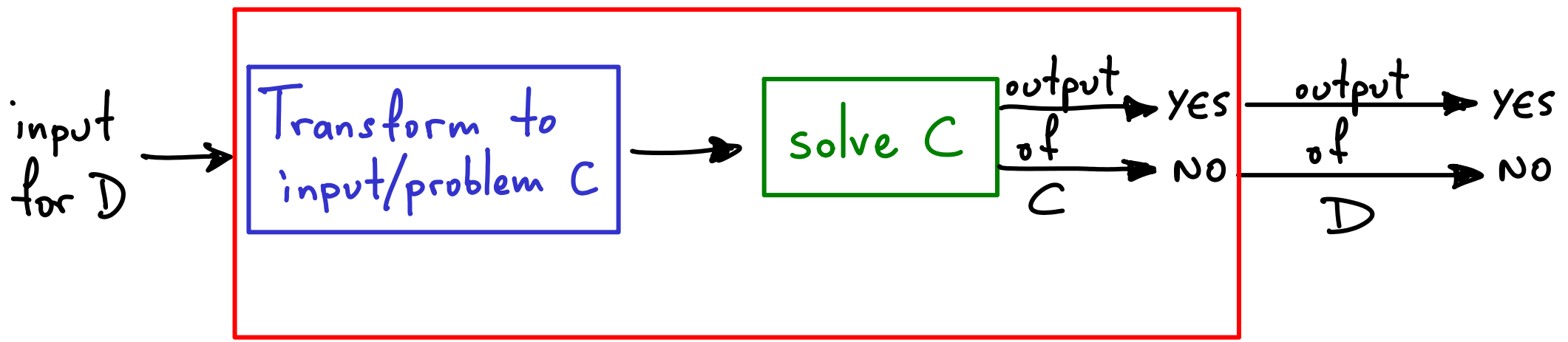
D

input
for D



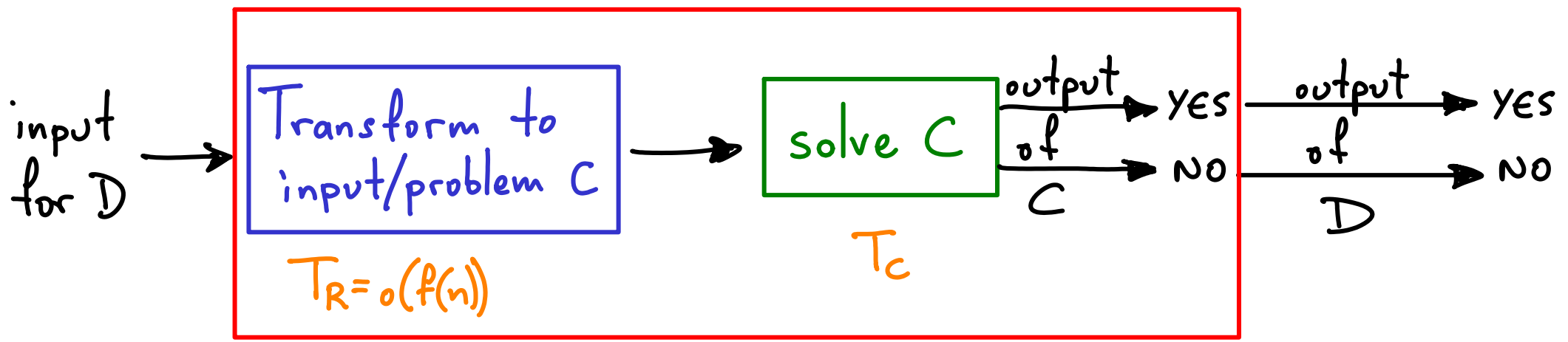
solve D: known $\Omega(f(n))$

LOWER BOUND FOR ONE (DECISION) PROBLEM VIA ANOTHER



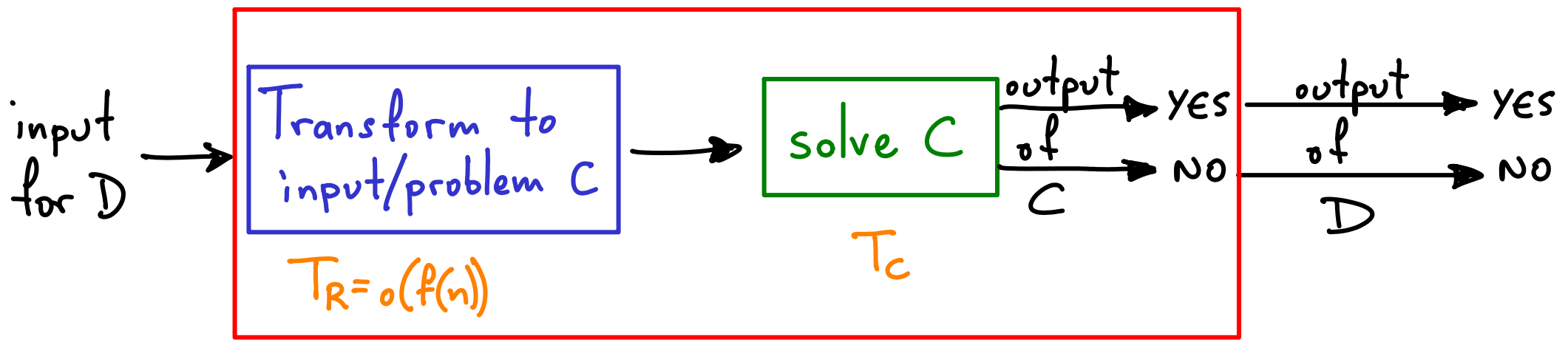
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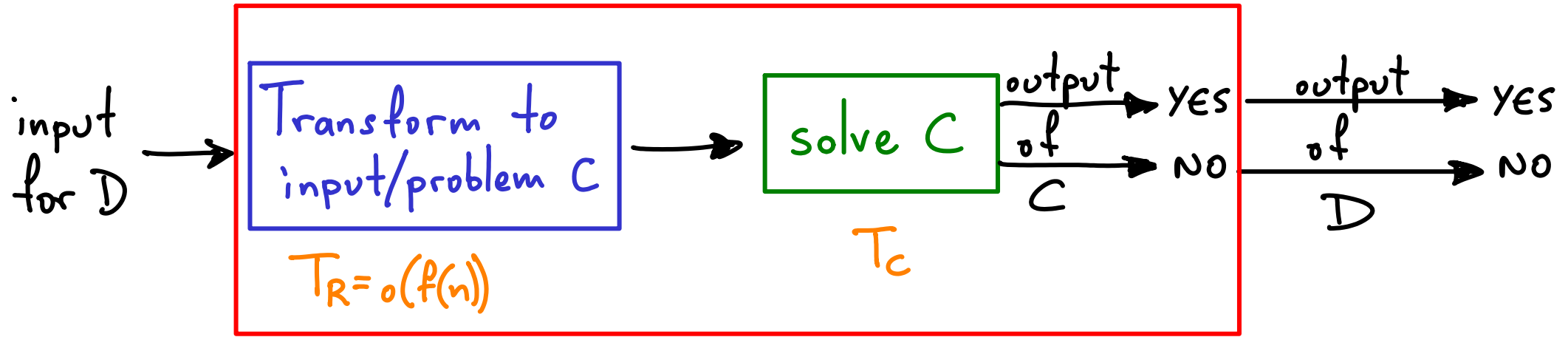
solve D: known $\Omega(f(n)) = T_R + T_C$

LOWER BOUND FOR ONE (DECISION) PROBLEM VIA ANOTHER



solve D: known $\Omega(f(n)) = T_R + T_C \Rightarrow T_C = \Omega(f(n))$

LOWER BOUND FOR ONE (DECISION) PROBLEM VIA ANOTHER



solve D: known $\Omega(f(n)) = T_R + T_C \Rightarrow T_C = \Omega(f(n))$

- quick transformation $T_R \Rightarrow C$ is at least as difficult as D

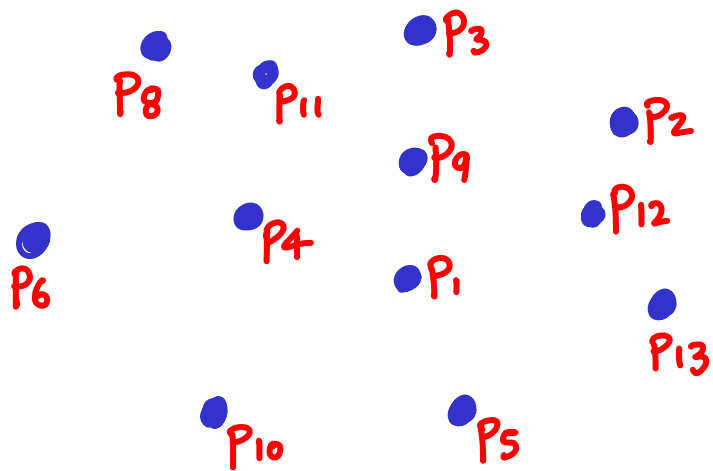
(fast solution for C \Rightarrow fast solution for D)

The CONVEX HULL problem (definition by picture)

C.H. input: list of (2D) points

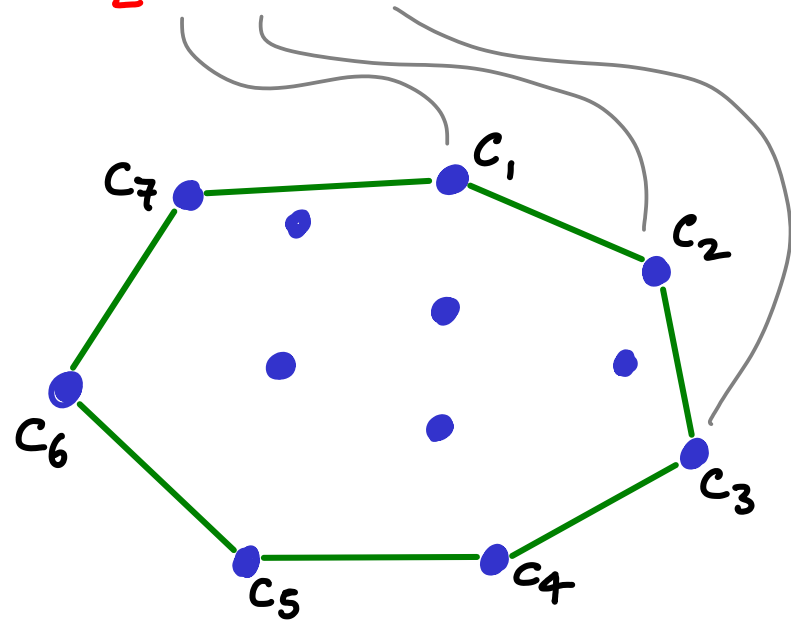
[P_{10} P_5 P_3 P_{12} P_1 ... etc...]

(x_{12}, y_{12})



C.H. output: a graph (cycle) containing only the "extreme" points

[P_3 P_2 P_{13} P_5 P_{10} P_6 P_8]



