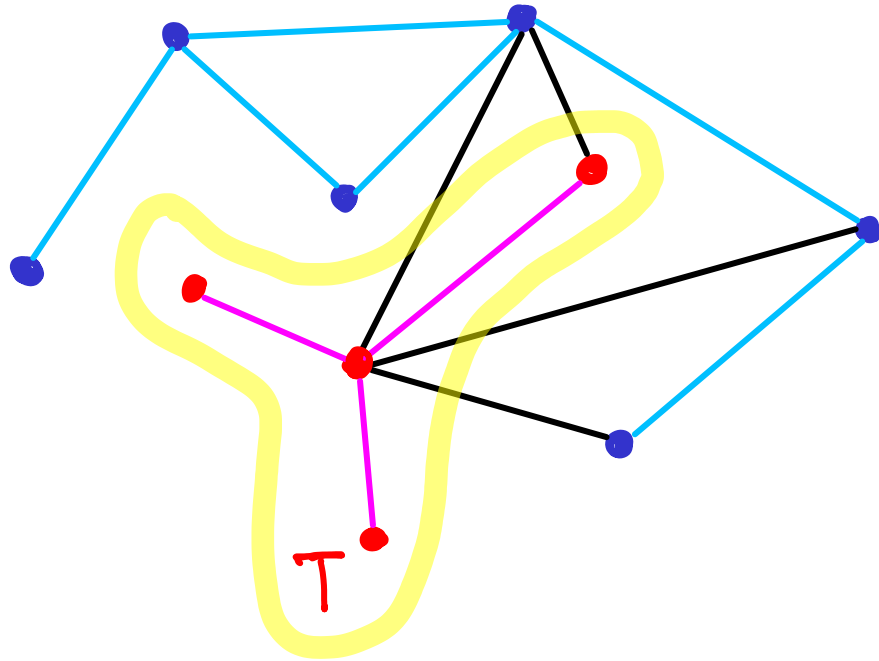


# PRIM'S ALGORITHM for MST

R. PRIM - 1957

(V. JARNIK - 1930)

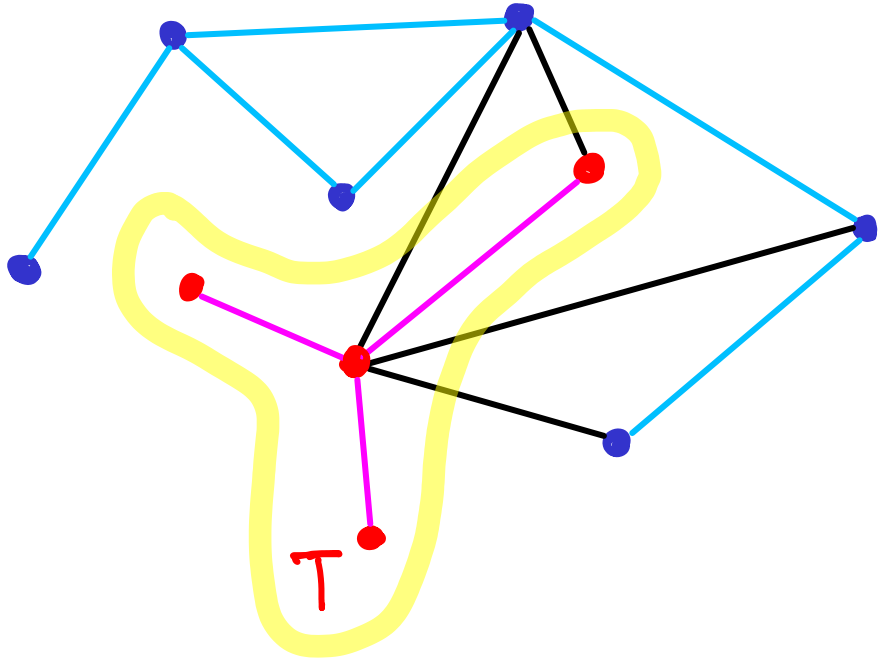
# PRIM'S ALGORITHM for MST



Uses basic principle:

Given a subtree  $T$  of MST,  
the "lightest" edge connecting  
to a vertex not in  $T$   
can be added to  $T$ .

# PRIM'S ALGORITHM for MST

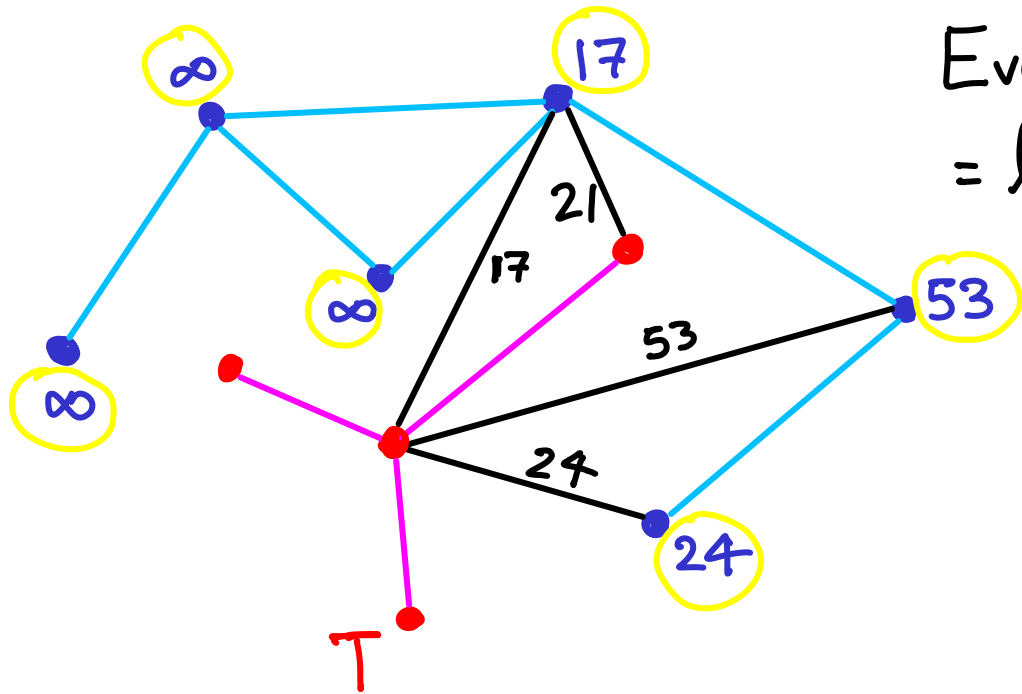


Uses basic principle:

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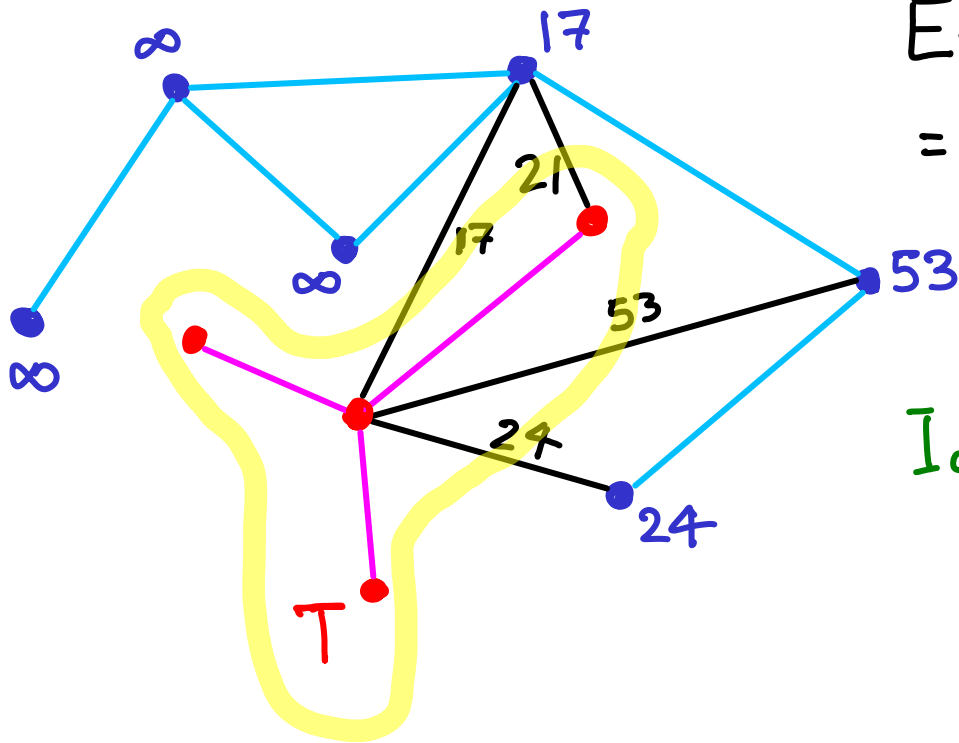
Grow one tree, incrementally adding one edge (& vertex)