LOWER BOUND FOR ONE ~~(DECISION)~~ PROBLEM VIA ANOTHER

Example

input
for sorting →



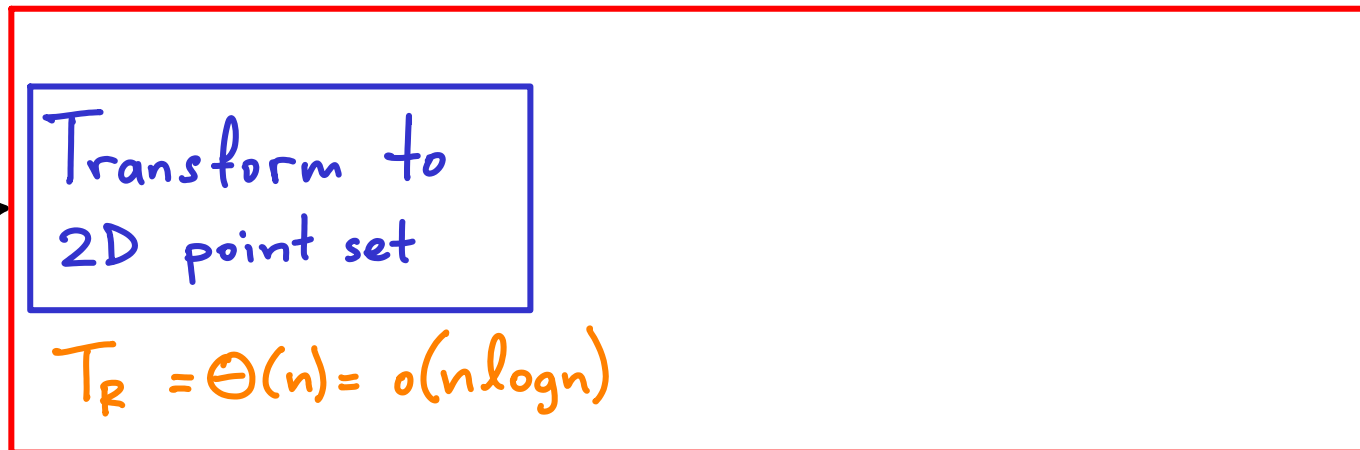
Sorted
output

solve sorting: known $\Omega(n \log n)$

LOWER BOUND FOR ONE ~~(DECISION)~~ PROBLEM VIA ANOTHER

Example

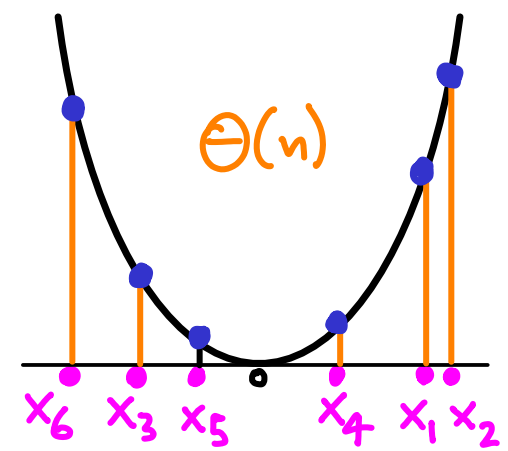
input
for sorting



Sorted
output

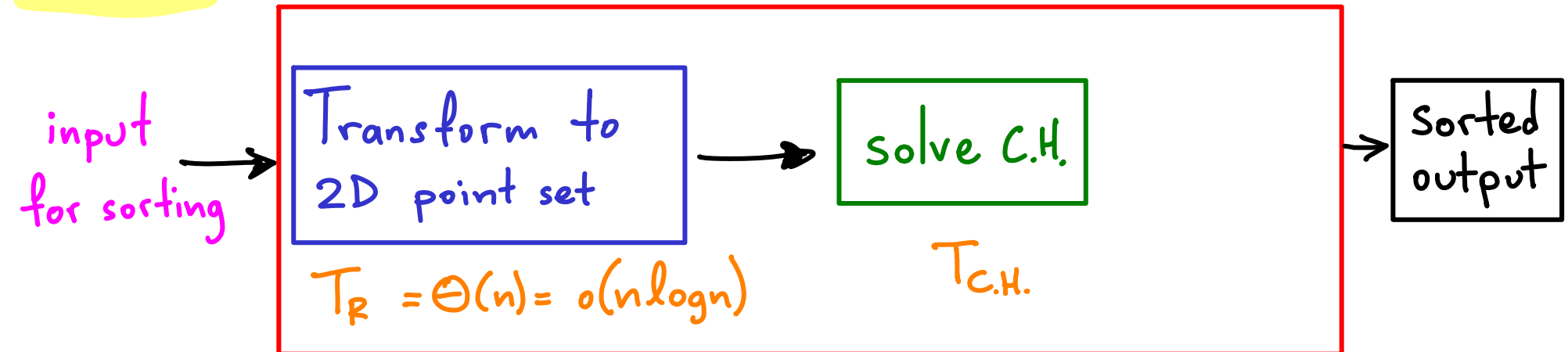
solve sorting: known $\Omega(n \log n)$

(x_i, x_i^2)
 $\Theta(i) \uparrow$
 x_i

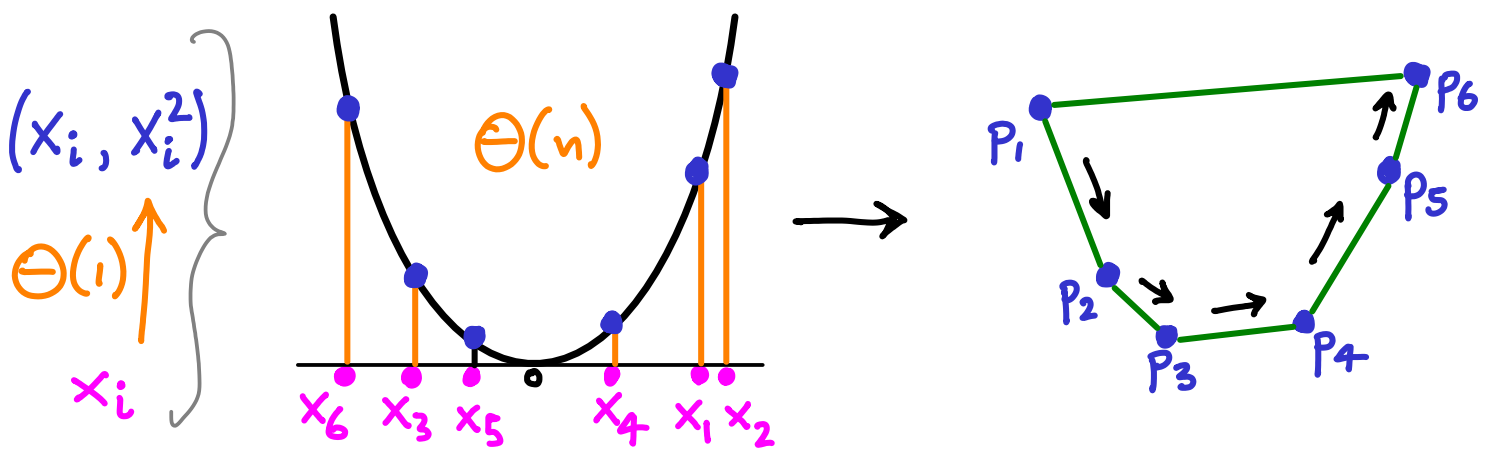


LOWER BOUND FOR ONE ~~(DECISION)~~ PROBLEM VIA ANOTHER

Example

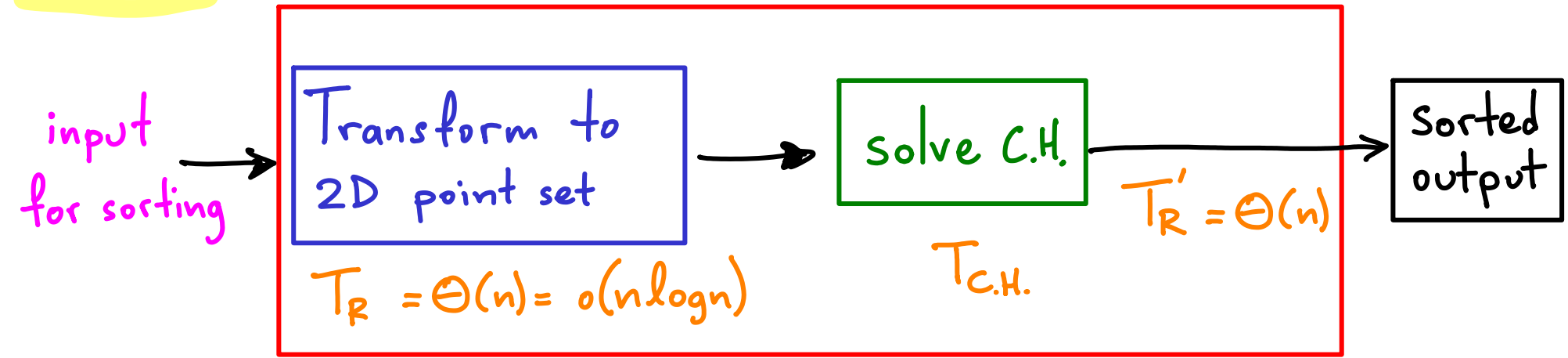


solve sorting: known $\Omega(n \log n)$

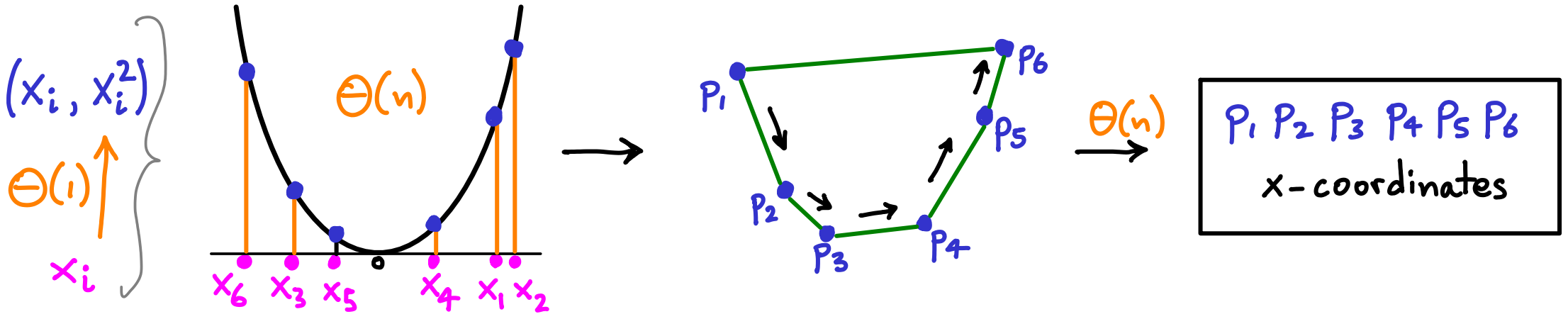


LOWER BOUND FOR ONE ~~(DECISION)~~ PROBLEM VIA ANOTHER

Example

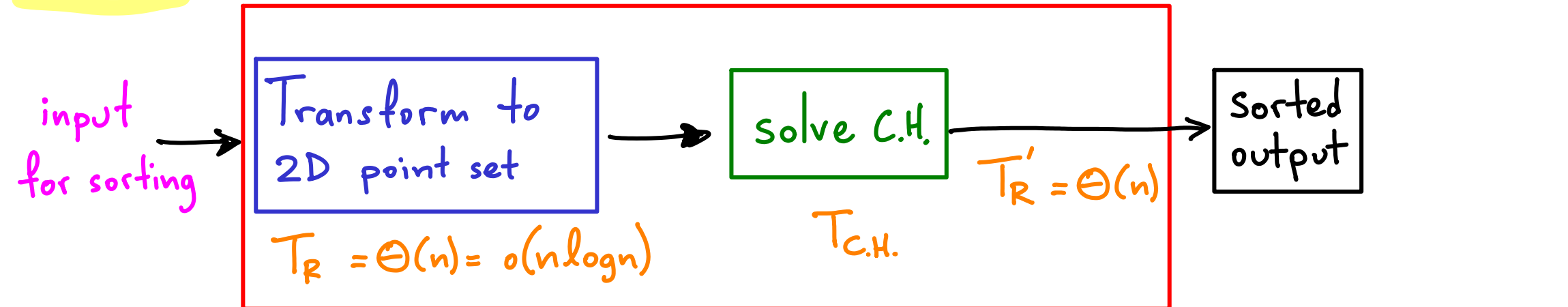


solve sorting: known $\Omega(n \log n)$

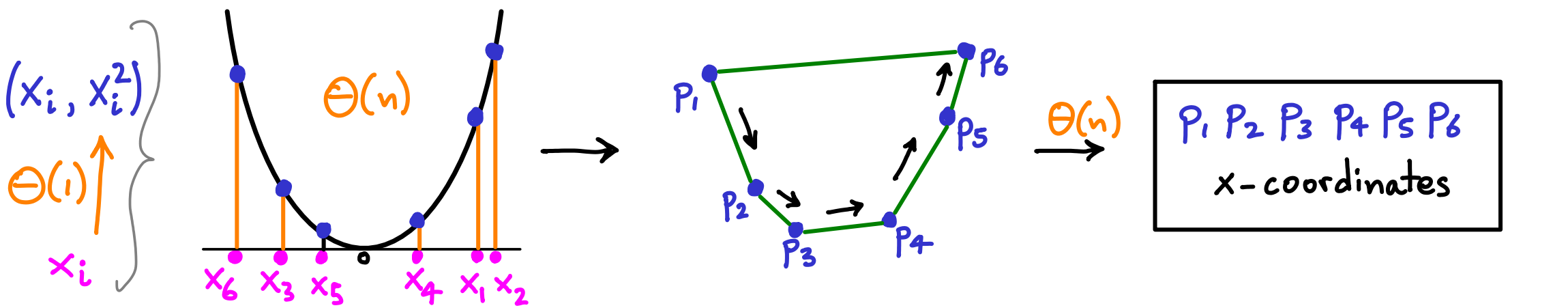


LOWER BOUND FOR ONE ~~(DECISION)~~ PROBLEM VIA ANOTHER

Example



solve sorting: known $\Omega(n \log n) = T_R + T'_R + T_{C.H.} \Rightarrow T_{C.H.} = \Omega(n \log n)$



NPC
REDUCTION

FROM ONE (DECISION) PROBLEM TO ANOTHER
D C

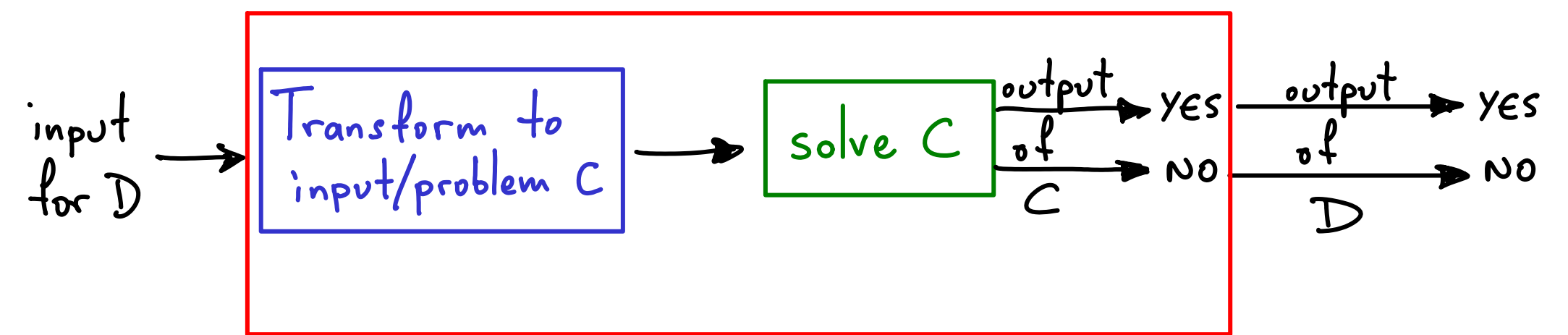
NPC REDUCTION

FROM ONE (DECISION) PROBLEM TO ANOTHER
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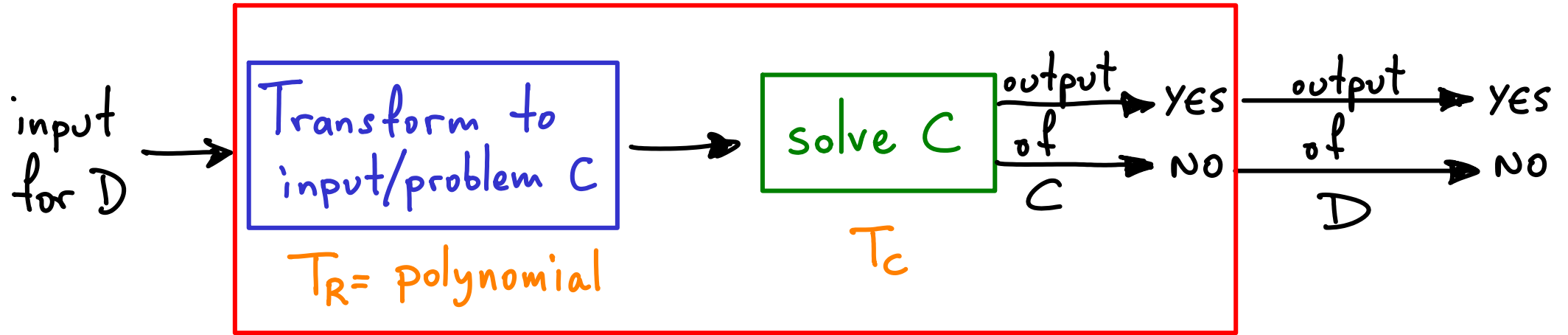
D: known NPC

NPC REDUCTION FROM ONE (DECISION) PROBLEM TO ANOTHER



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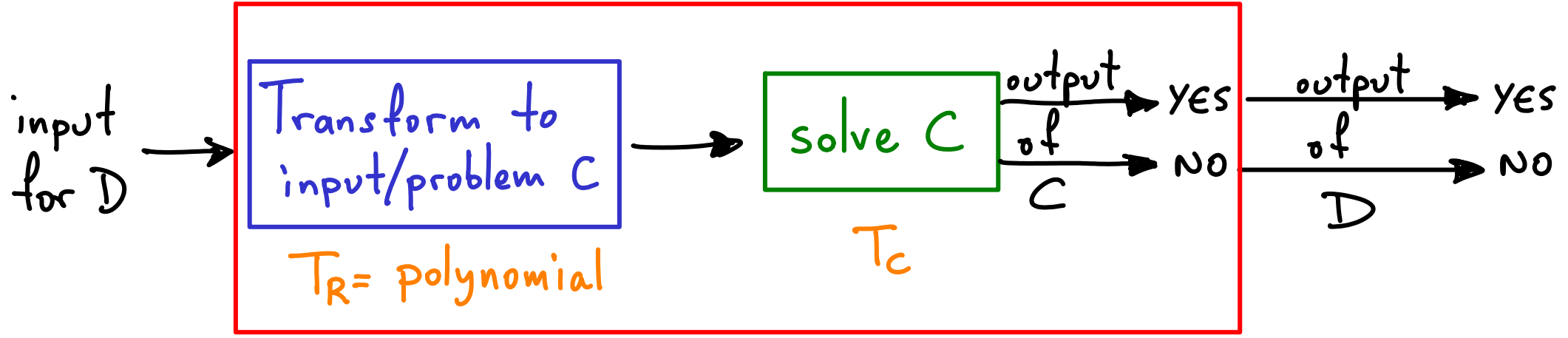


D: known NPC

NPC REDUCTION

FROM ONE (DECISION) PROBLEM TO ANOTHER

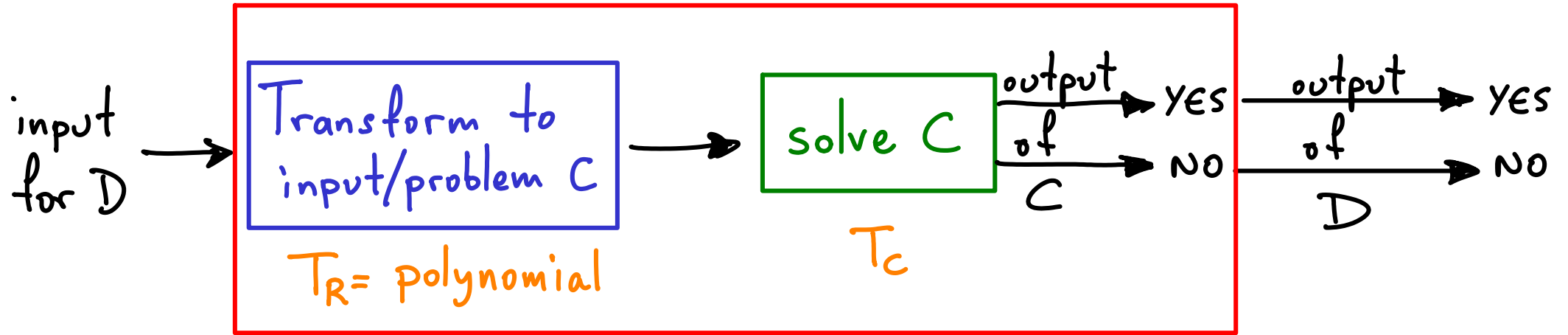
D C



solve D: known NPC = $T_R + T_C = \text{poly-time} + T_C$

NPC REDUCTION

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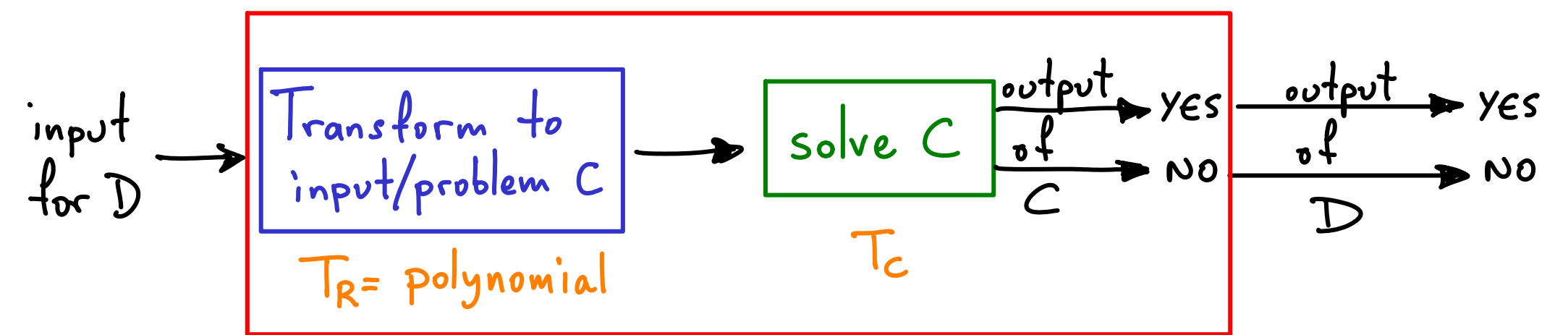


solve D: known NPC = $T_R + T_C = \text{poly-time} + T_C$

\Rightarrow C is NP-hard

(if T_C is polynomial $\Rightarrow P = NP$)

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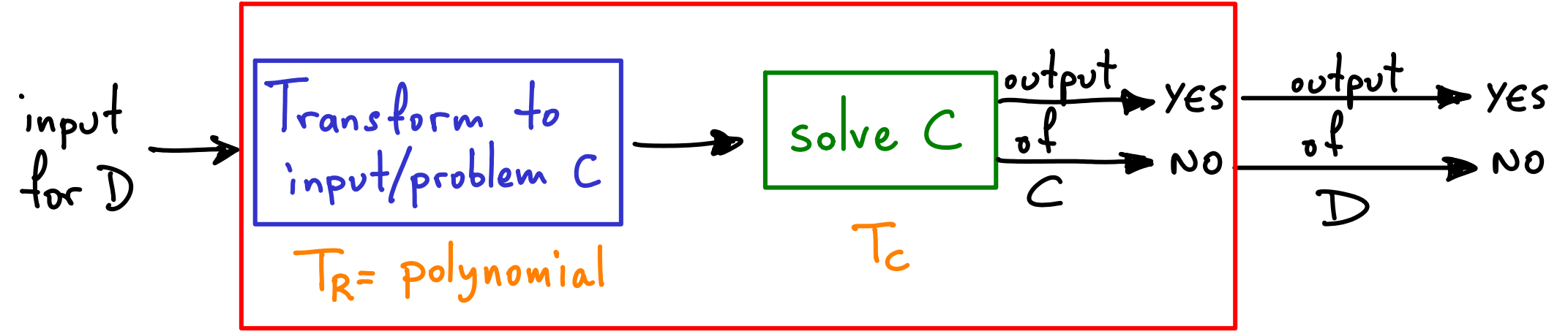
\Rightarrow C is NP-hard

(if T_C is polynomial $\Rightarrow P = NP$)

& if C is in NP then C is NPC

NPC REDUCTION FROM ONE (DECISION) PROBLEM TO ANOTHER

~ LIKE ESTABLISHING AN ALMOST CERTAIN LOWER BOUND FOR C.



solve D: known NPC = $T_R + T_C = \text{poly-time} + T_C$

\Rightarrow C is NP-hard

(if T_C is polynomial $\Rightarrow P = NP$)

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$A \leq_p B$: in polynomial time, A can be reduced to B

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↳ B is at least as hard as A.

Solving B in poly-time \Rightarrow solving A in poly-time

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Solving B in poly-time \Rightarrow solving A in poly-time

If $\{\text{every problem in NP}\} \leq_p B$ then B is NP-hard
and if B is in NP, ...?