# PRIM'S ALGORITHM for MST



Every vertex not in  $T$  has a score =  
= lightest edge weight connecting it to  $T$

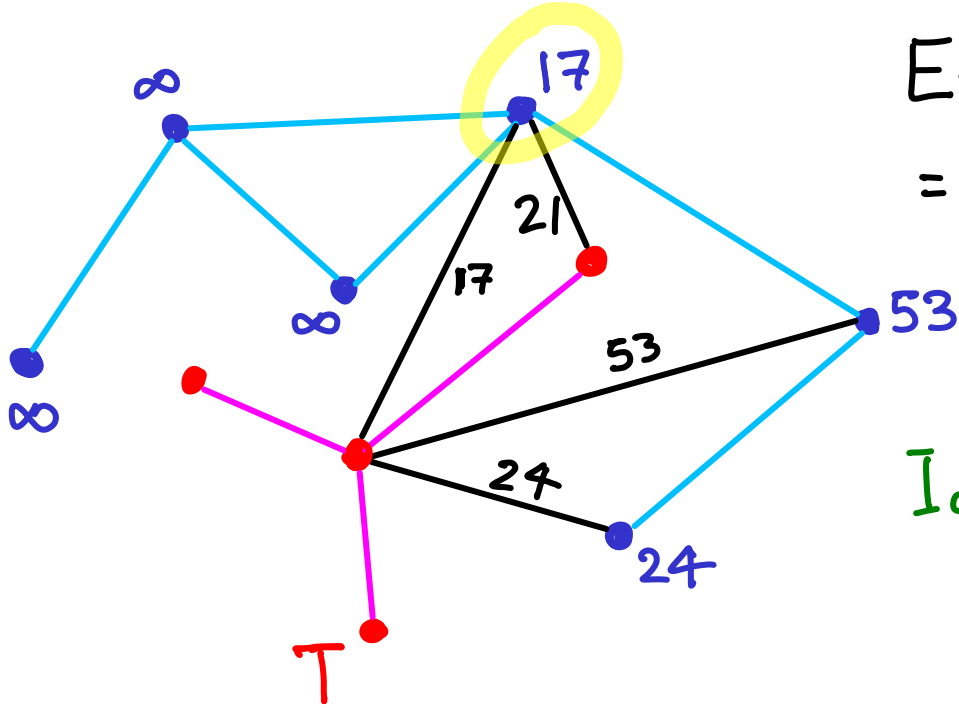
# PRIM'S ALGORITHM for MST



Every vertex not in  $T$  has a score =  
= lightest edge weight connecting it to  $T$

Identify lightest edge crossing cut:  
How?

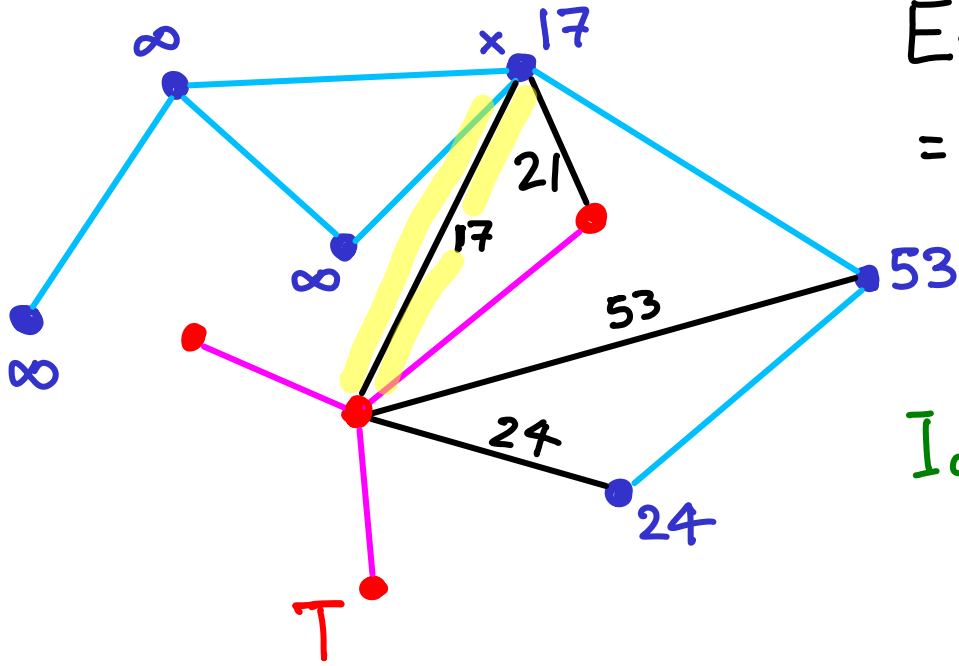
# PRIM'S ALGORITHM for MST



Every vertex not in  $T$  has a score =  
= lightest edge weight connecting it to  $T$

Identify lightest edge crossing cut:  
1) identify min-score vertex, (x)

# PRIM'S ALGORITHM for MST

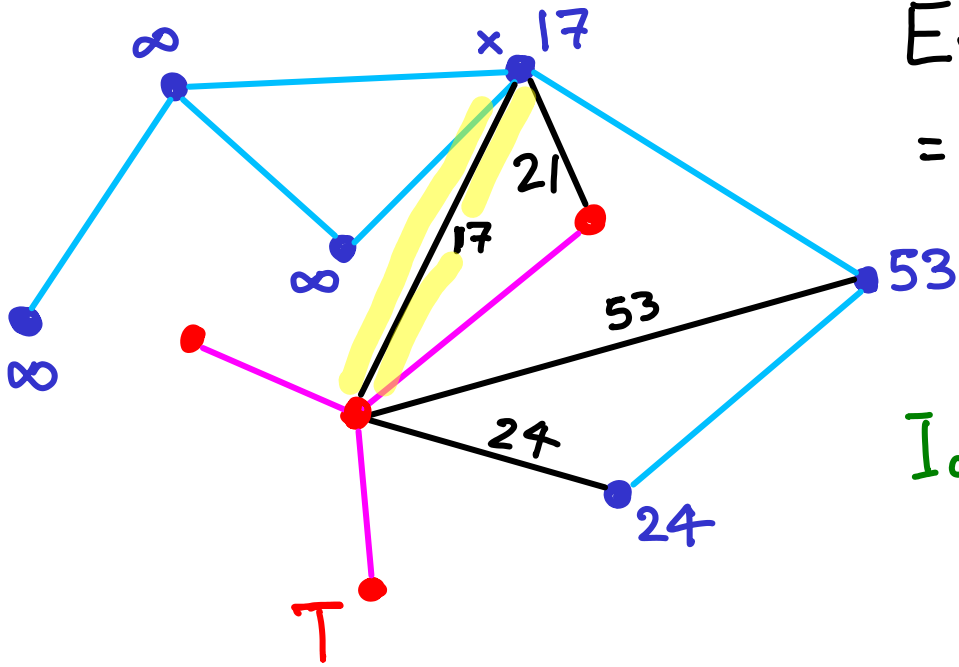


Every vertex not in  $T$  has a score =  
= lightest edge weight connecting it to  $T$

Identify lightest edge crossing cut:

- 1) identify min-score vertex,  $x$
- 2) identify lightest edge from  $x$  to  $T$

# PRIM'S ALGORITHM for MST



Every vertex not in  $T$  has a score =  
= lightest edge weight connecting it to  $T$