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Solving B in poly-time \Rightarrow solving A in poly-time

If $\{ \text{every problem in NP} \} \leq_p B$
↳ or $\{ \dots ? \}$

then B is NP-hard
(and if B is in NP, then B is NPC)

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Solving B in poly-time \Rightarrow solving A in poly-time

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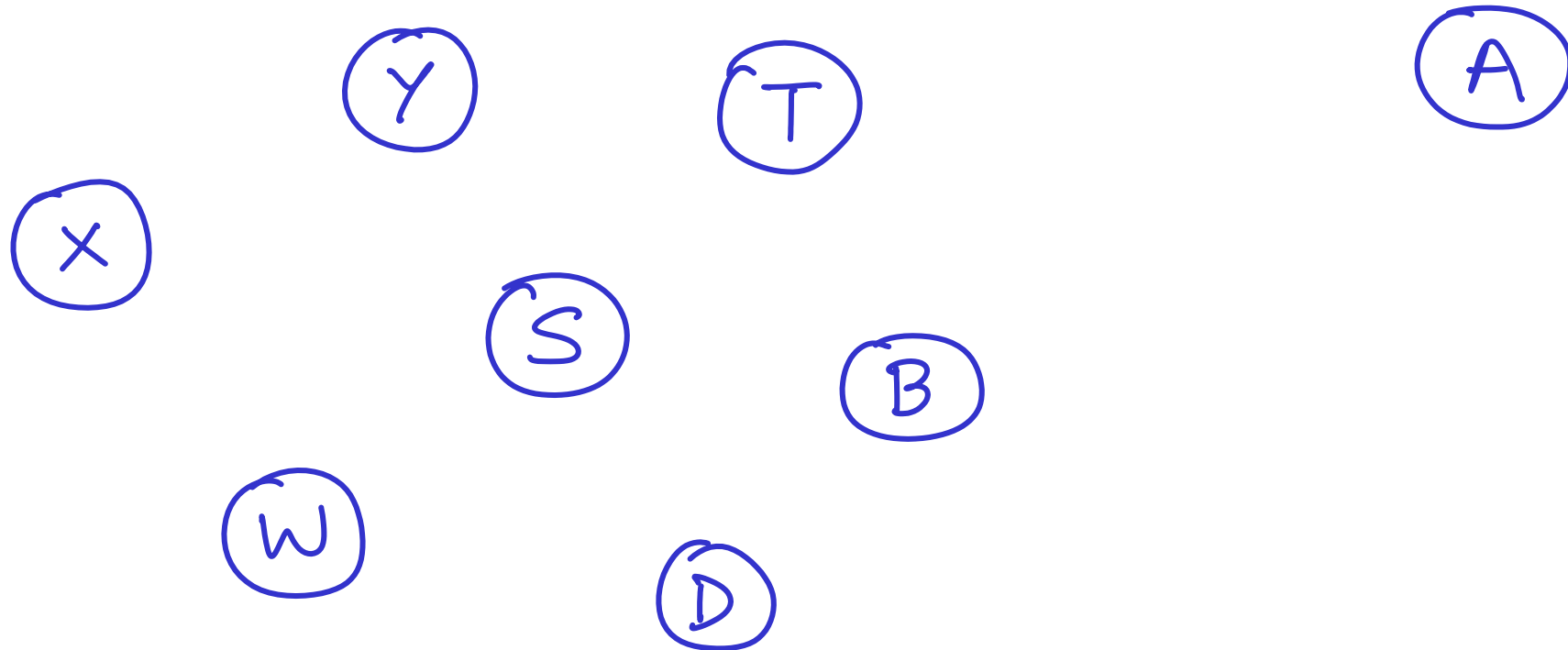
Solving B in poly-time \Rightarrow solving A in poly-time

If $\{\text{every problem in NP}\} \leq_p B$
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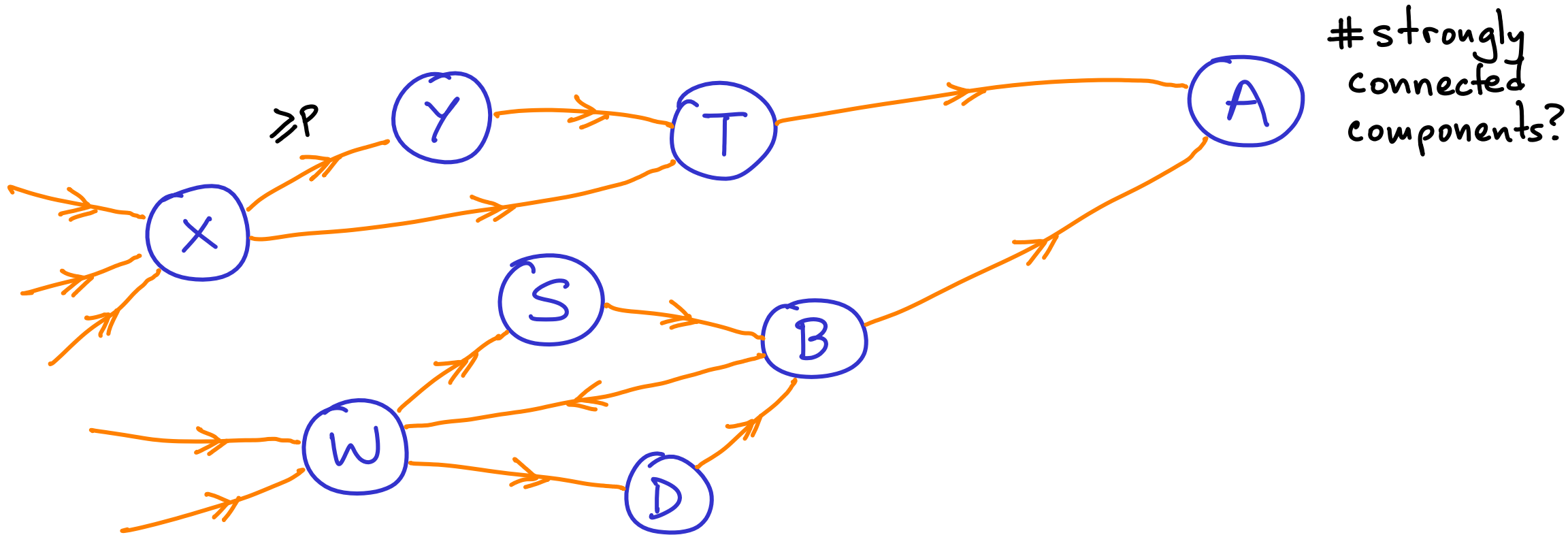
if A & B are NPC then $A \leq_p B$ & $B \leq_p A$
 $\sim A \stackrel{p}{=} B$

THOUSANDS OF NPC PROBLEMS



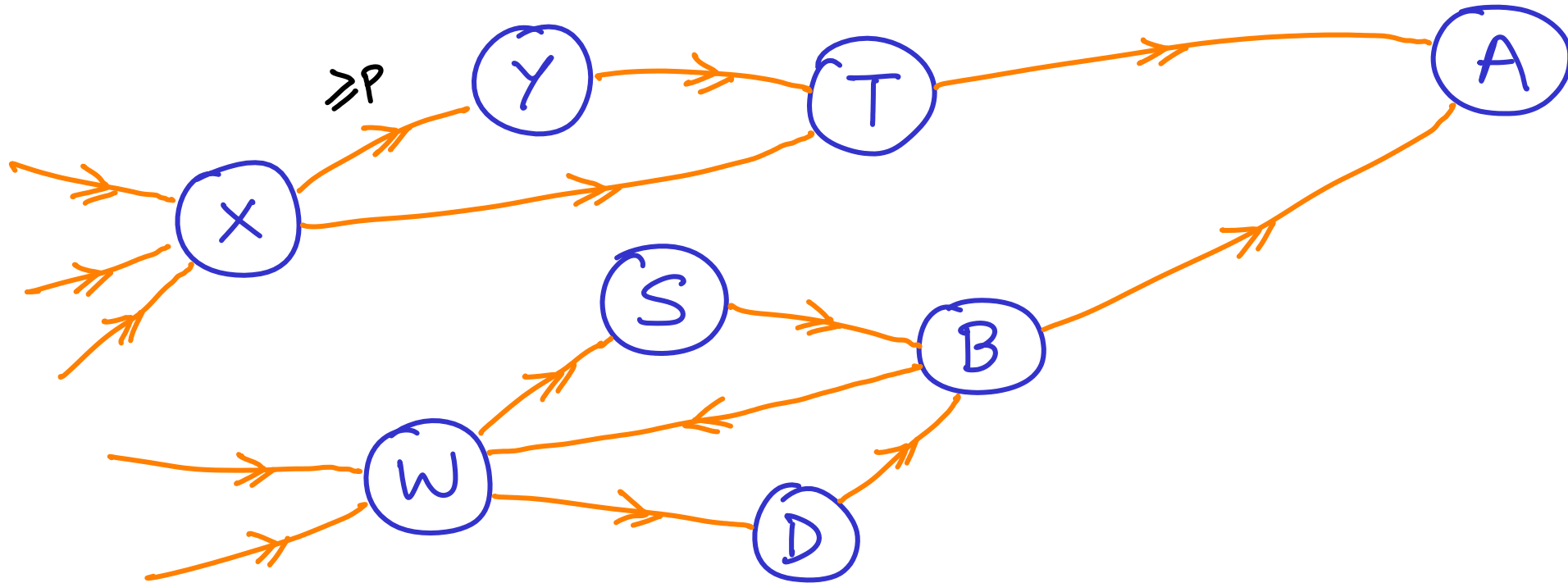
THOUSANDS OF NPC PROBLEMS

Reductions/transformation between them resemble a di-graph.



THOUSANDS OF NPC PROBLEMS

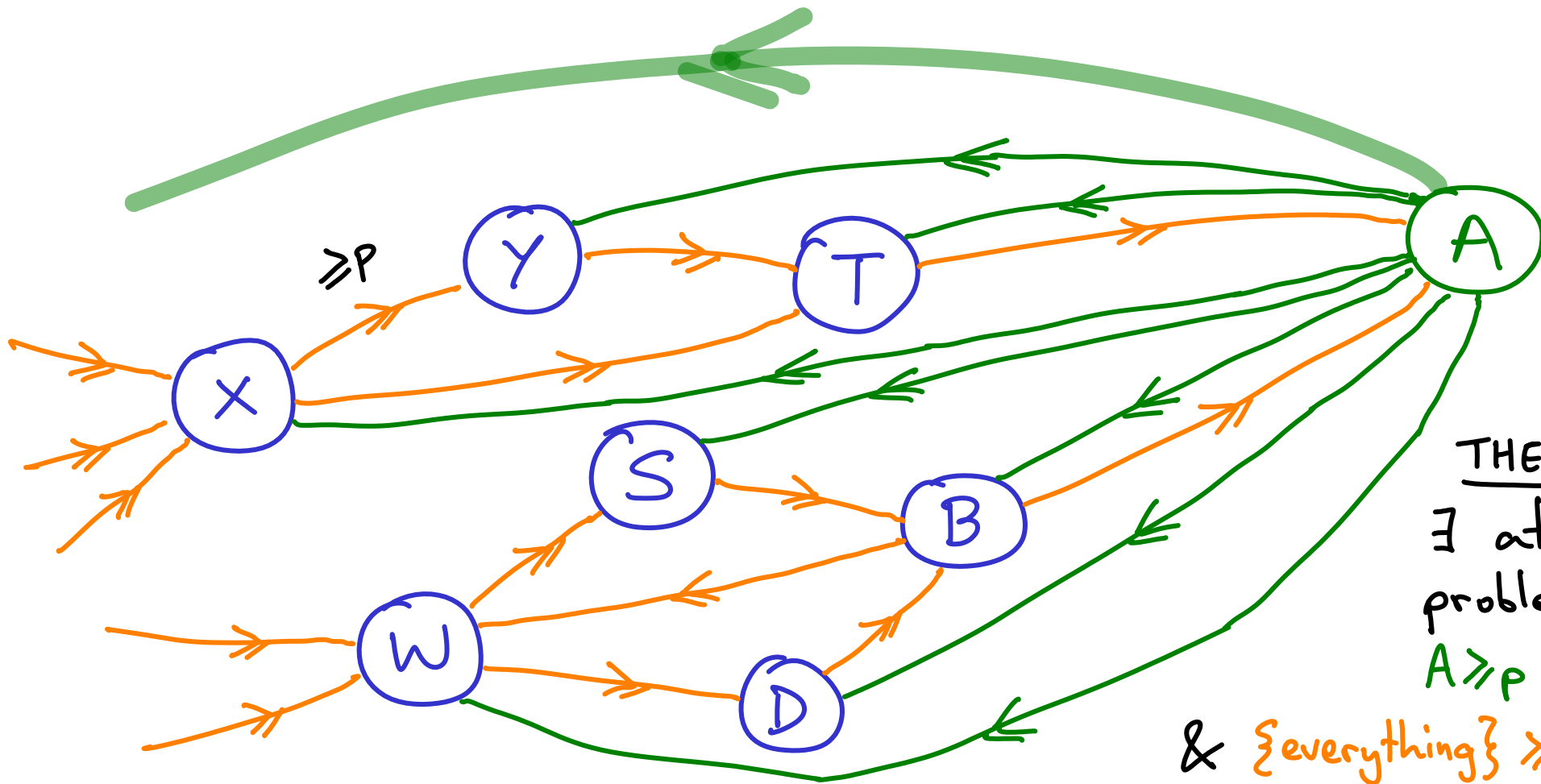
Reductions/transformation between them resemble a di-graph.



strongly connected components?
Must be 1. precisely.

THOUSANDS OF NPC PROBLEMS

Reductions/transformation between them resemble a di-graph.



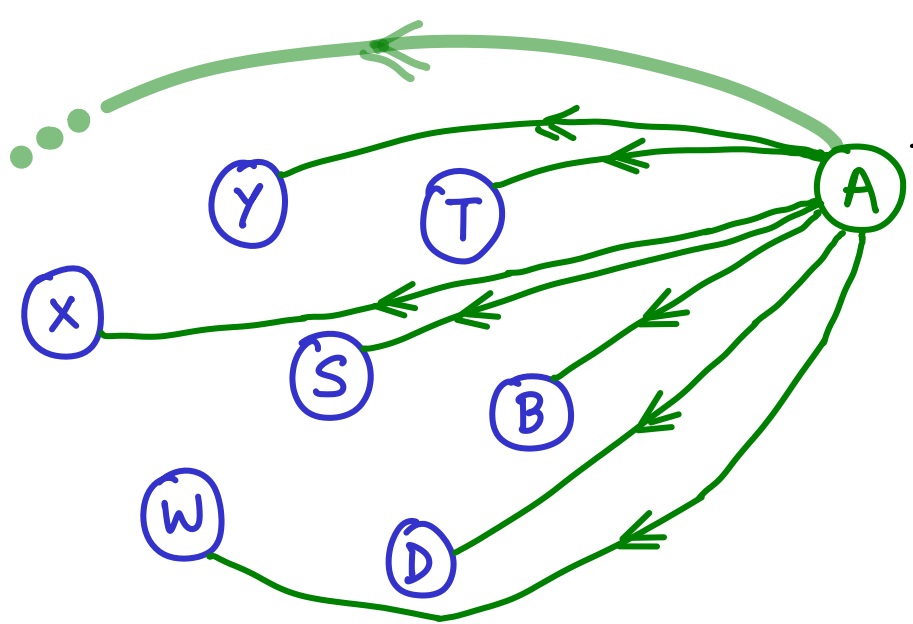
strongly connected components?
Must be 1. precisely.

THEOREM

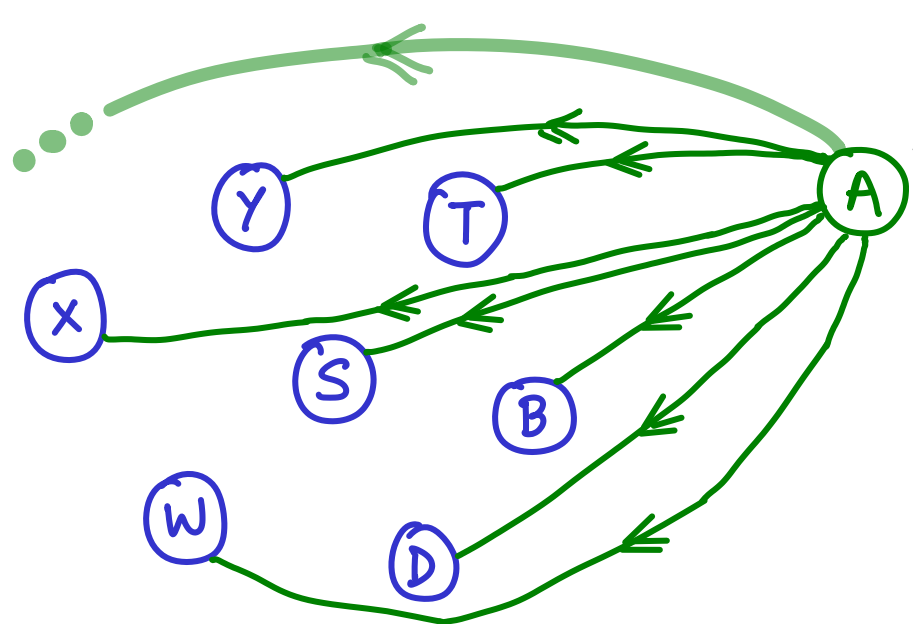
\exists at least one problem A s.t.

$A \geq_P \{ \text{everything} \}$

& $\{ \text{everything} \} \geq_P \dots \geq_P \dots \geq_P A$

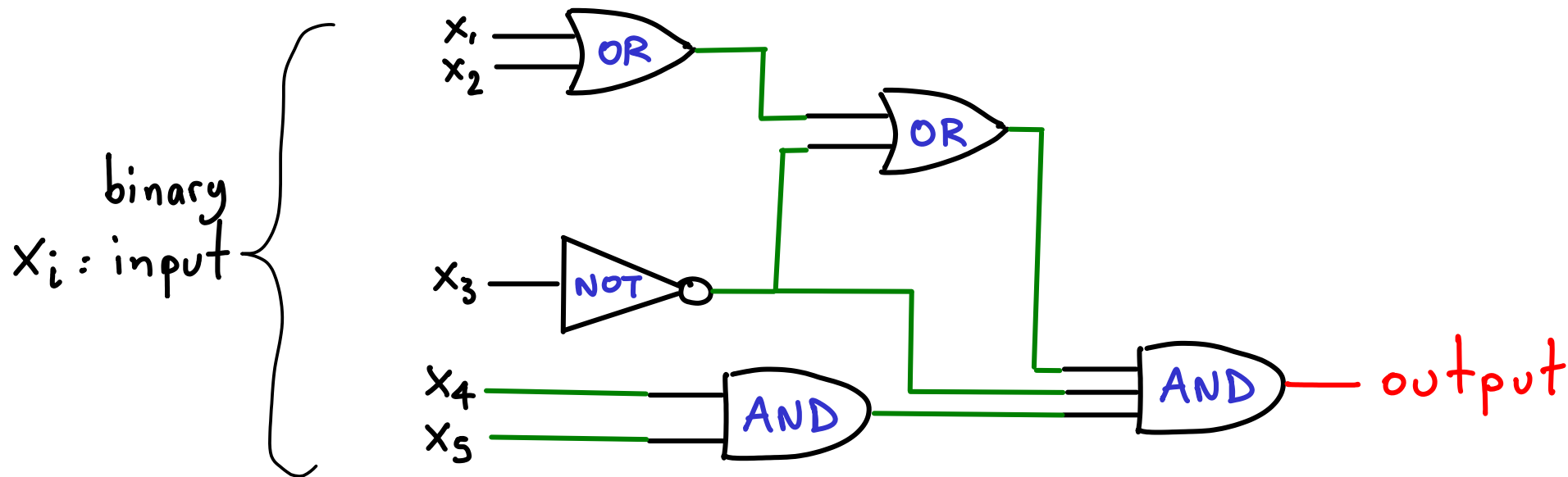


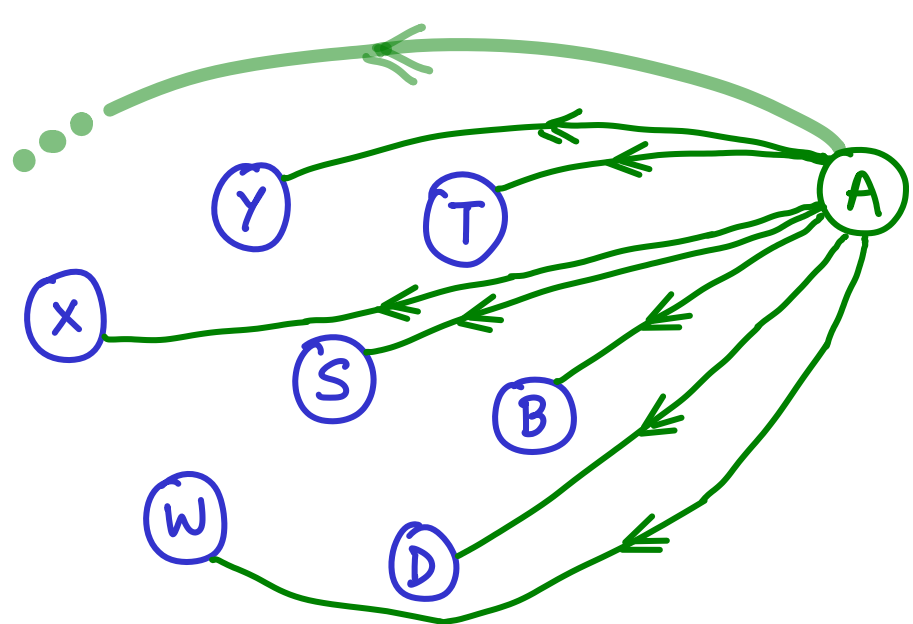
Circuit SAT (satisfiability)
The first NPC problem.



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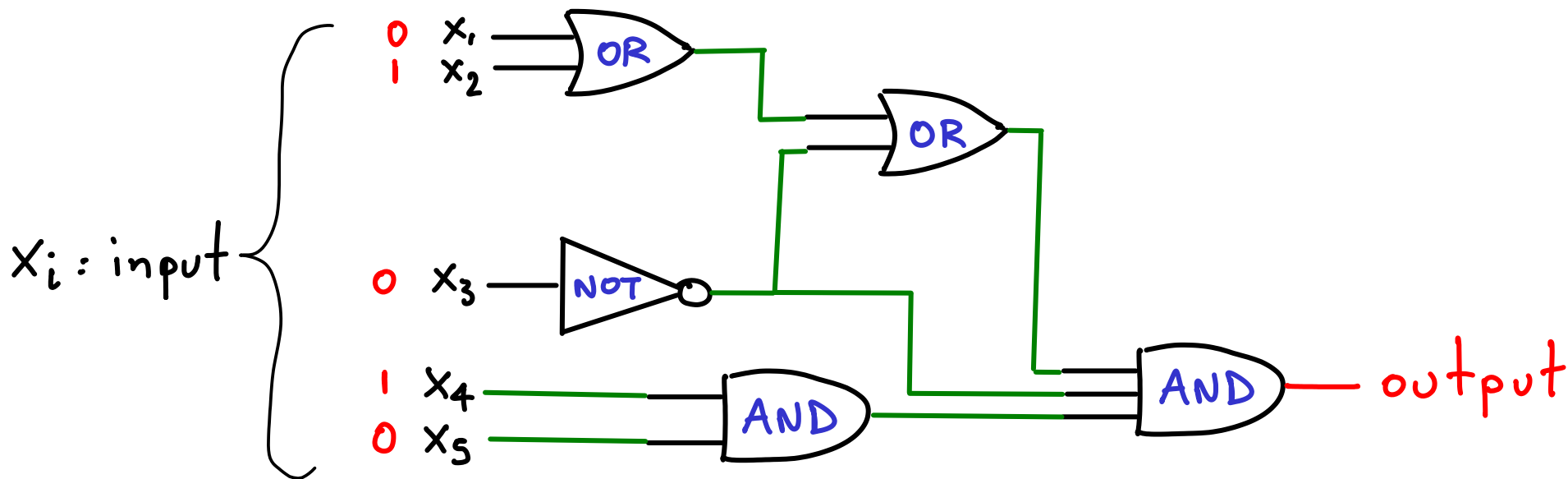
Given a circuit, can the output ever be 1?

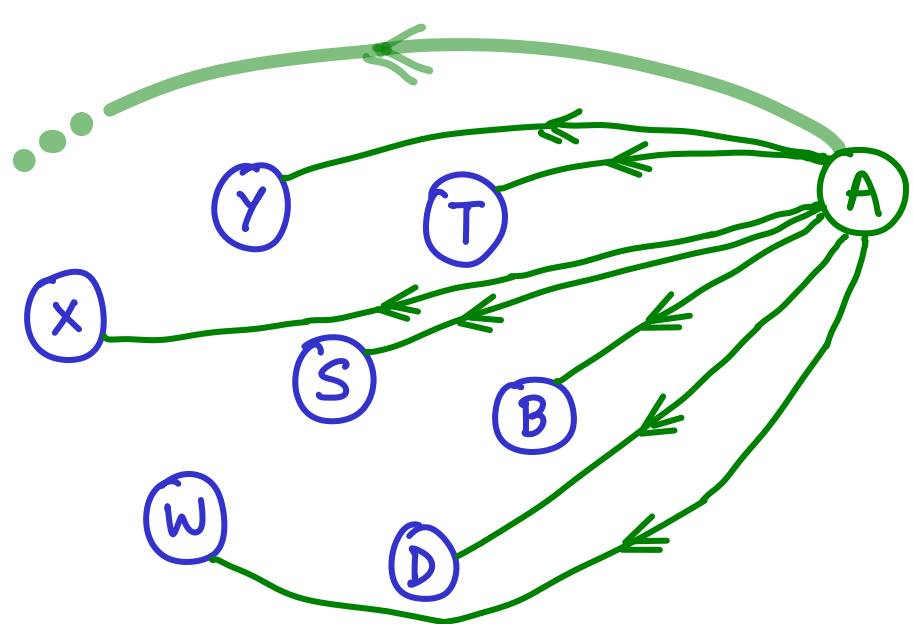




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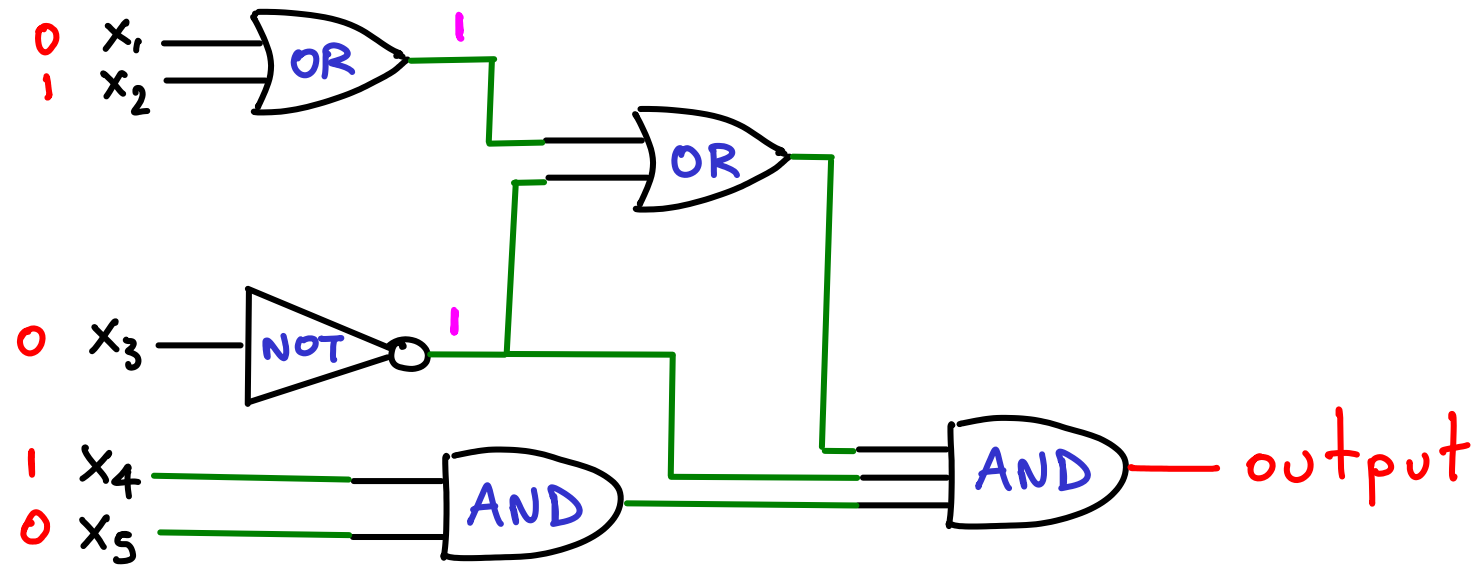


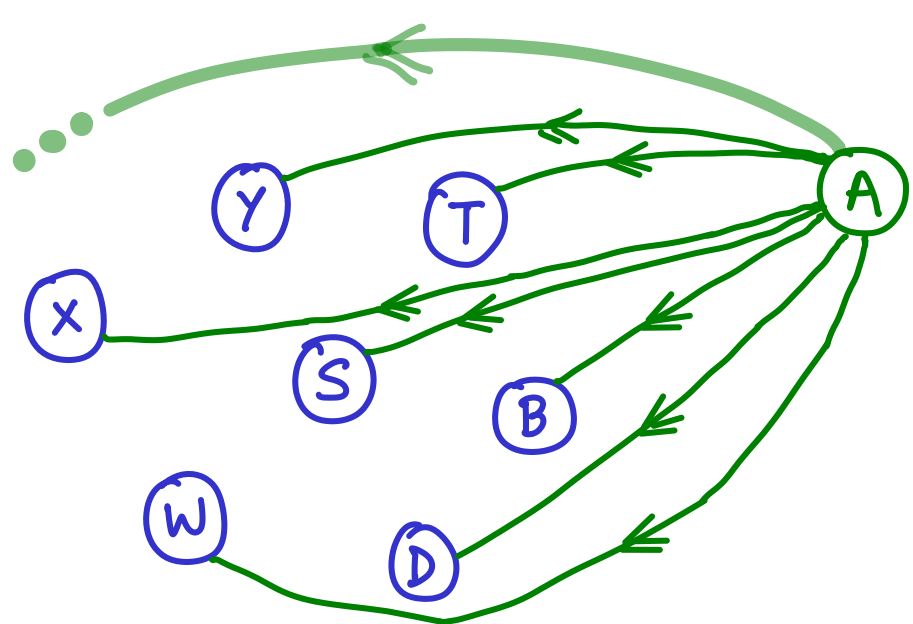


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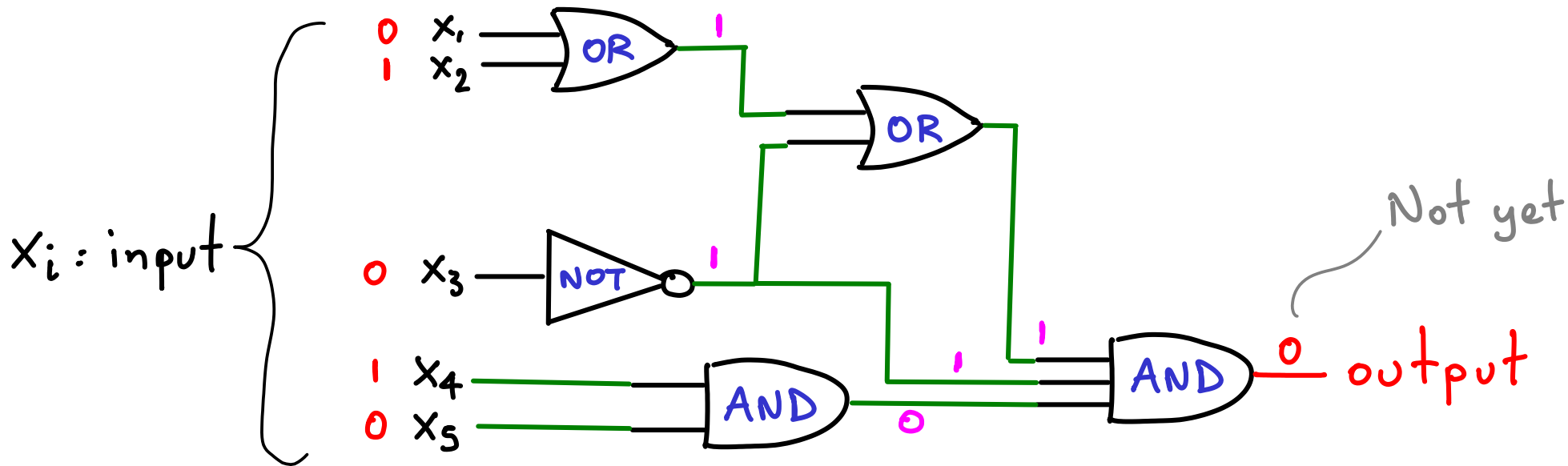
x_i : input

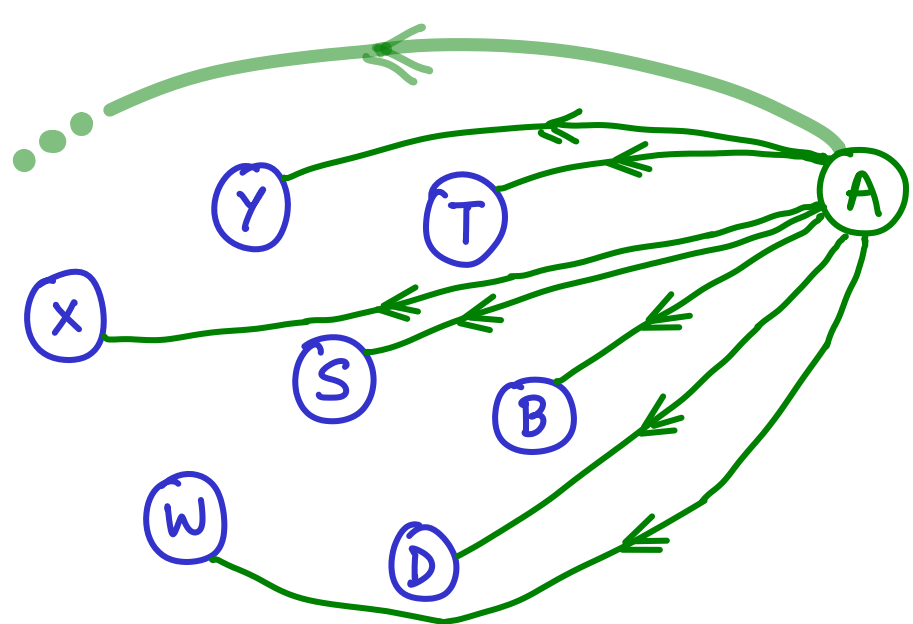




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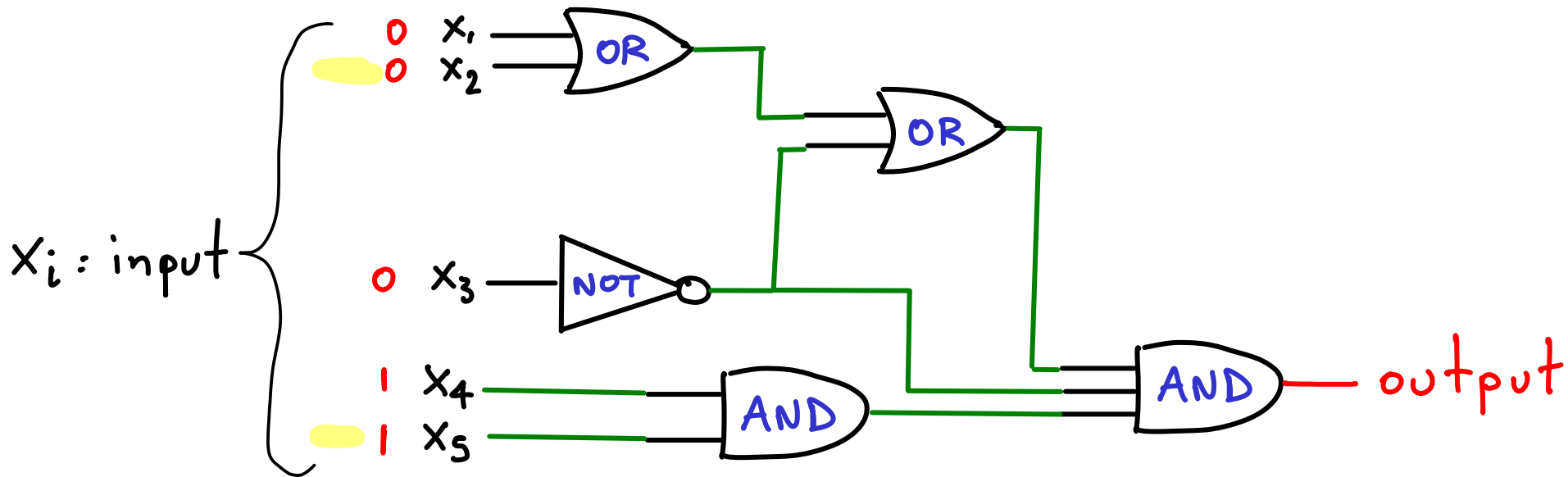
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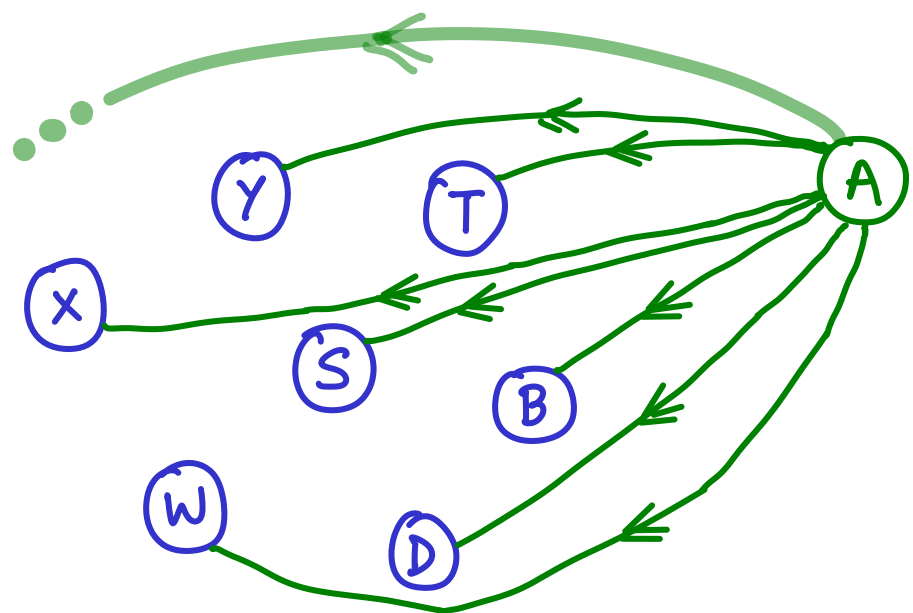