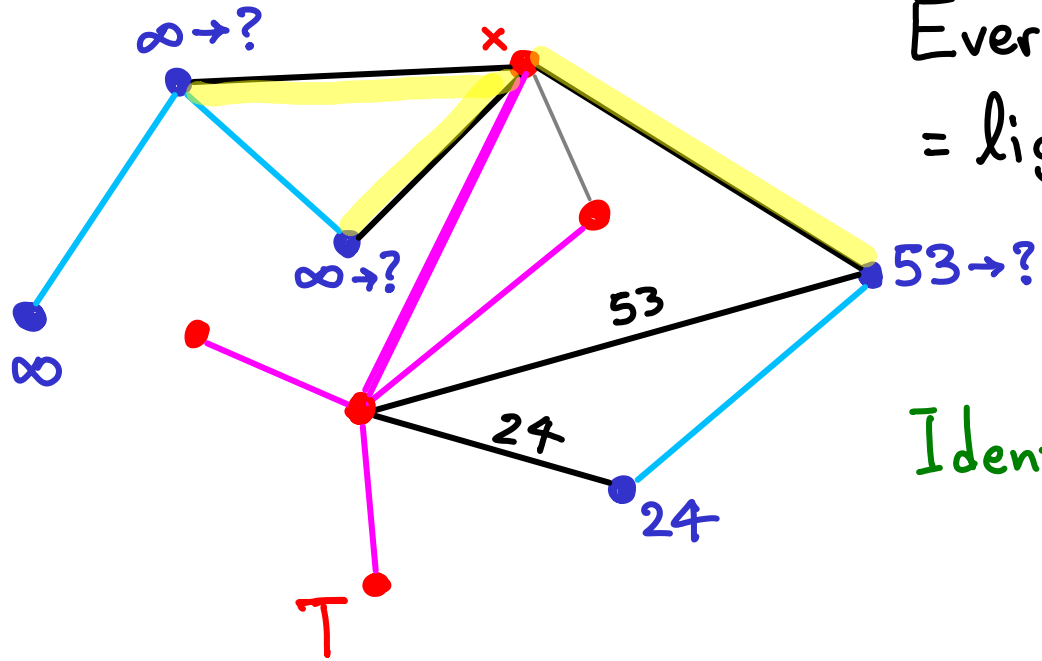
Identify lightest edge crossing cut:

- 1) identify min-score vertex,  $x$
- 2) identify lightest edge from  $x$  to  $T$

Brute force:  $O(V)$  per MST edge



# PRIM'S ALGORITHM for MST



Every vertex not in  $T$  has a score =  
= lightest edge weight connecting it to  $T$

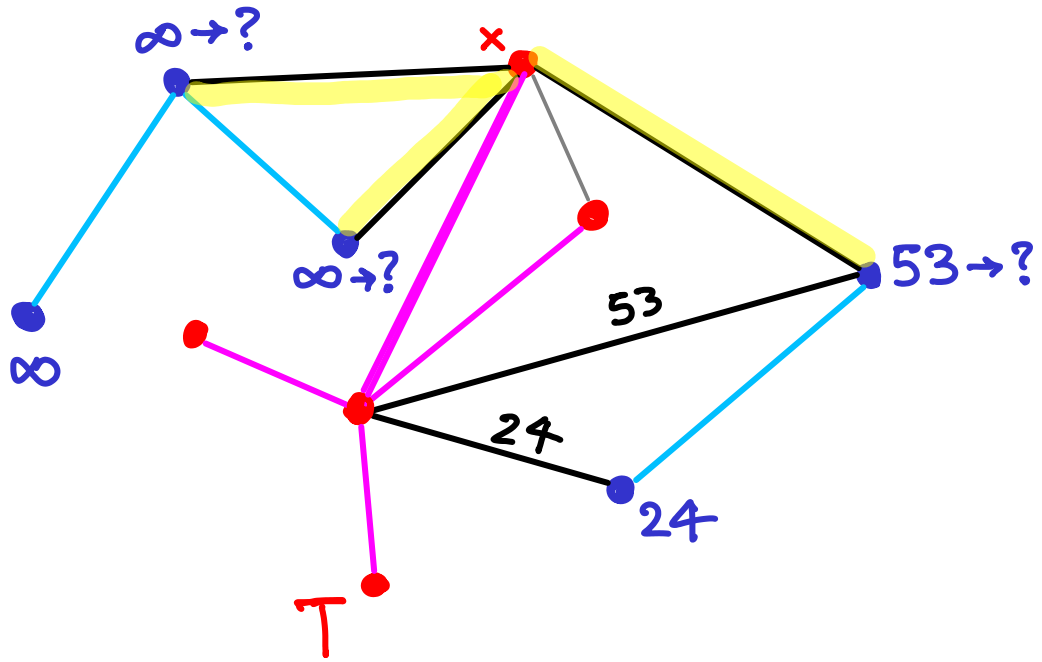
Identify lightest edge crossing cut:

- 1) identify min-score vertex,  $x$
- 2) identify lightest edge from  $x$  to  $T$

Brute force:  $O(V)$  per MST edge

... but we must still update scores after adding  $x$  to  $T$

# PRIM'S ALGORITHM for MST



Update scores when  $x$  joins  $T$ :

For each neighbor  $v_i$  of  $x$

if  $v_i$  not in  $T$

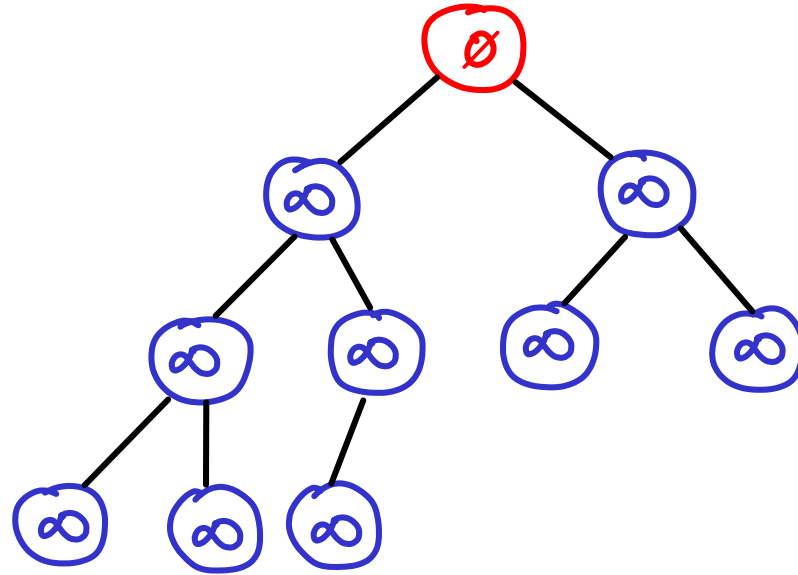
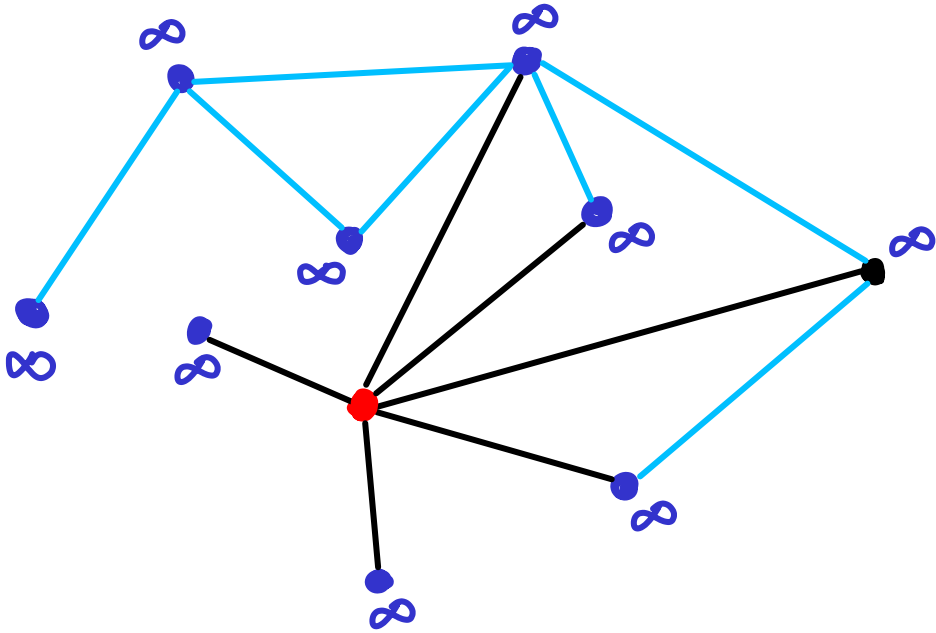
$c = \text{score}(v_i)$