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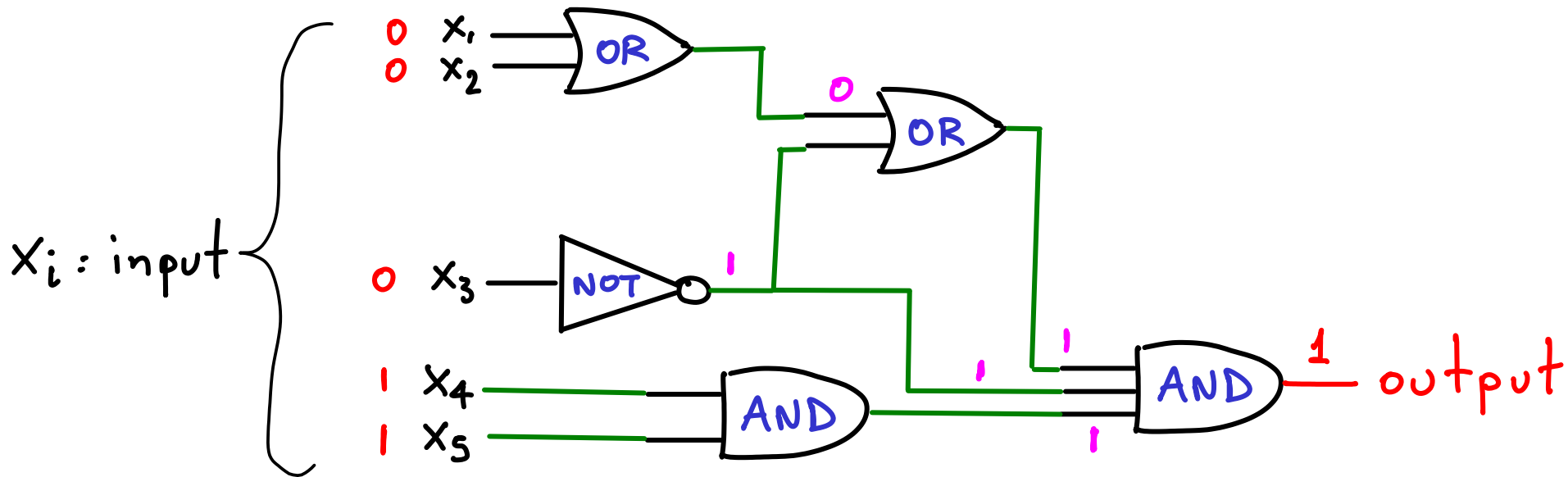
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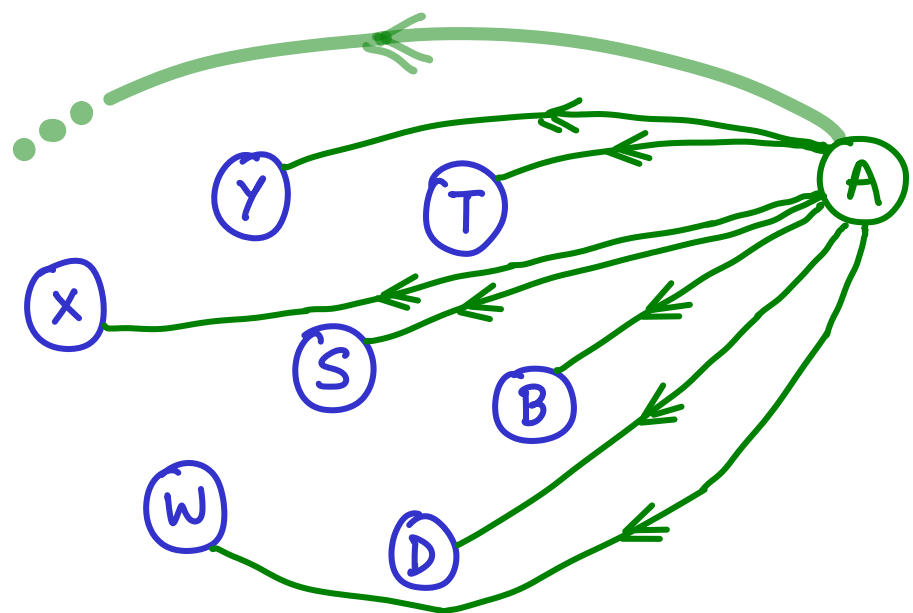




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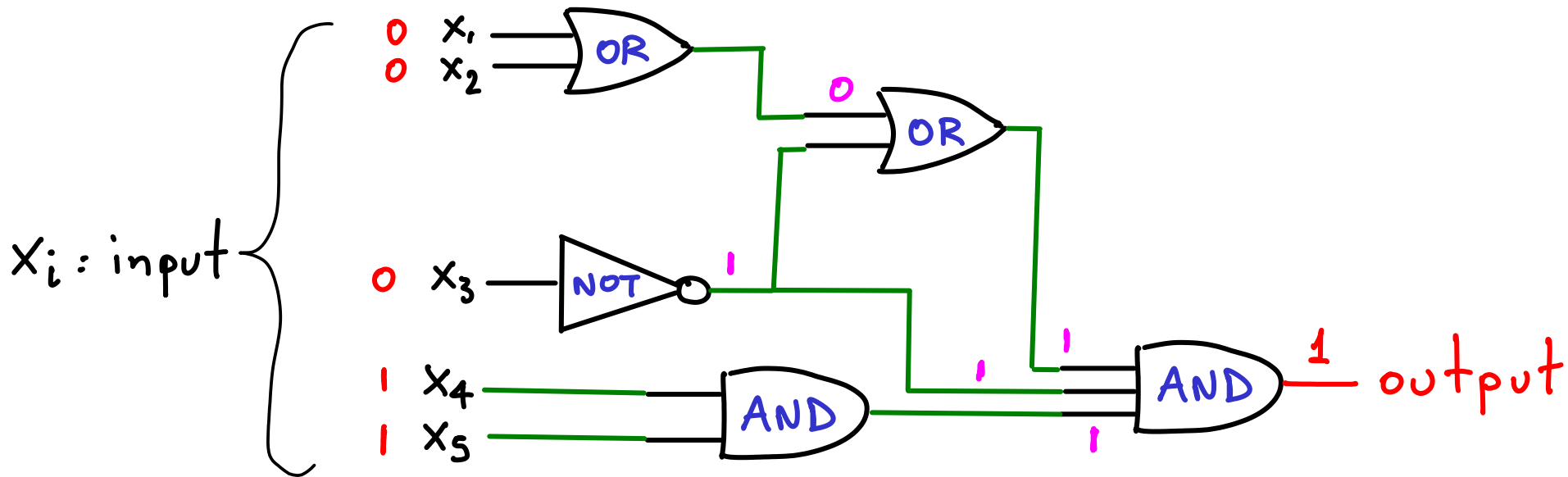
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Circuit SAT (satisfiability)
 The first NPC problem.

Given a circuit, can the output ever be 1?
 1 - in NP ... intuitive



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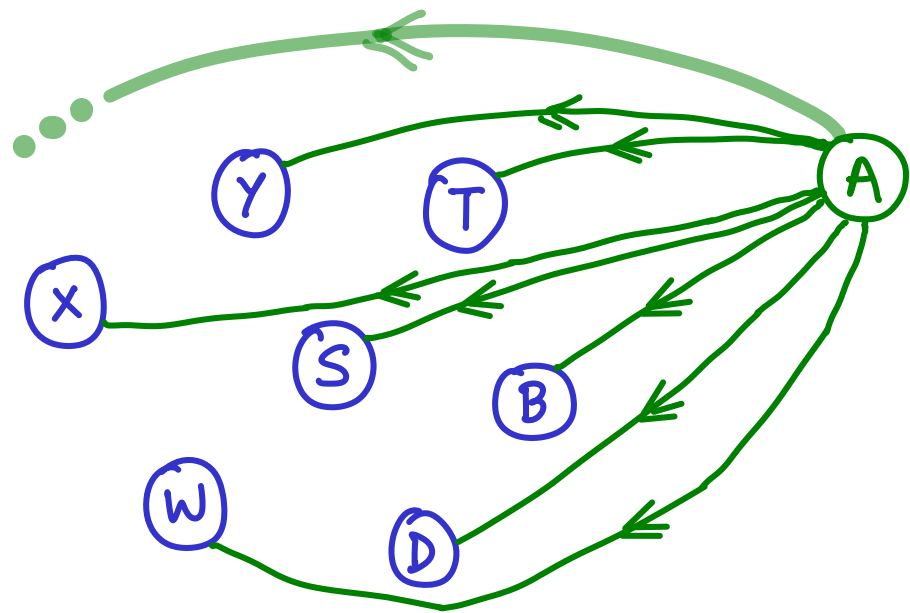
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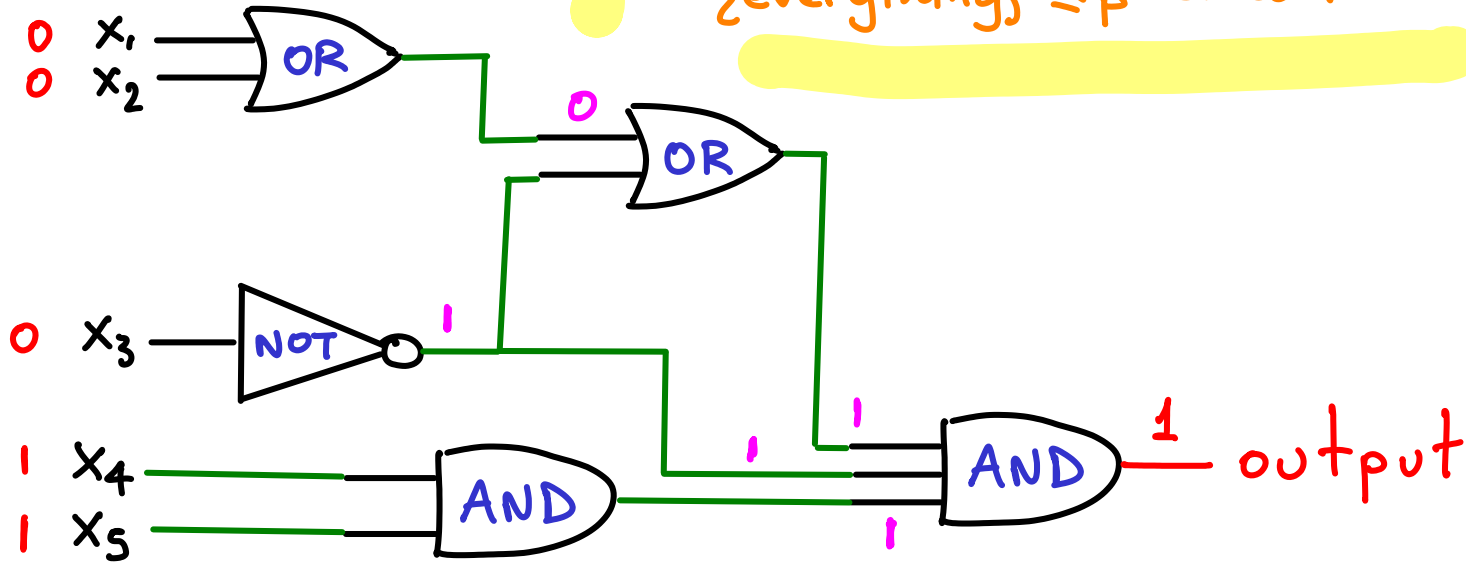
2 ~ every problem can be described as a circuit

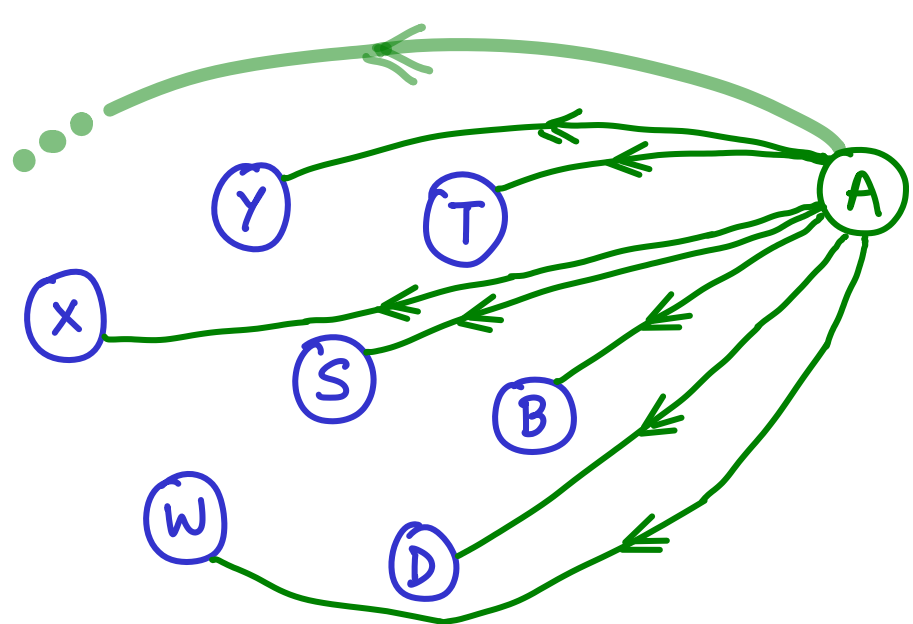
$\{\text{everything}\} \leq_p \text{circuit-SAT}$

technical



x_i : input





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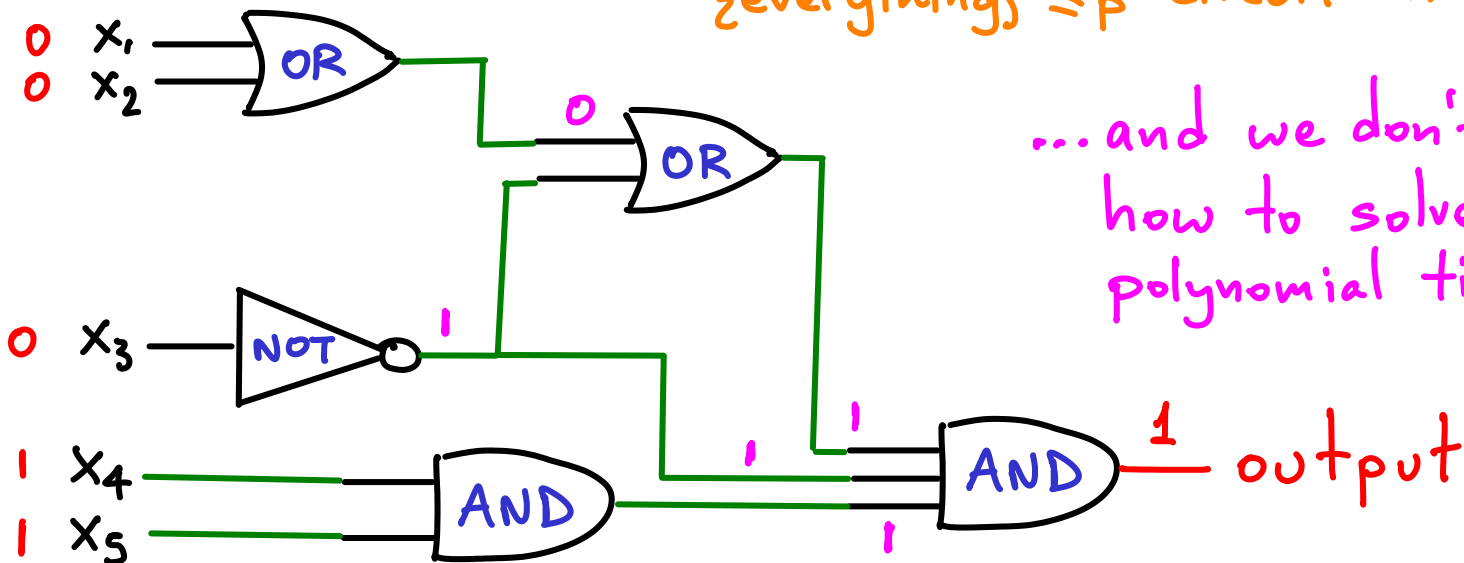
1 - in NP ... intuitive

2 ~ every problem can be described as a circuit

{everything} \leq_p circuit-SAT

technical

x_i : input



...and we don't know how to solve this in polynomial time. (not in P)

1 output

boolean
SAT

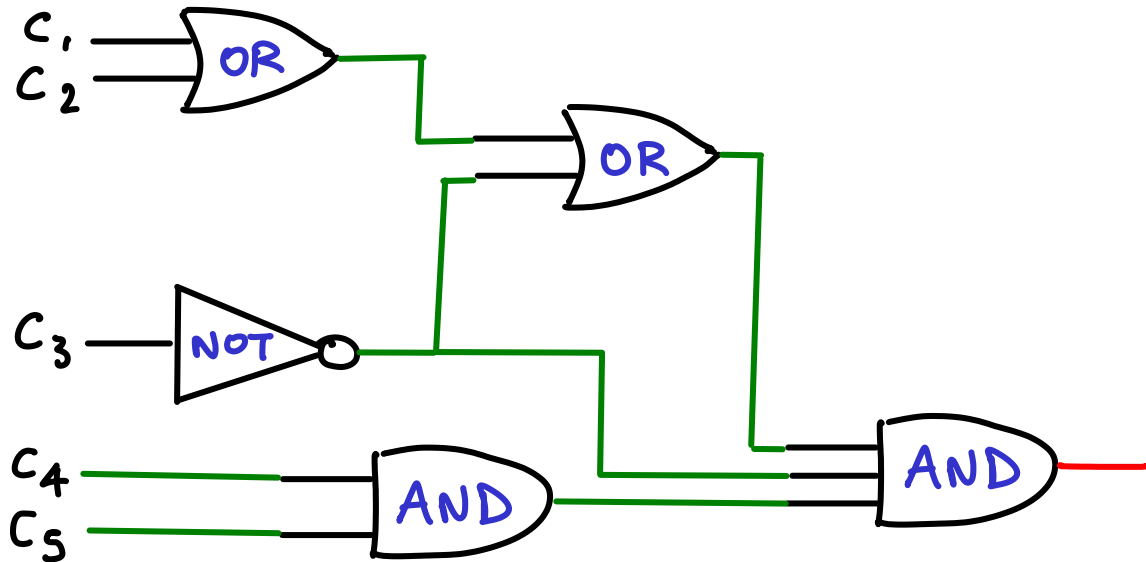
Boolean SAT $(x_1 \vee x_2 \vee \bar{x}_3) \wedge ((x_1 \leftrightarrow x_5) \vee (x_4 \rightarrow \bar{x}_3)) \rightarrow ? \rightarrow 1$

boolean
SAT

circuit
SAT

Boolean SAT $(x_1 \vee x_2 \vee \bar{x}_3) \wedge ((x_1 \leftrightarrow x_5) \vee (x_4 \rightarrow \bar{x}_3)) \rightarrow ? \rightarrow 1$

Given a circuit-SAT instance

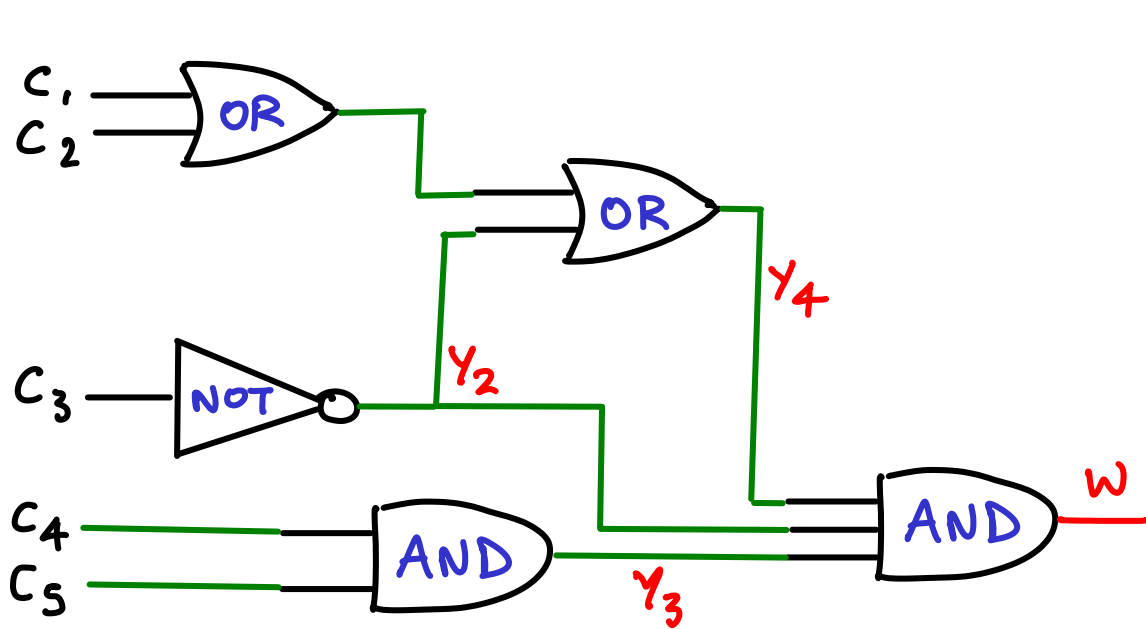


boolean SAT

circuit SAT

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Given a circuit-SAT instance transform (quickly) into a Boolean SAT.