$\text{score}(v_i) \leftarrow \min \{c, \underbrace{w(x, v_i)}_{\text{new option}}\}$

new option

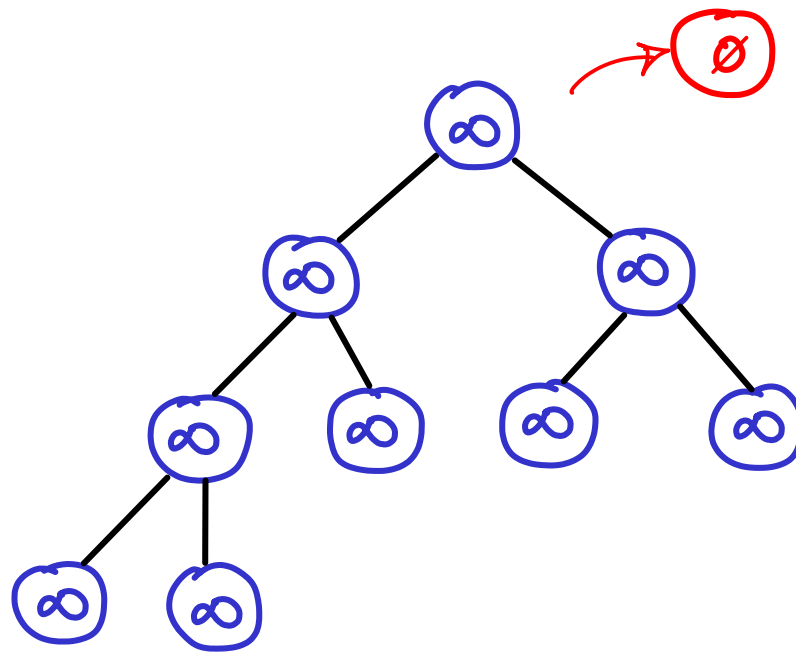
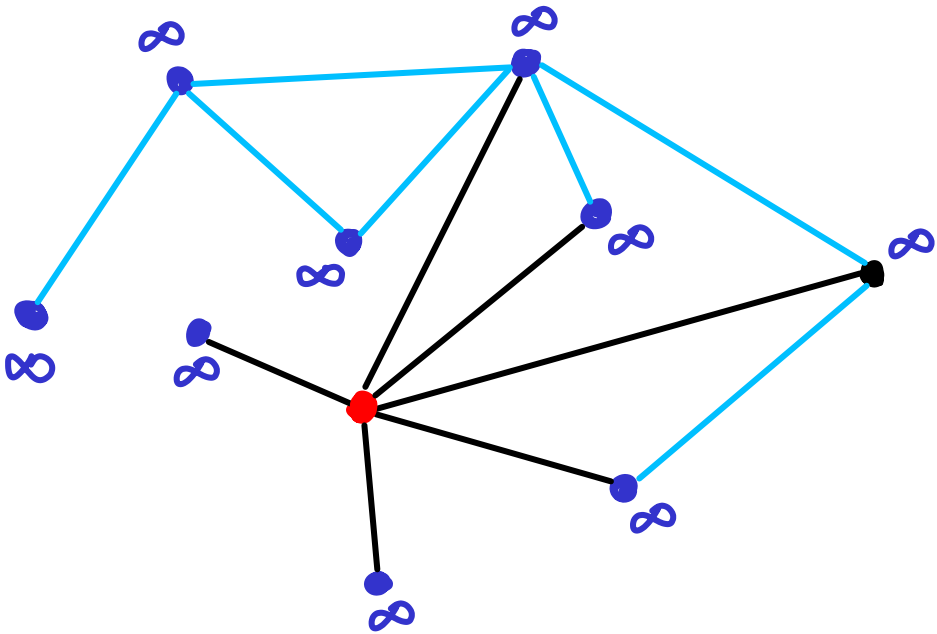


# PRIM'S ALGORITHM for MST



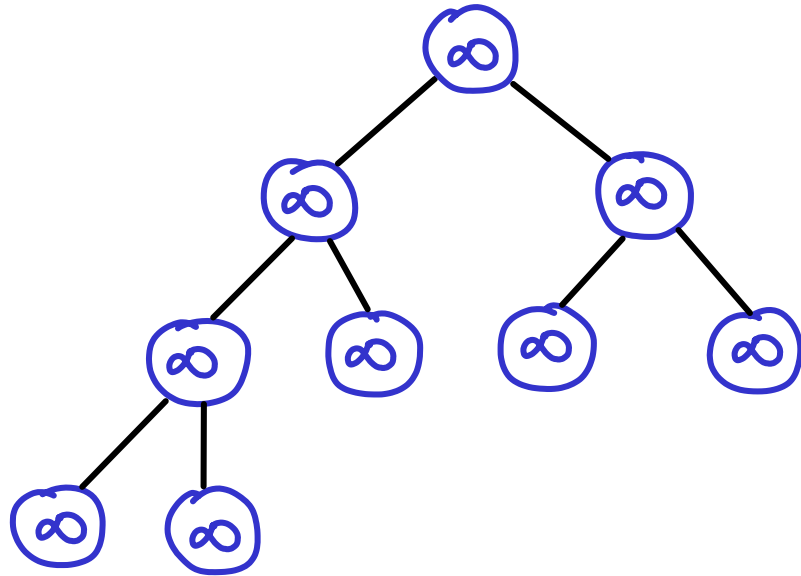
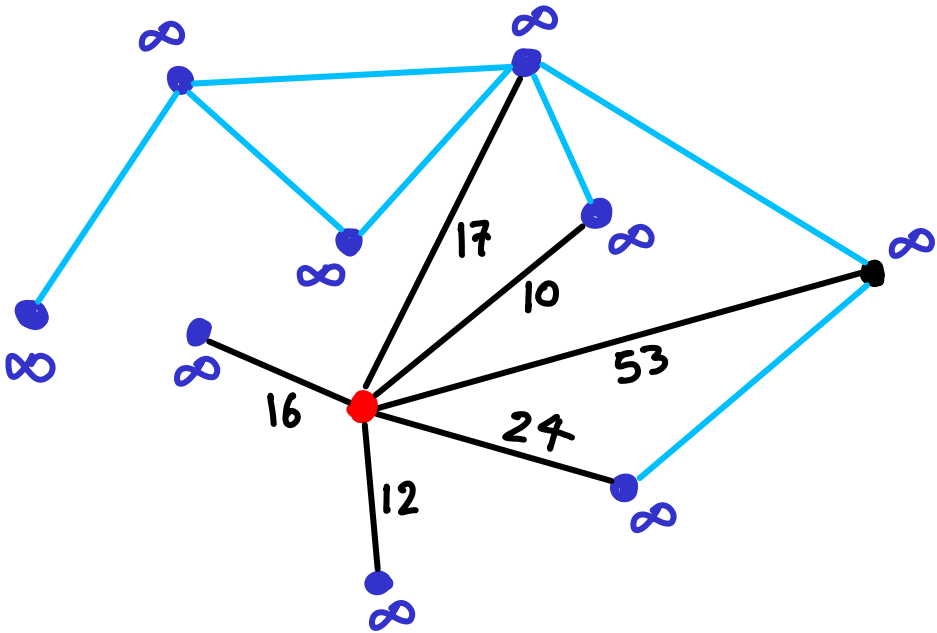
priority queue

# PRIM'S ALGORITHM for MST



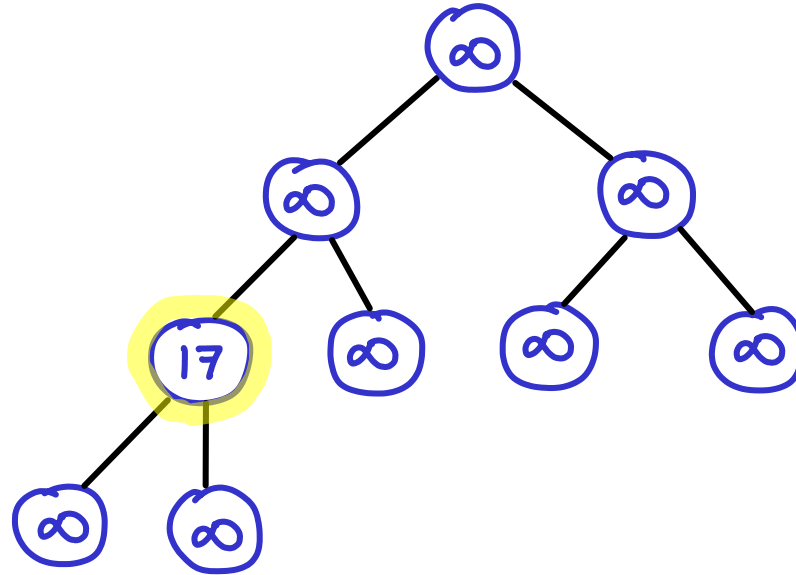
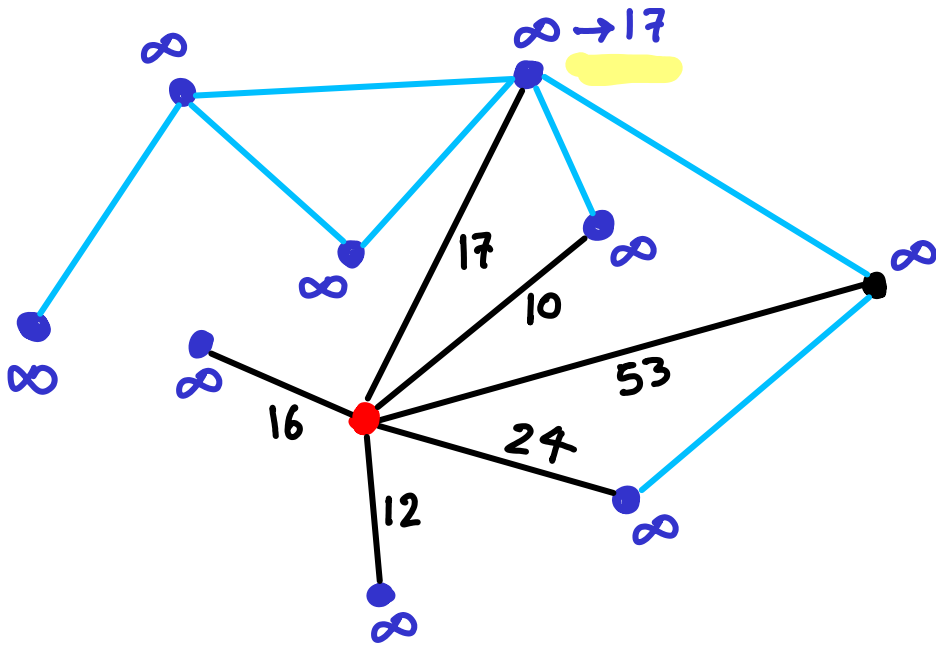
priority queue

# PRIM'S ALGORITHM for MST



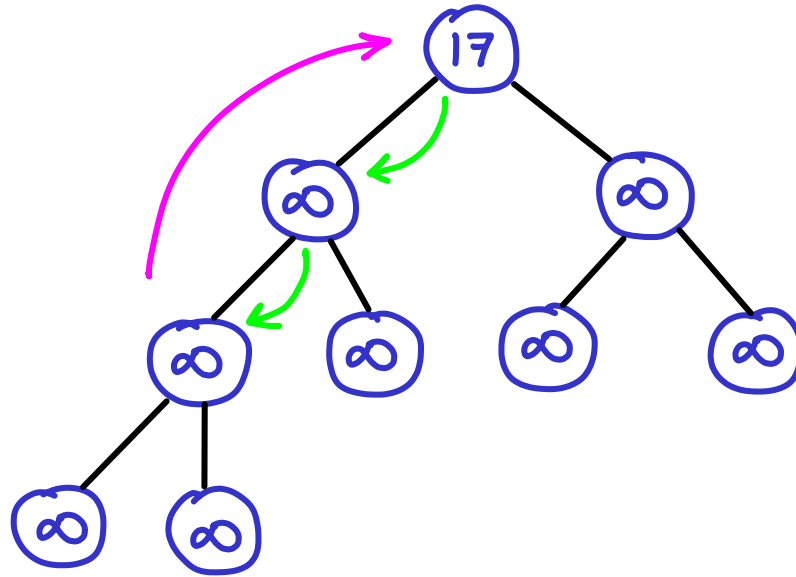
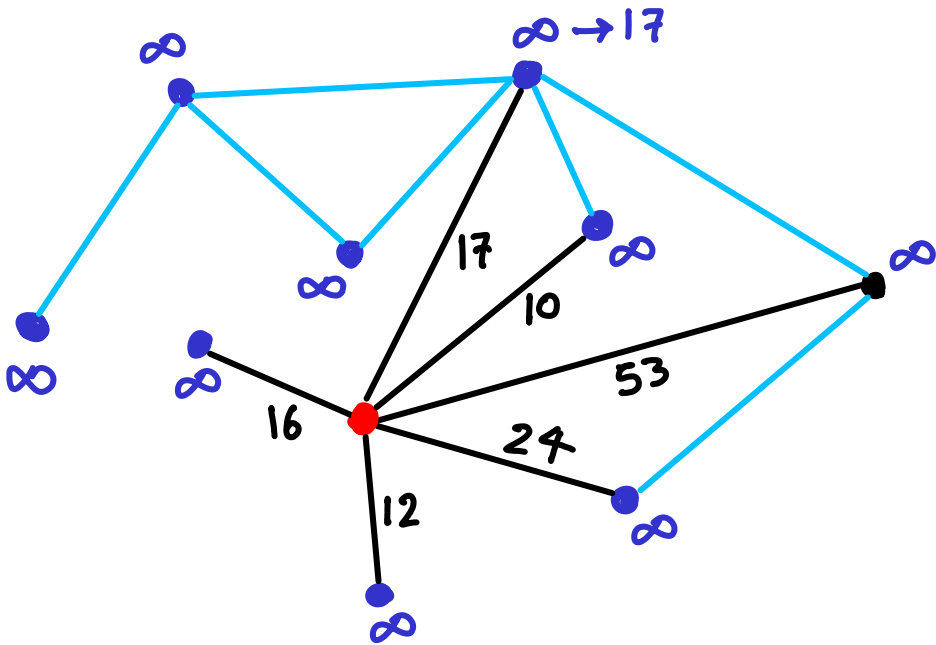
priority queue

# PRIM'S ALGORITHM for MST



priority queue

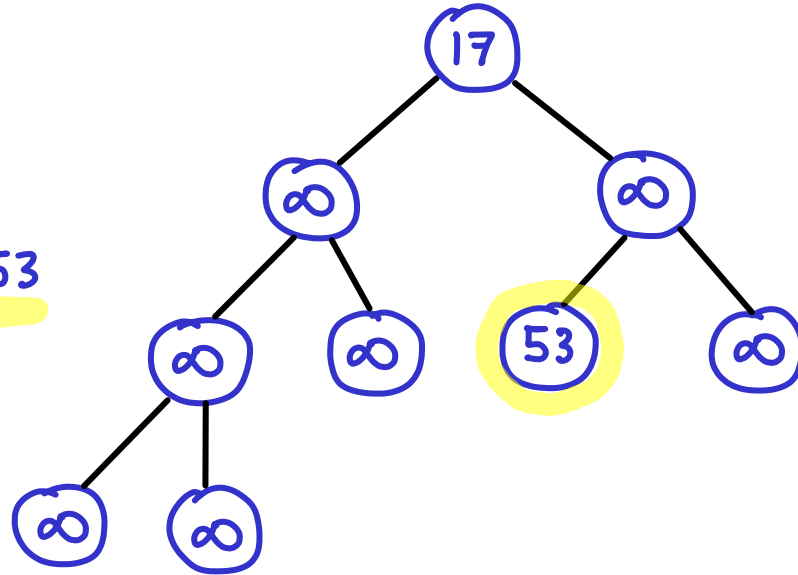
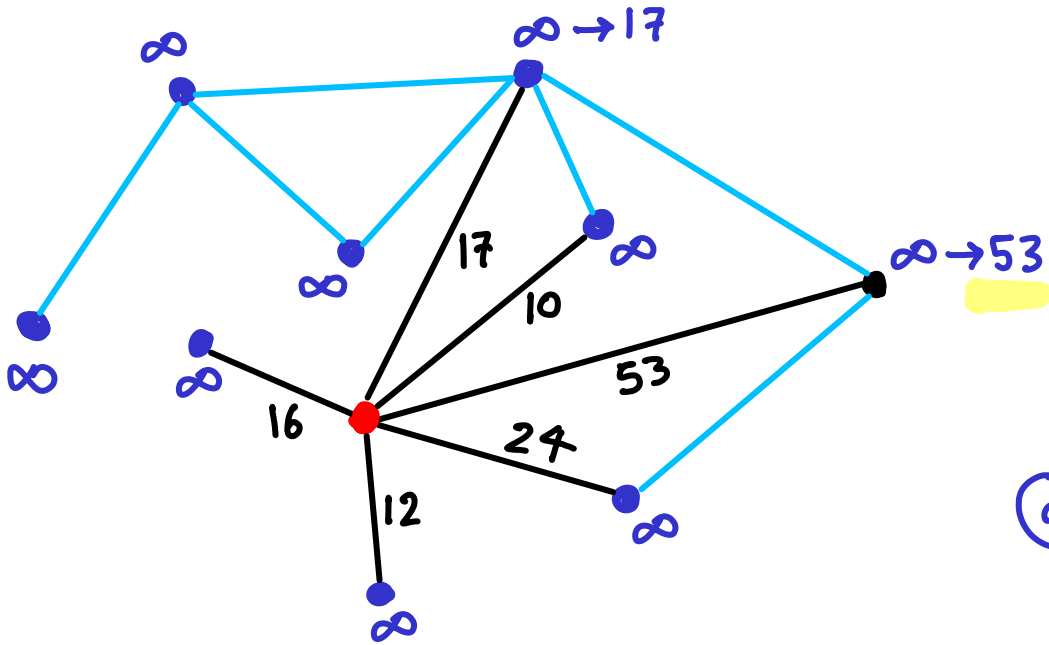
# PRIM'S ALGORITHM for MST