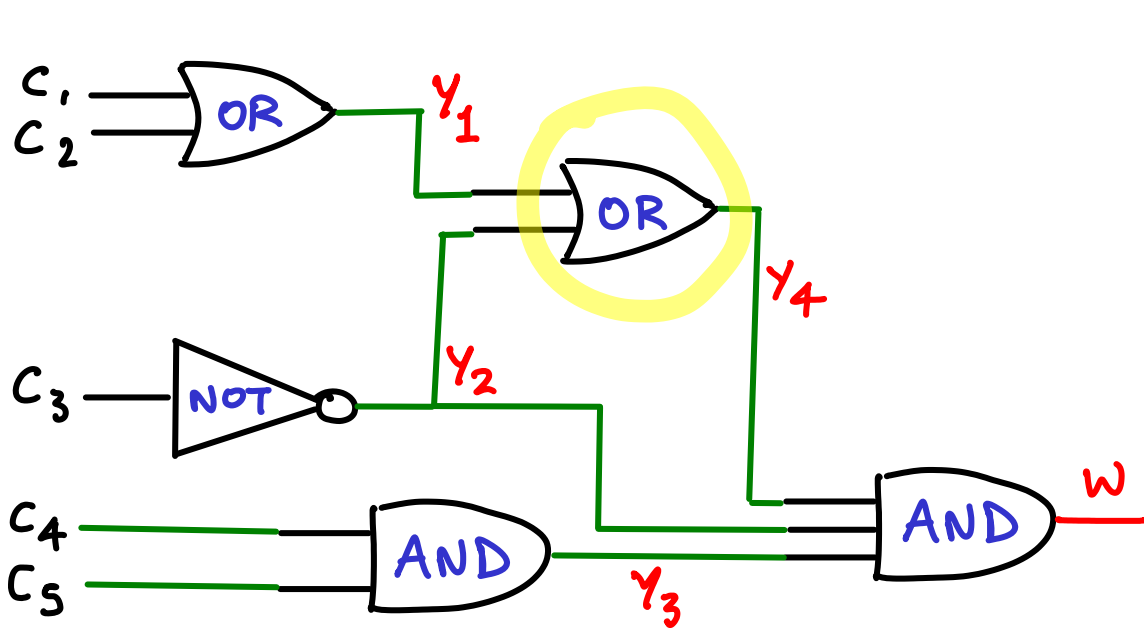
$w \wedge (w \leftrightarrow (y_4 \wedge y_2 \wedge y_3))$

boolean SAT

circuit SAT

Boolean SAT $(x_1 \vee x_2 \vee \bar{x}_3) \wedge ((x_1 \leftrightarrow x_5) \vee (x_4 \rightarrow \bar{x}_3)) \rightarrow ? \rightarrow 1$

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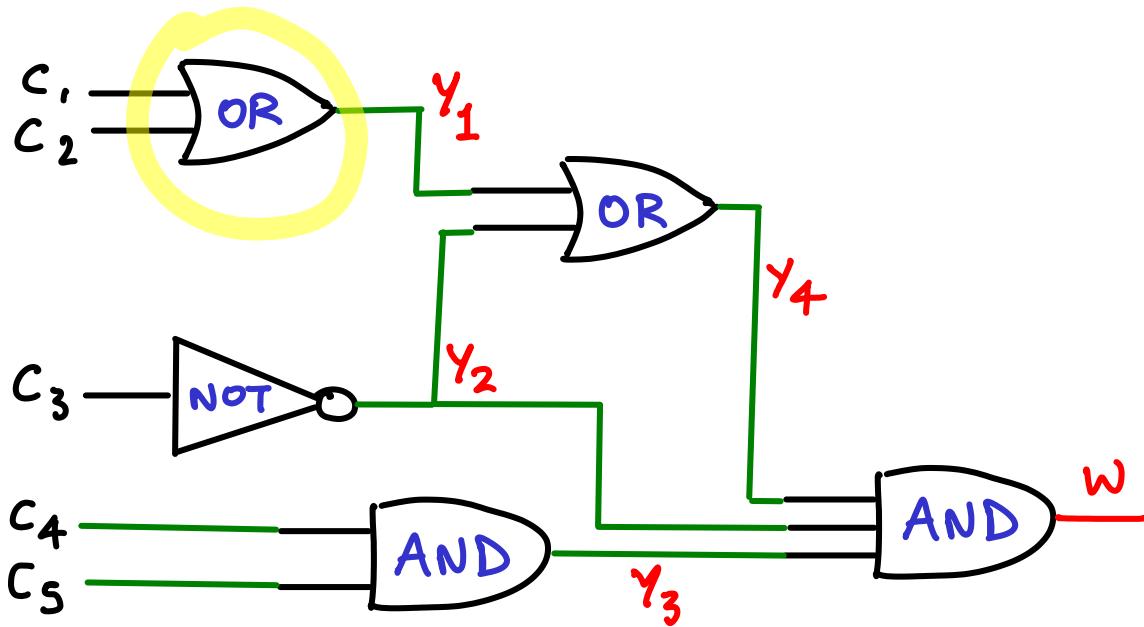
$w \wedge (w \leftrightarrow (y_4 \wedge y_2 \wedge y_3))$
 $\wedge (y_4 \leftrightarrow (y_1 \vee y_2))$

boolean SAT

circuit SAT

Boolean SAT $(x_1 \vee x_2 \vee \bar{x}_3) \wedge ((x_1 \leftrightarrow x_5) \vee (x_4 \rightarrow \bar{x}_3)) \rightarrow ? \rightarrow 1$

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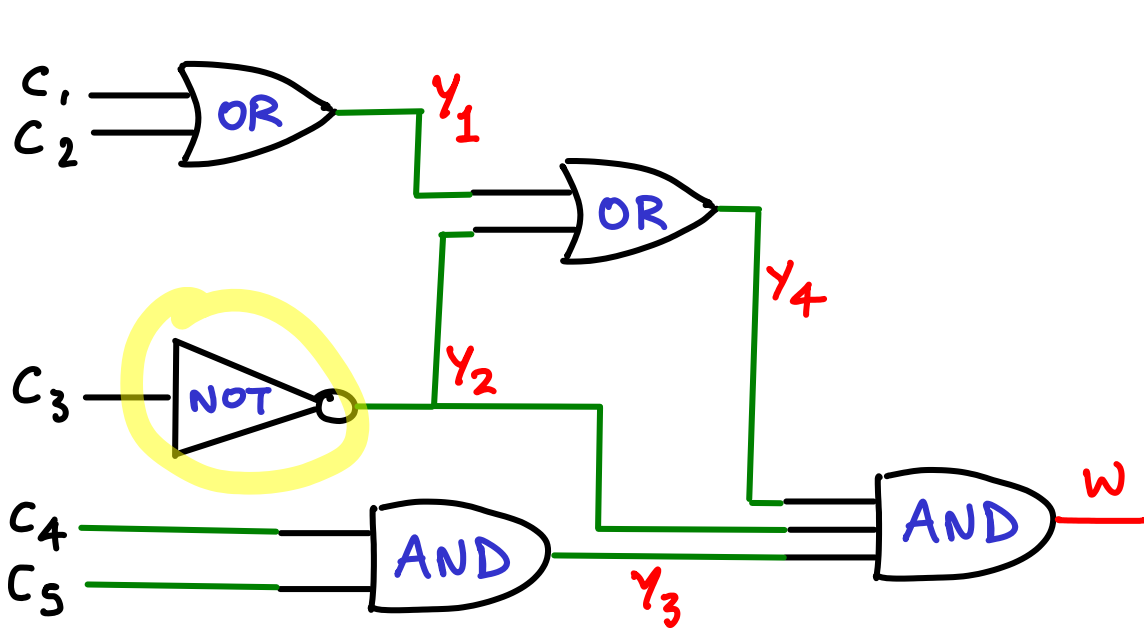
$$\begin{aligned} & w \wedge (w \leftrightarrow (y_4 \wedge y_2 \wedge y_3)) \\ & \wedge (y_4 \leftrightarrow (y_1 \vee y_2)) \\ & \wedge (y_1 \leftrightarrow (c_1 \vee c_2)) \end{aligned}$$

boolean
SAT

circuit
SAT

Boolean SAT $(x_1 \vee x_2 \vee \bar{x}_3) \wedge ((x_1 \leftrightarrow x_5) \vee (x_4 \rightarrow \bar{x}_3)) \rightarrow ? \rightarrow 1$

Given a circuit-SAT instance transform (quickly) into a Boolean SAT.



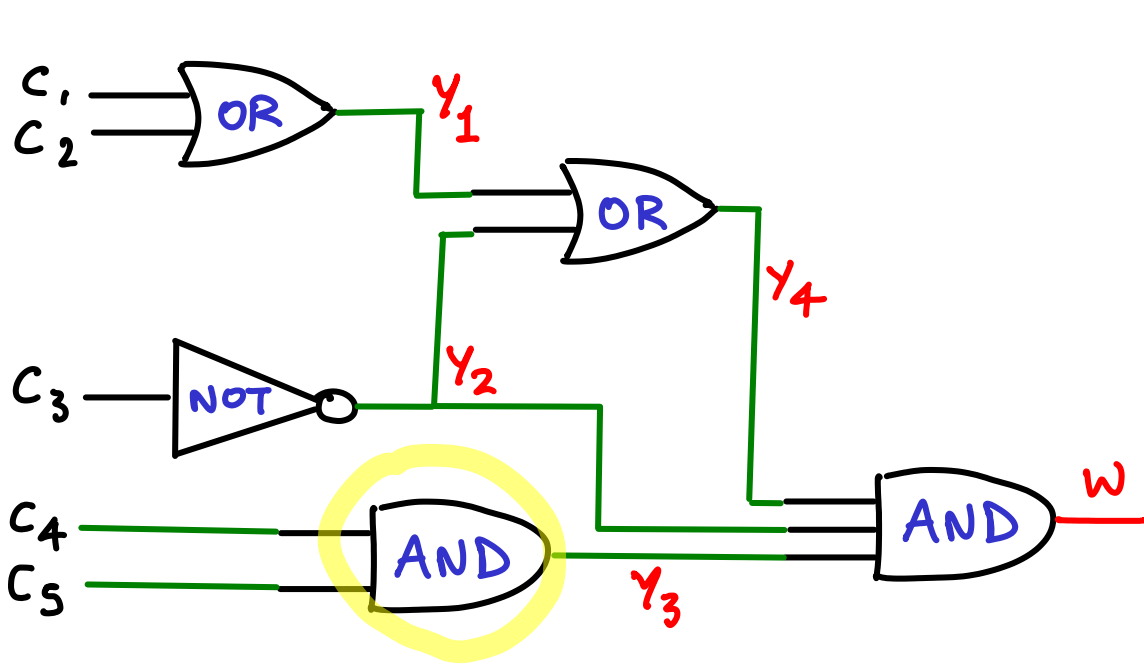
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 $\wedge (y_4 \leftrightarrow (y_1 \vee y_2))$
 $\wedge (y_1 \leftrightarrow (c_1 \vee c_2))$
 $\wedge (y_2 \leftrightarrow \bar{c}_3)$

boolean SAT

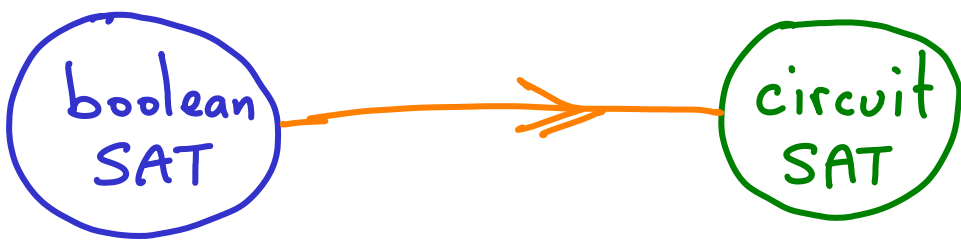
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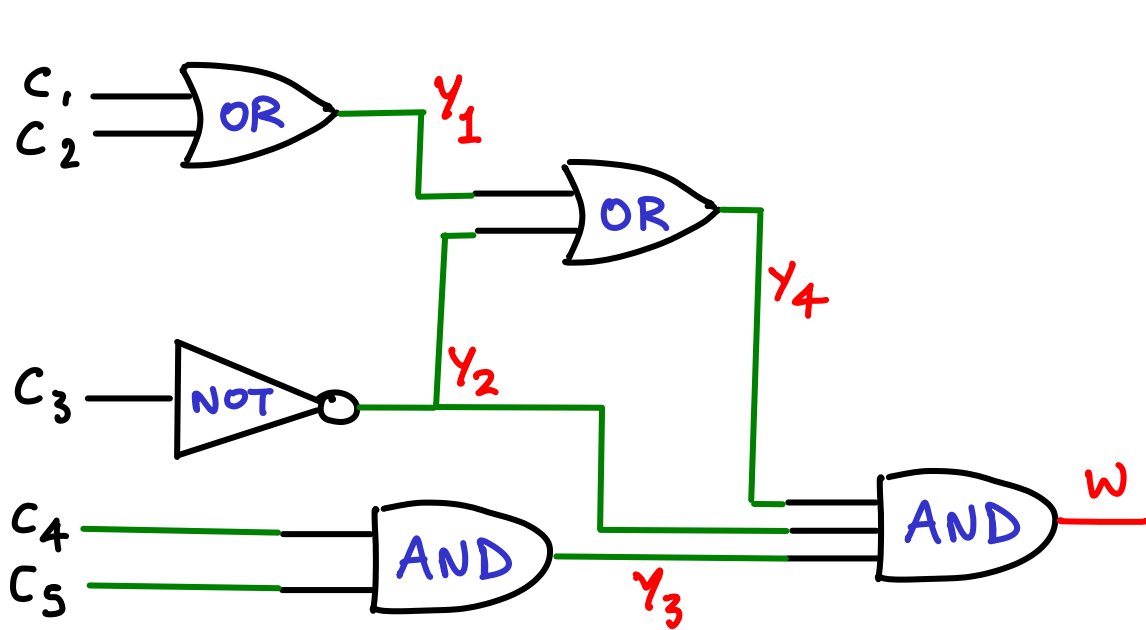
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 $\wedge (y_1 \leftrightarrow (c_1 \vee c_2))$
 $\wedge (y_2 \leftrightarrow \bar{c}_3)$
 $\wedge (y_3 \leftrightarrow (c_4 \wedge c_5))$



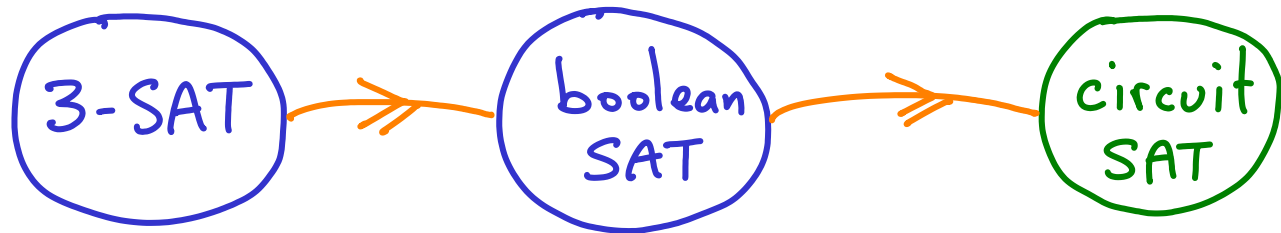
circuit-SAT \leq_p Boolean SAT
 (actually also prototypical)

Boolean SAT $(x_1 \vee x_2 \vee \bar{x}_3) \wedge ((x_1 \leftrightarrow x_5) \vee (x_4 \rightarrow \bar{x}_3)) \rightarrow ? \rightarrow 1$

Given a circuit-SAT instance transform (quickly) into a Boolean SAT.



$w \wedge (w \leftrightarrow (y_4 \wedge y_2 \wedge y_3))$
 $\wedge (y_4 \leftrightarrow (y_1 \vee y_2))$
 $\wedge (y_1 \leftrightarrow (c_1 \vee c_2))$
 $\wedge (y_2 \leftrightarrow \bar{c}_3)$
 $\wedge (y_3 \leftrightarrow (c_4 \wedge c_5))$



3-SAT

$$(x_1 \vee x_2 \vee x_3)$$

$$\wedge (x_1 \vee x_4 \vee x_5)$$

$$\wedge (x_2 \vee \bar{x}_4 \vee x_{13})$$

$$\wedge (x_2 \vee \bar{x}_3 \vee x_3)$$

⋮

k clauses

each w/ 3 literals

$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

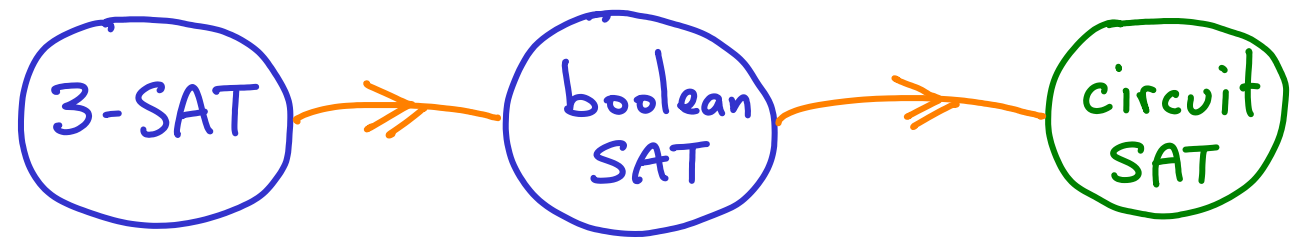
} k clauses

construct
graph
(quickly)