priority queue

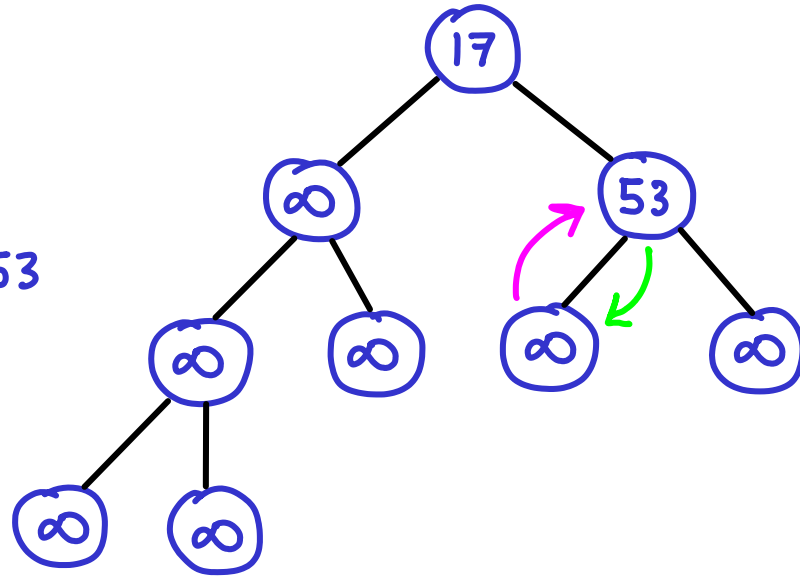
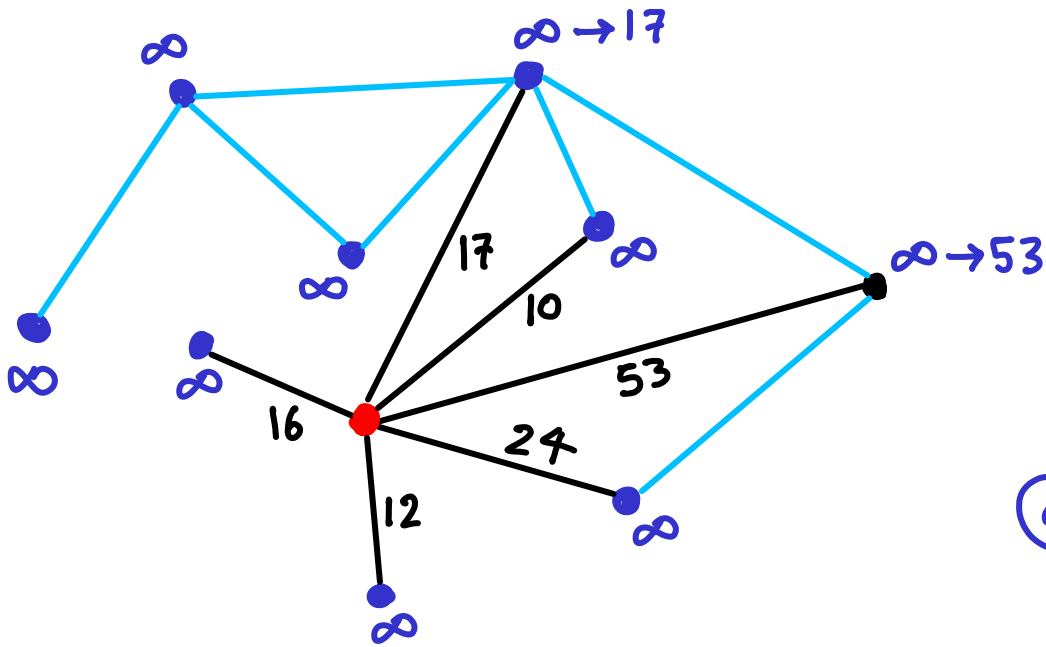


# PRIM'S ALGORITHM for MST



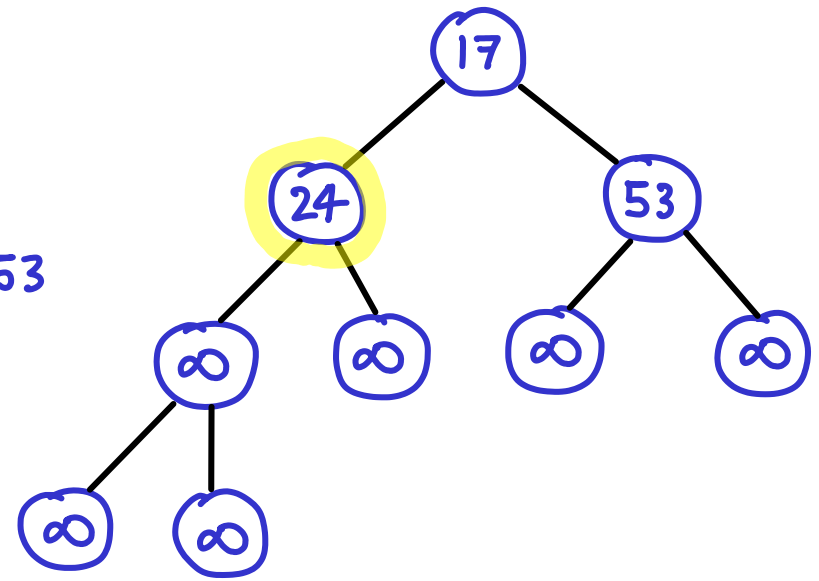
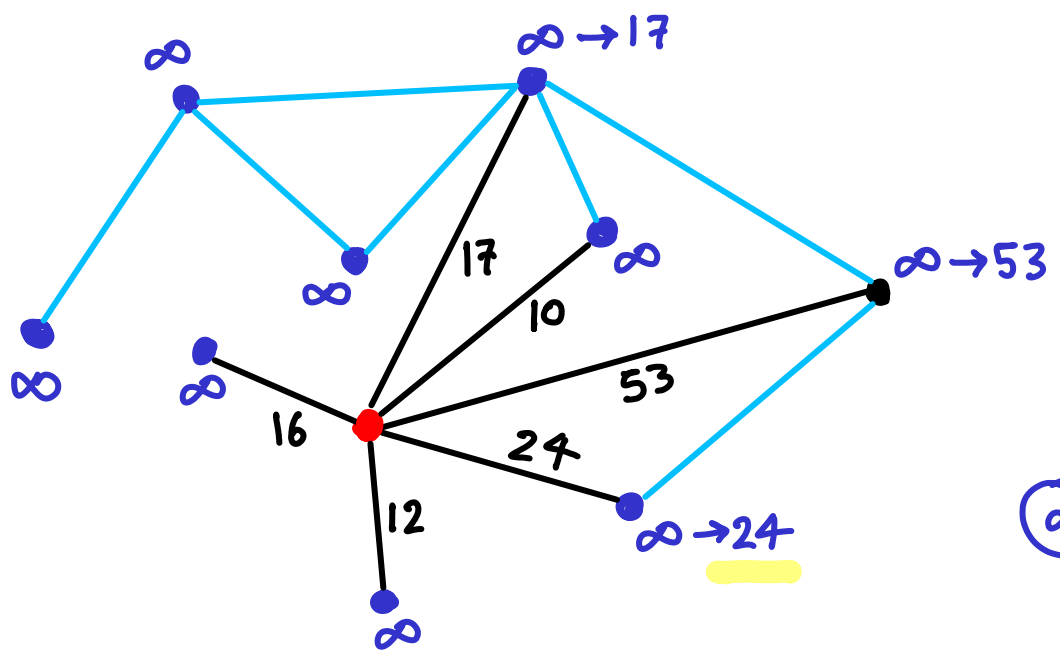
priority queue

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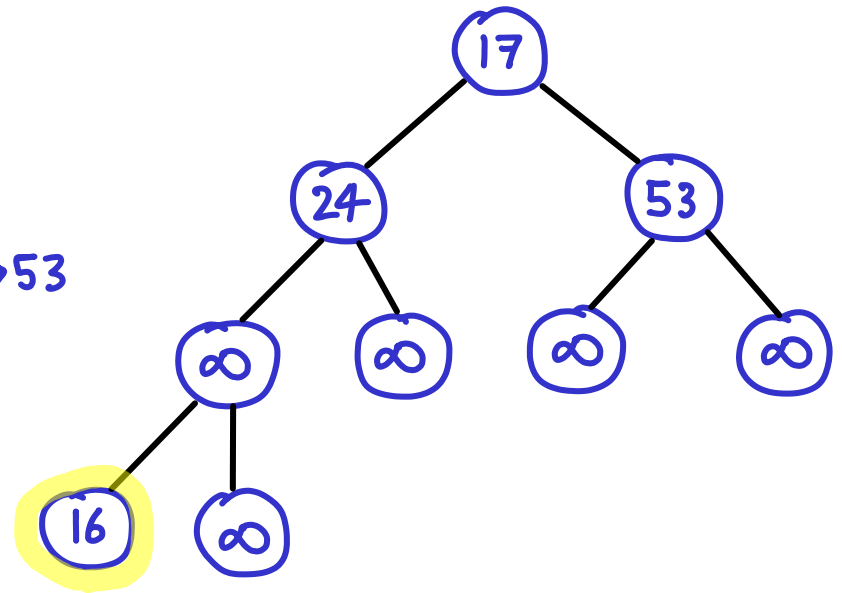
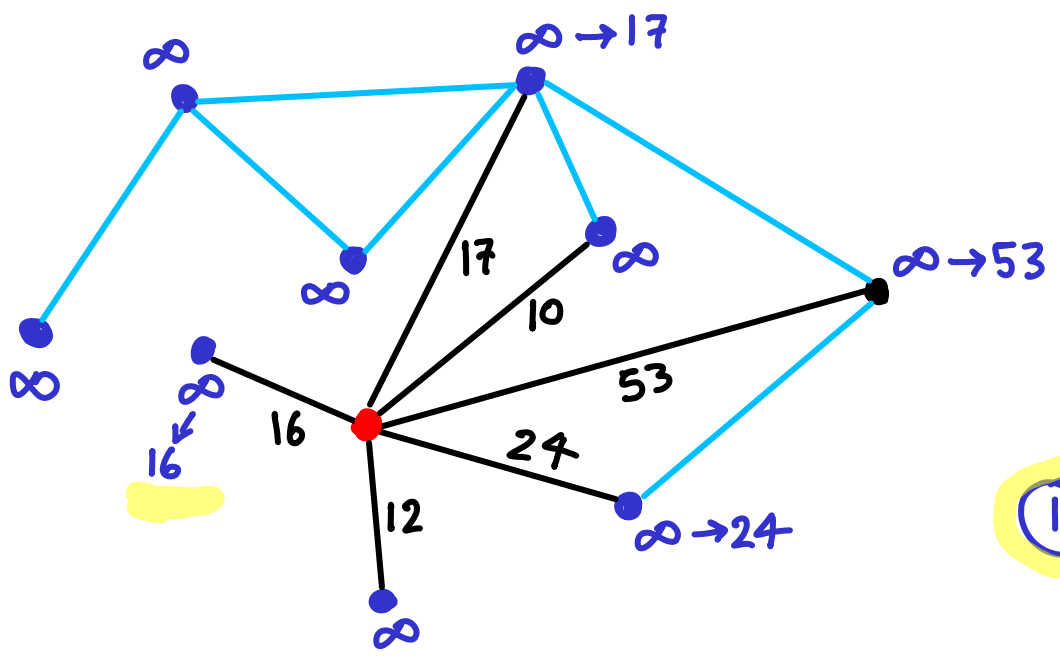
priority queue

# PRIM'S ALGORITHM for MST



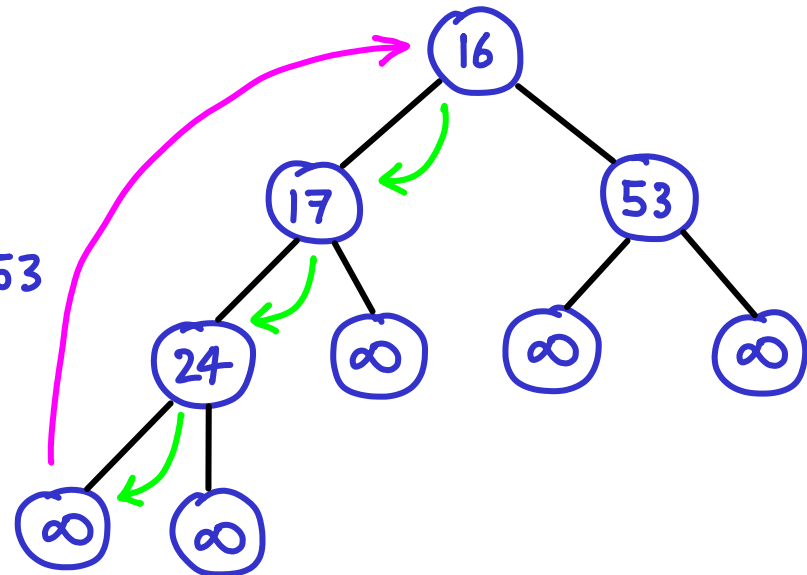
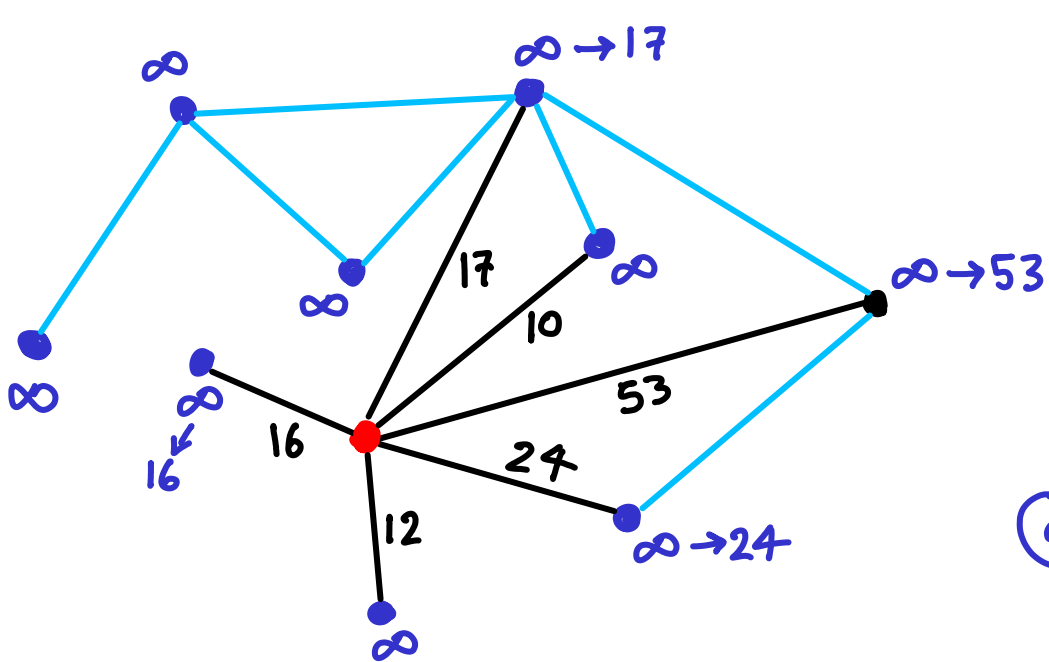
priority queue