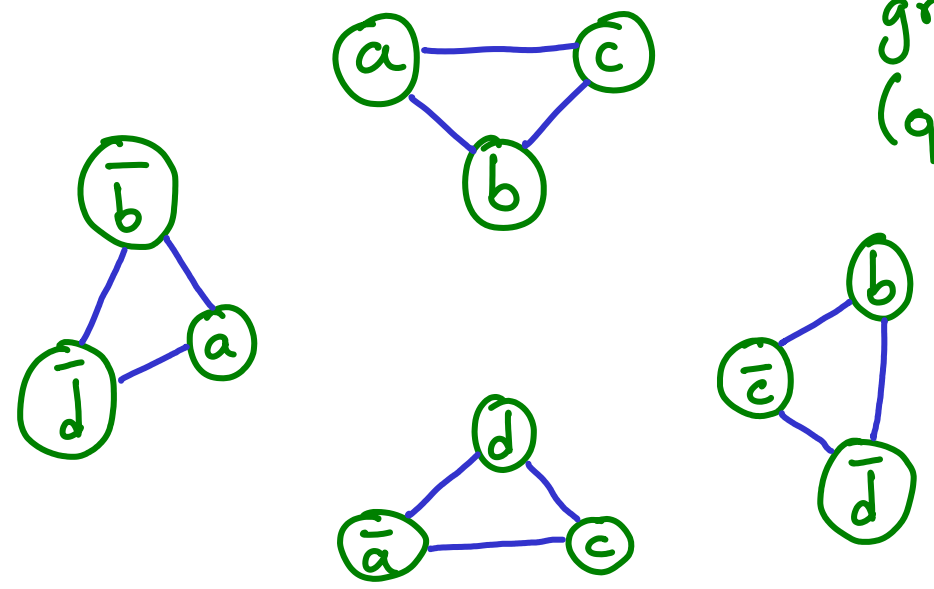


$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

k clauses



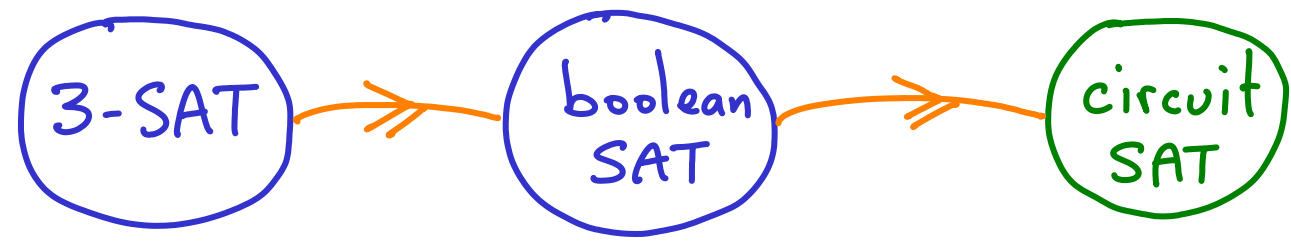
construct graph (quickly)



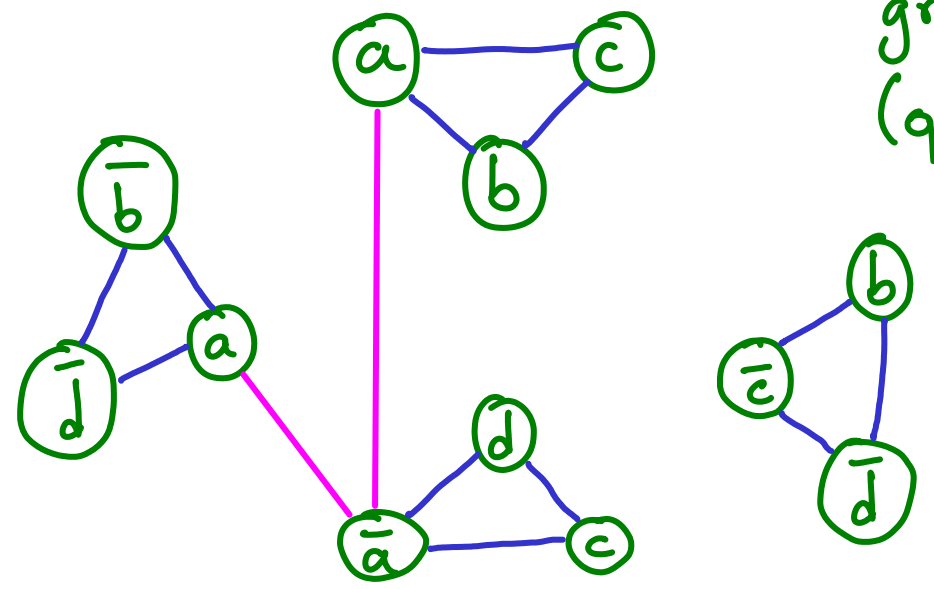
$(a \vee b \vee c)$
 $(a \vee \bar{b} \vee \bar{d})$ $(b \vee \bar{c} \vee \bar{d})$
 $(\bar{a} \vee c \vee d)$

$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

} k clauses

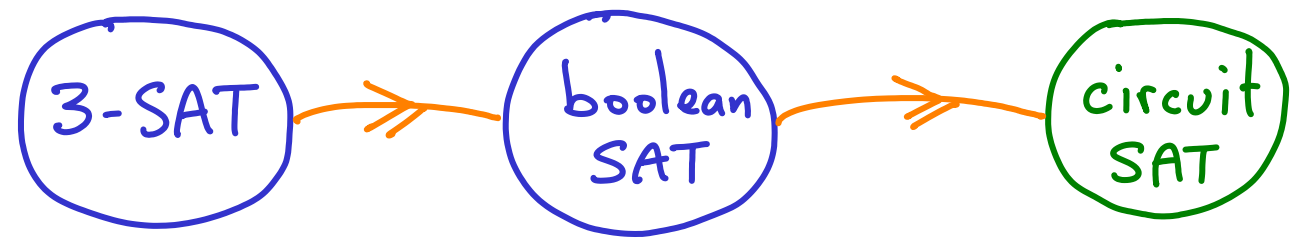


construct graph (quickly)

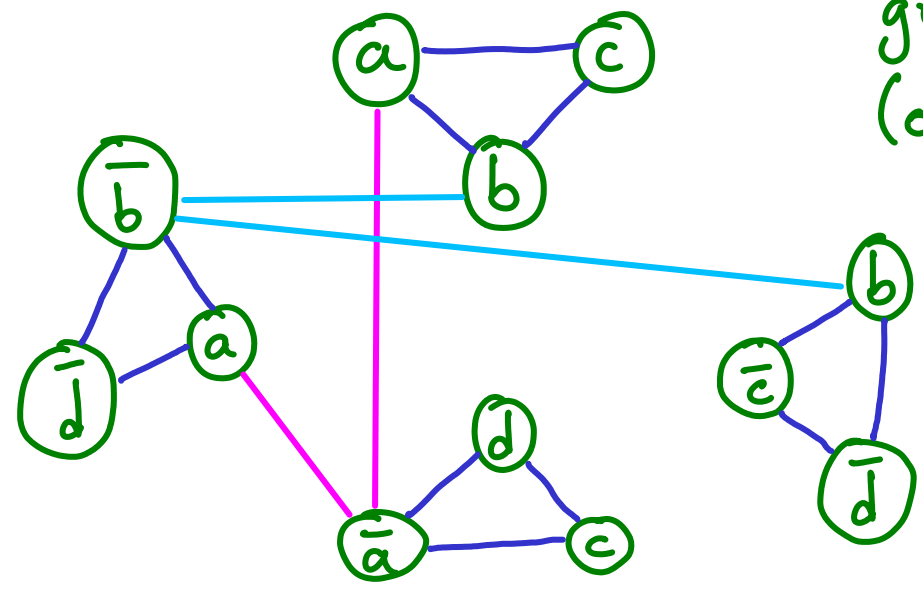


$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

} k clauses

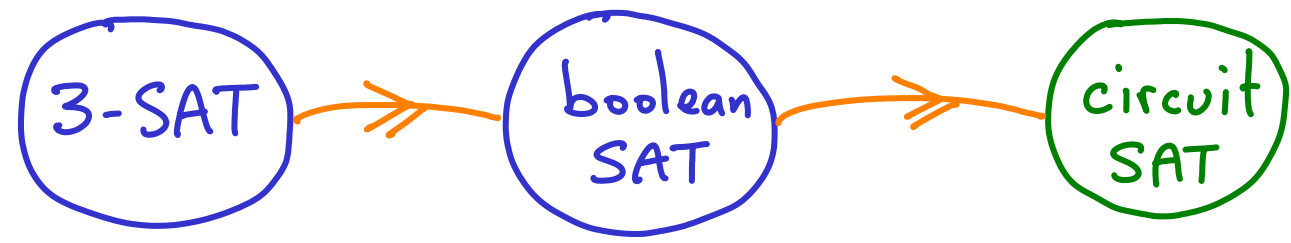


construct graph (quickly)

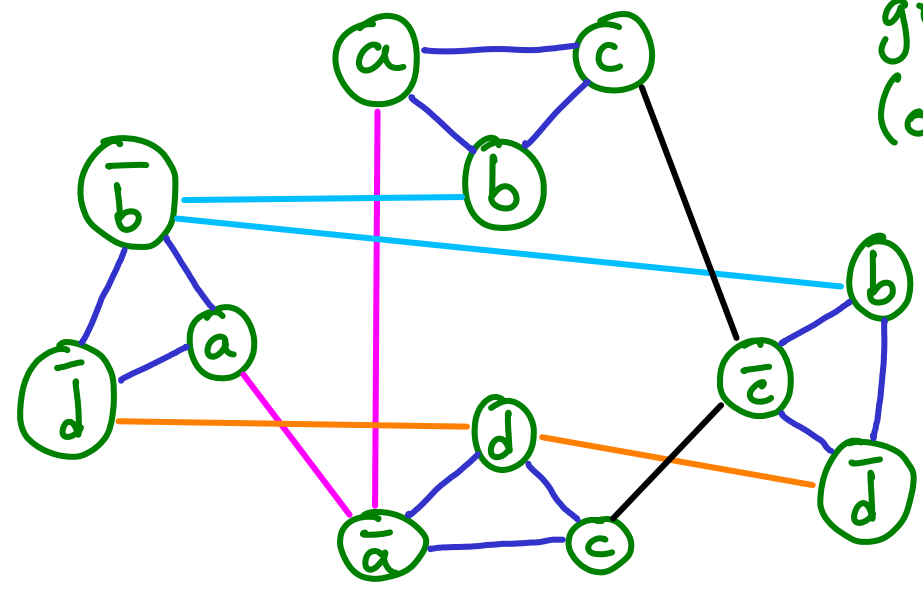


$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

} k clauses

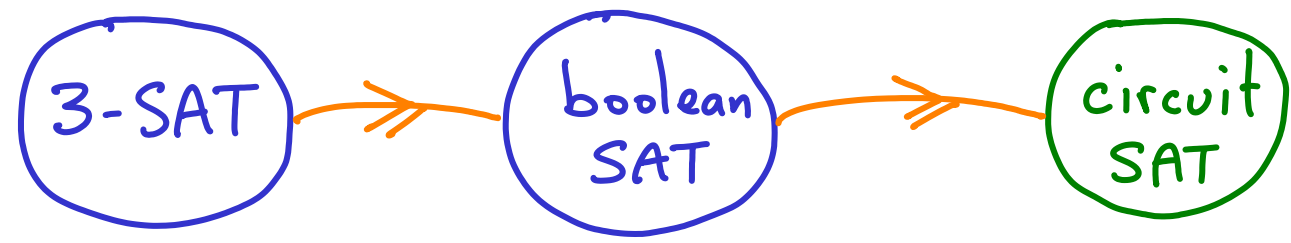


construct graph (quickly)

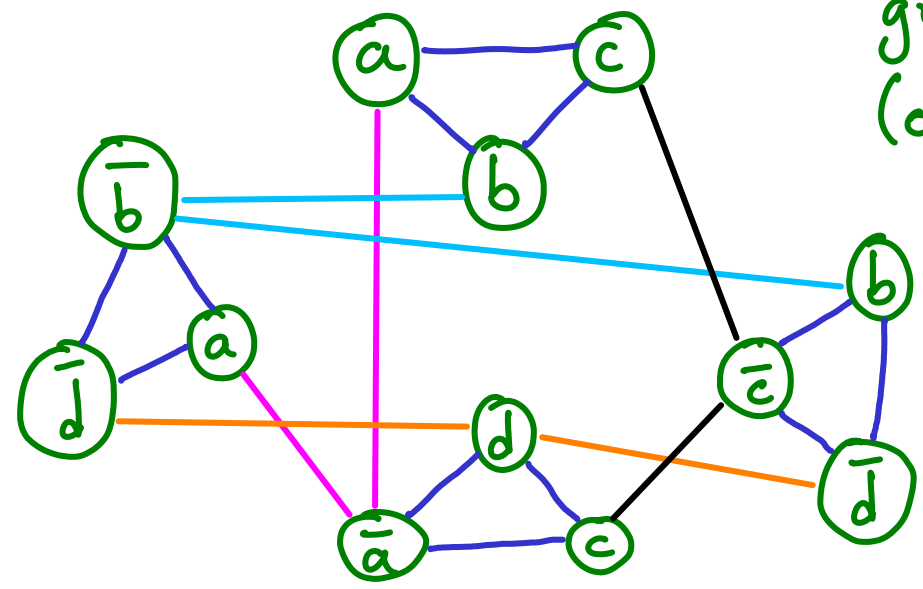


$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

} k clauses



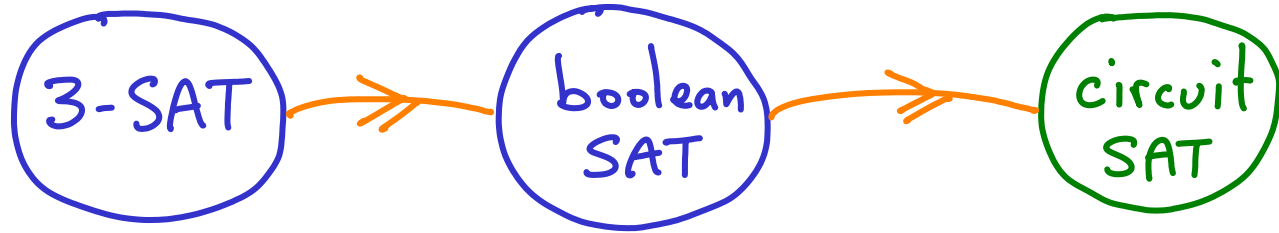
construct graph (quickly)



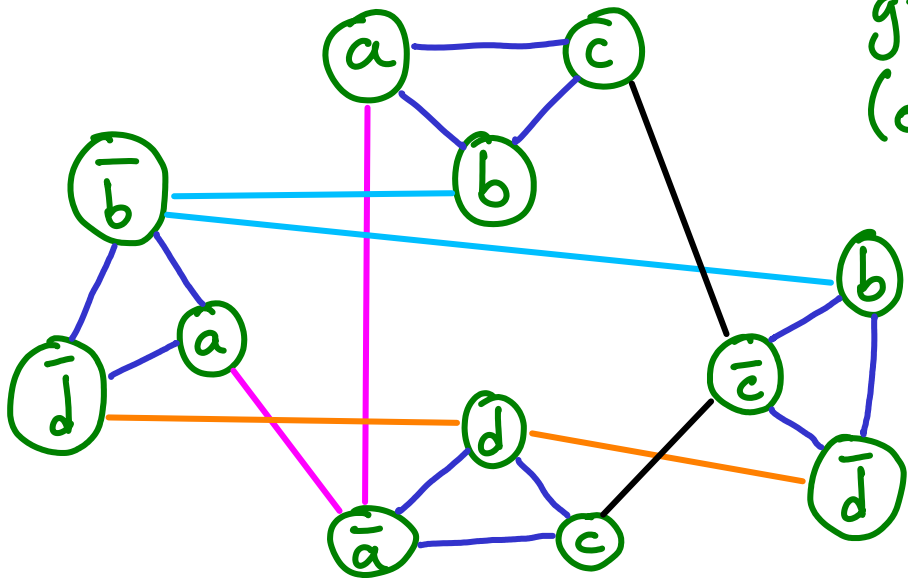
Ask: does this graph have k independent vertices?

$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

k clauses



construct graph (quickly)



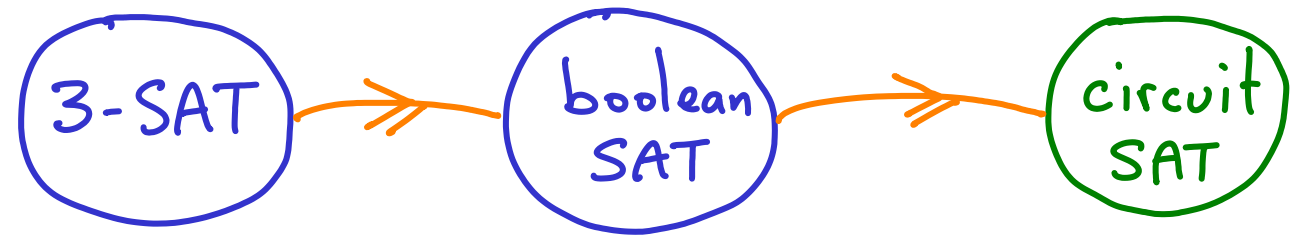
Ask: does this graph have k independent vertices?

Would need 1 vertex per triple
(can't have 2 in any triple)

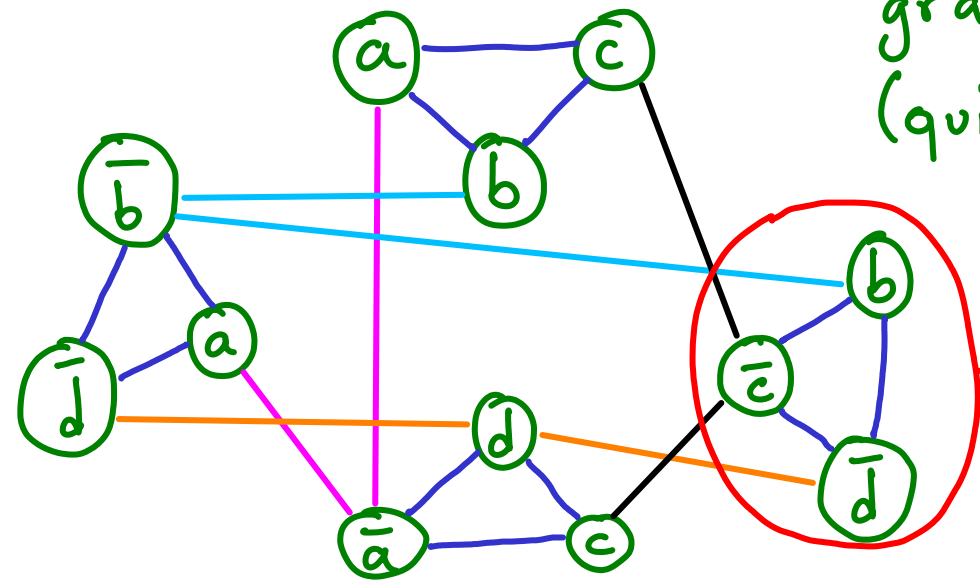
Answer maps back to 3-SAT

$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

k clauses



construct graph (quickly)



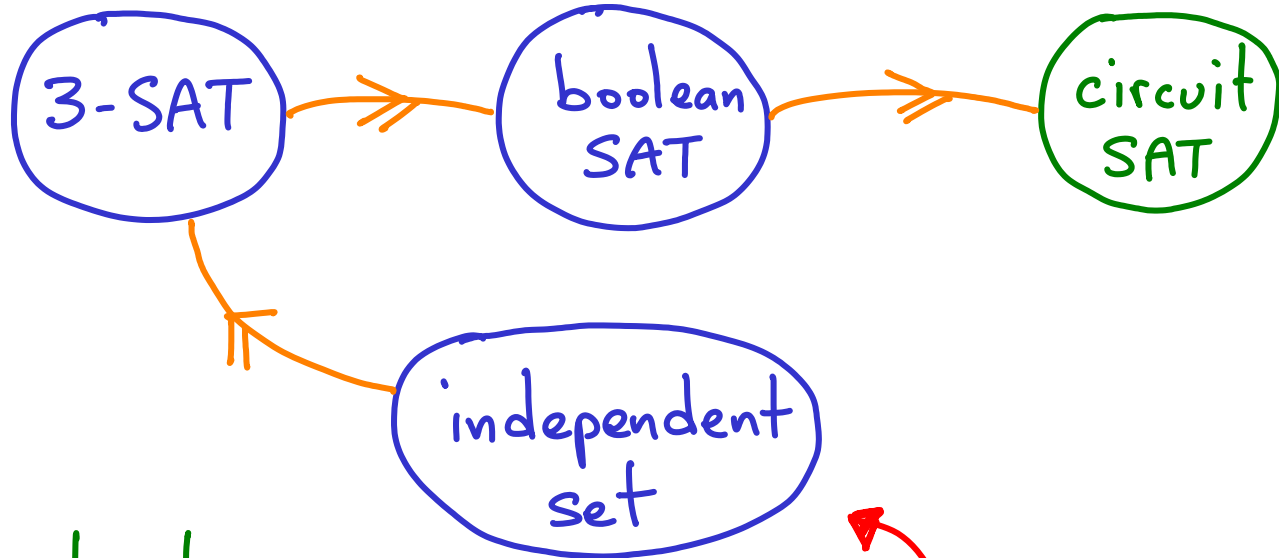
≤ 1 per triple

Ask: does this graph have k independent vertices?

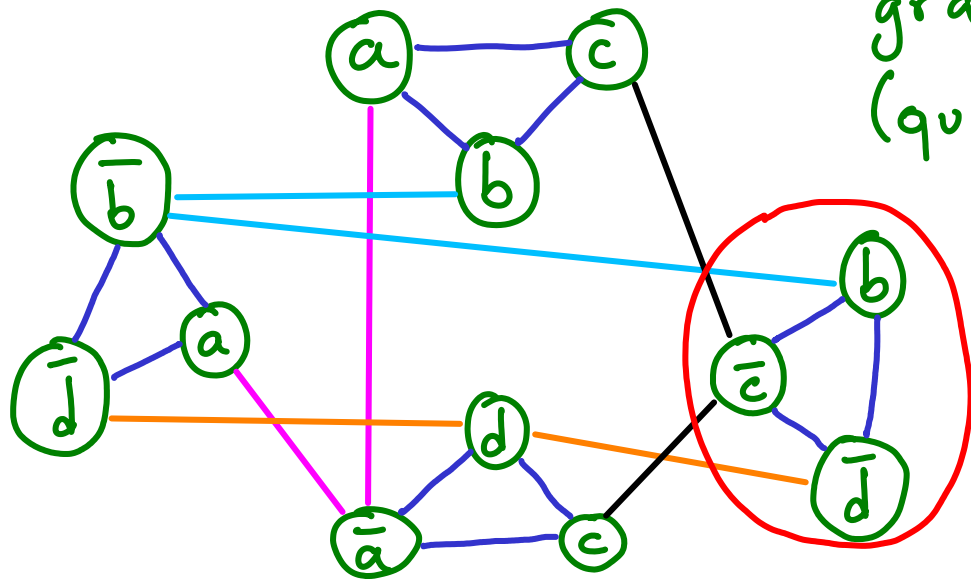
If yes, then 3-SAT is \checkmark
 If no, then 3-SAT is \times

$(a \vee b \vee c)$
 $\wedge (b \vee \bar{c} \vee \bar{d})$
 $\wedge (\bar{a} \vee c \vee d)$
 $\wedge (a \vee \bar{b} \vee \bar{d})$

k clauses



construct graph (quickly)

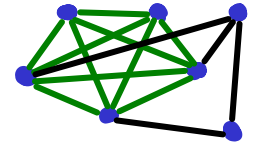


≤ 1 per triple

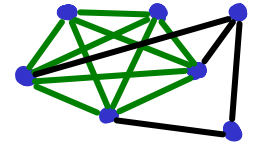
Ask: does this graph have k independent vertices?

If yes, then 3-SAT is \checkmark
 If no, then 3-SAT is \times

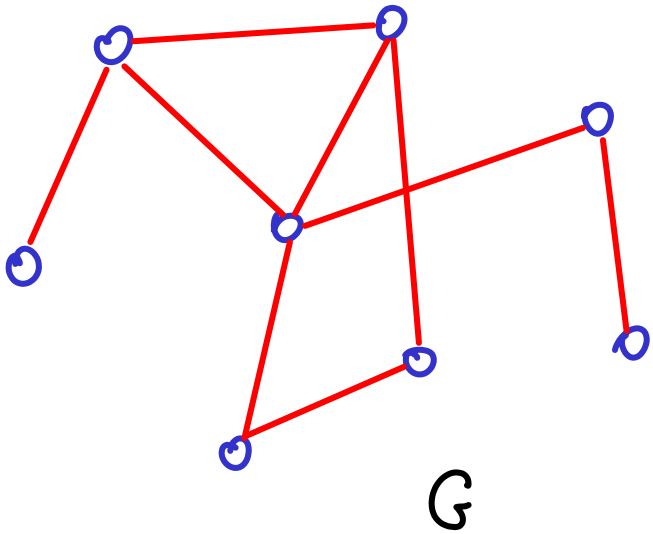
CLIQUE in a graph : subset of V s.t. all pairs of vertices share edges.



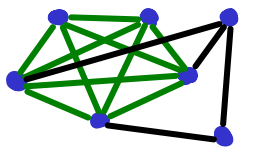
CLIQUE in a graph : subset of V s.t. all pairs of vertices share edges.



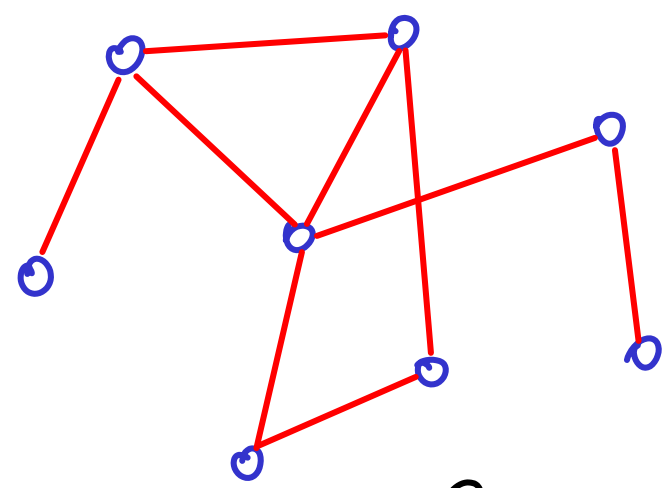
size k independent set in G ?



CLIQUE in a graph : subset of V s.t. all pairs of vertices share edges.

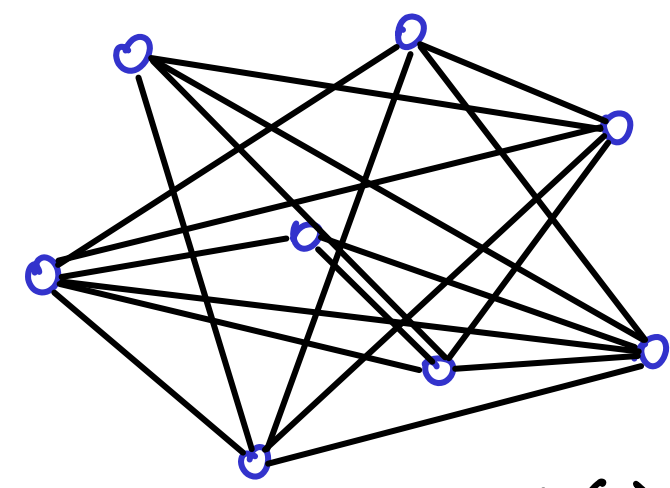


size k independent set in G ?



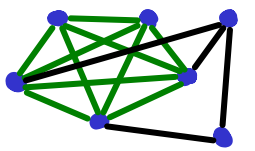
G

transform



complement $(G) = G^c$

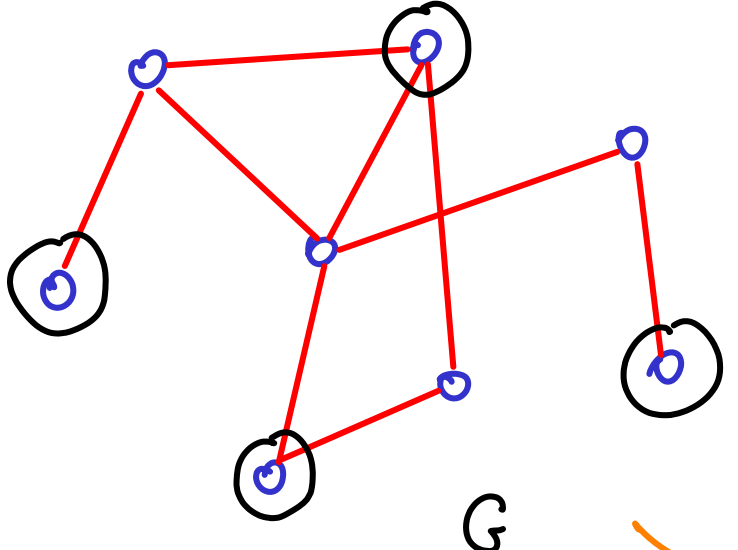
CLIQUE in a graph : subset of V s.t. all pairs of vertices share edges.



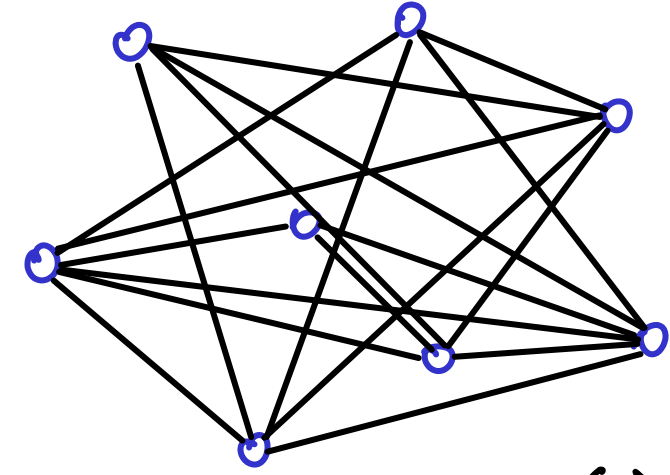
size k independent set in G ?



size k clique in G^c ?

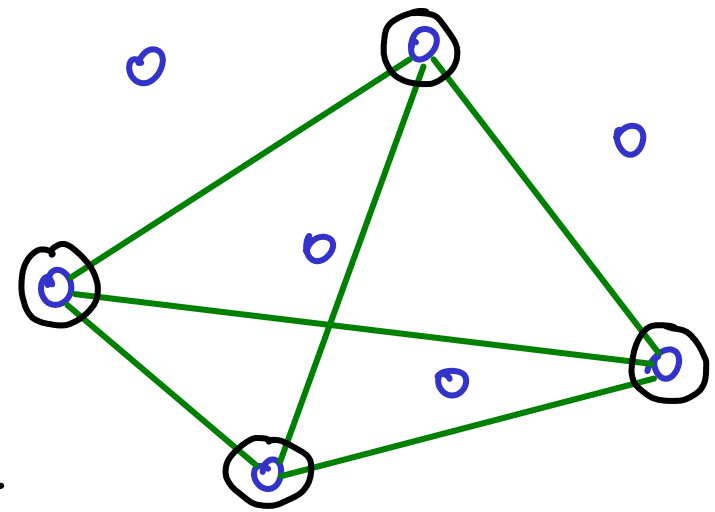


G

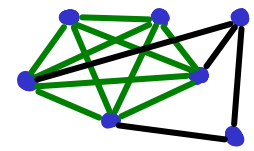


complement (G) = G^c

transform



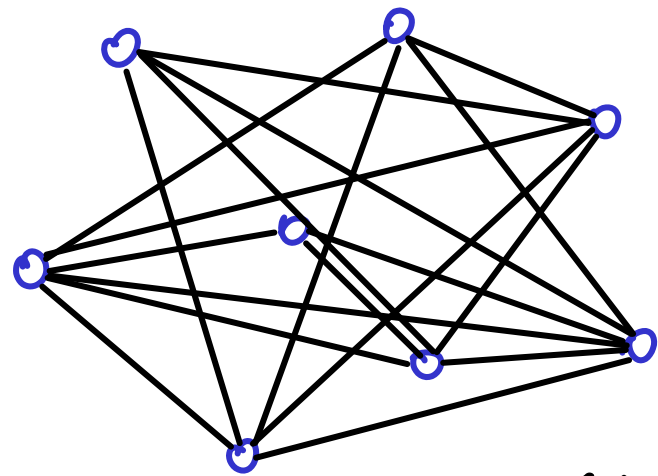
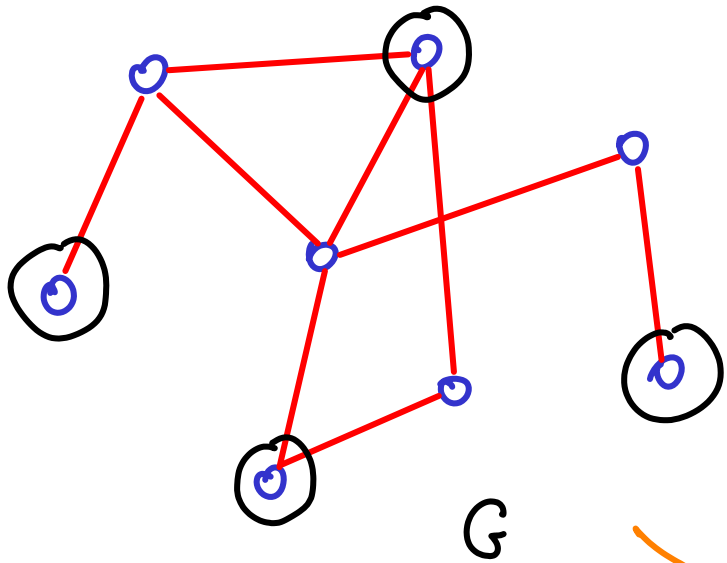
CLIQUE in a graph : subset of V s.t. all pairs of vertices share edges.



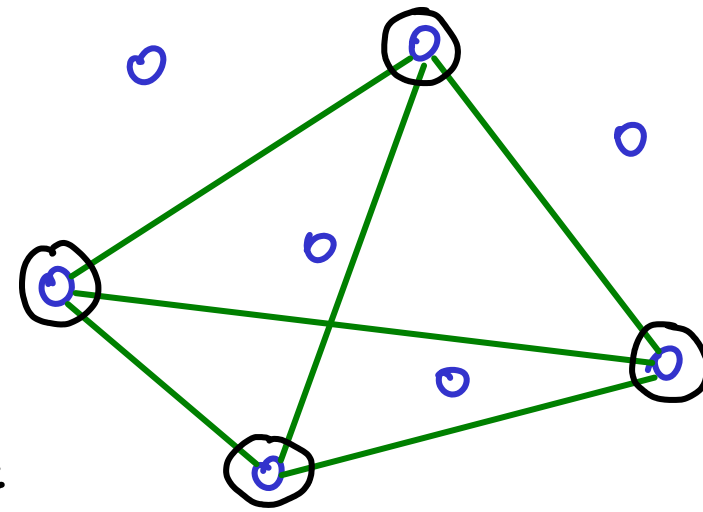
size k independent set in G ?



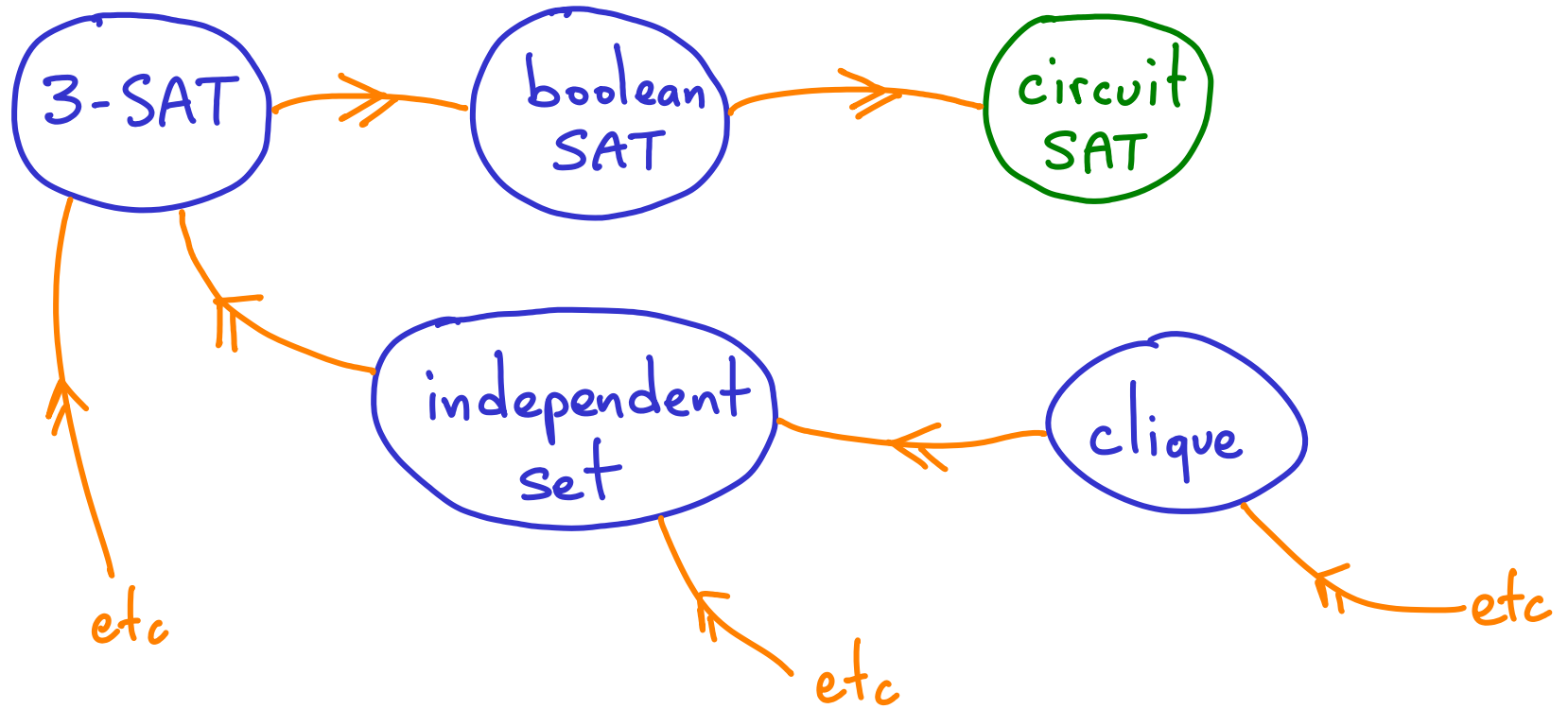
size k clique in G^c ?



transform



Asking if a graph has a clique of size k : NPC



OTHER HARD PROBLEMS

- knapsack: given item types, w/ size & value, fill a bag w/ max value
(multiples ok)
- subset sum: does a subset of given integers sum to t ?
- partition: split set of integers in 2 groups with equal sums
- planar SAT: SAT without wire crossings
- set cover: given some sets, select min# sets s.t. all elements are present
- hitting set: given sets, select min# elements s.t. all sets are represented
- longest path: visiting each vertex once.
- Steiner tree: \sim MST on selected subset of a graph
- traveling salesman: min-cost simple cycle on weighted complete graph

OTHER HARD PROBLEMS

... & some are even harder

Tetris

Minesweeper

Lemmings

Mario Bros

Pac-man

Prince of Persia

Portal

Doom

etc