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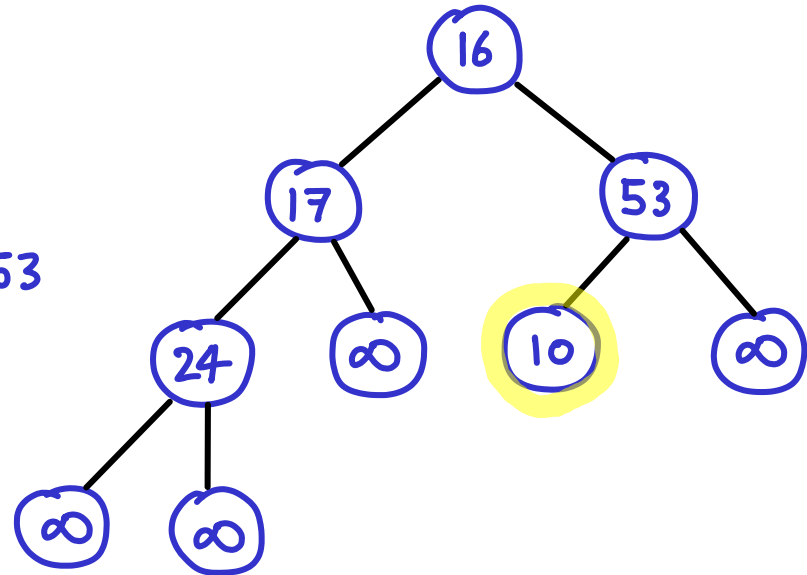
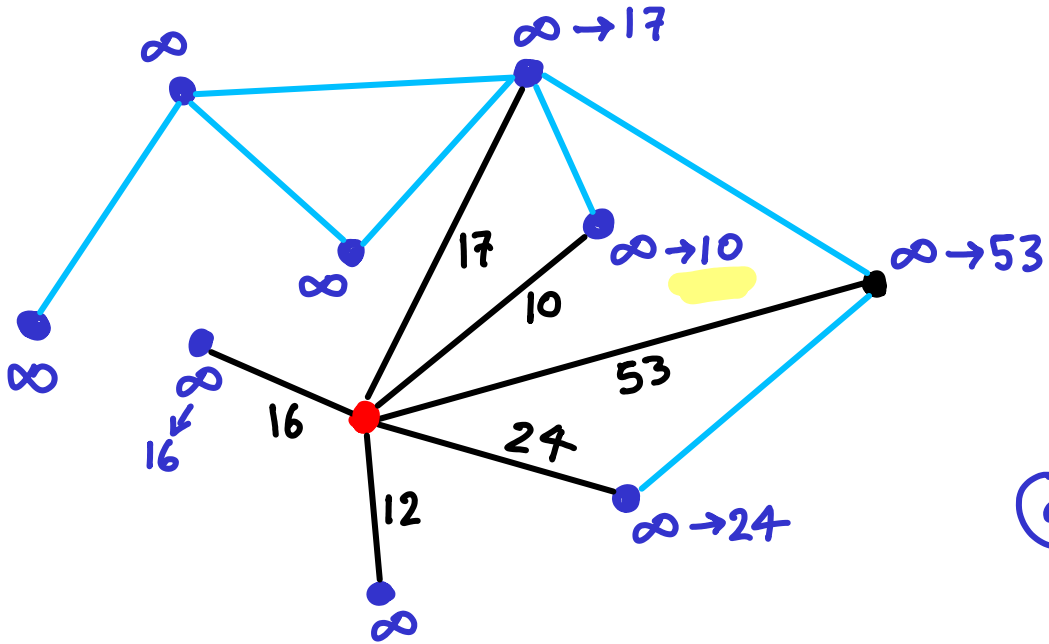
priority queue

# PRIM'S ALGORITHM for MST



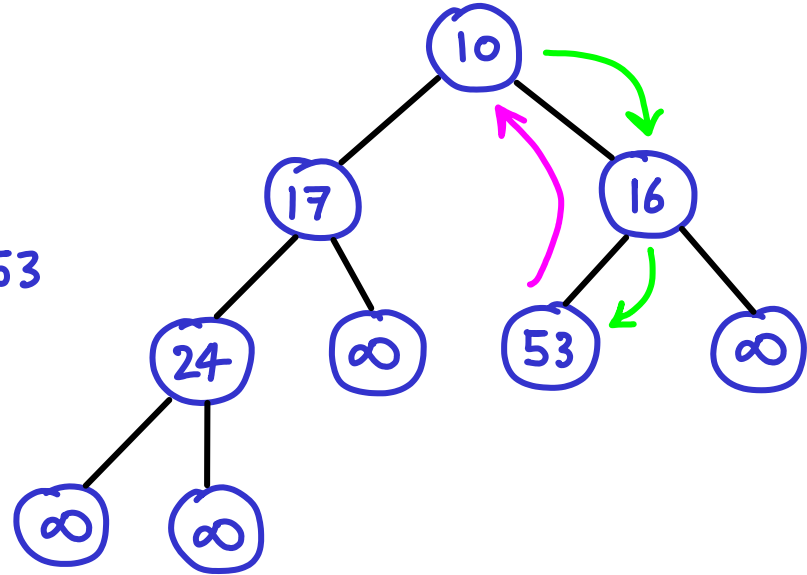
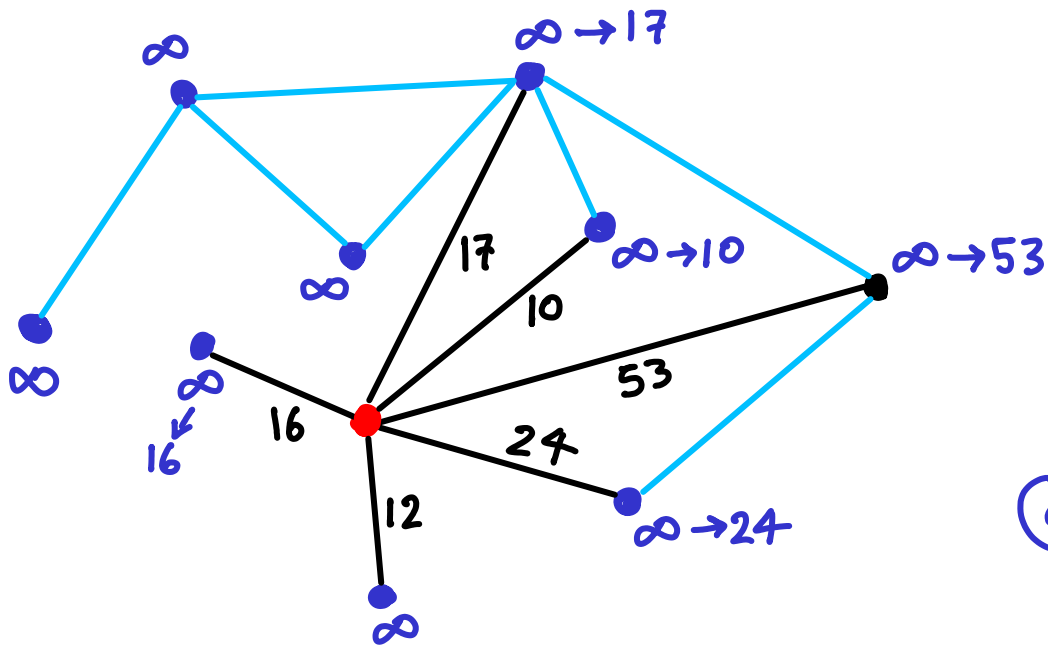
priority queue

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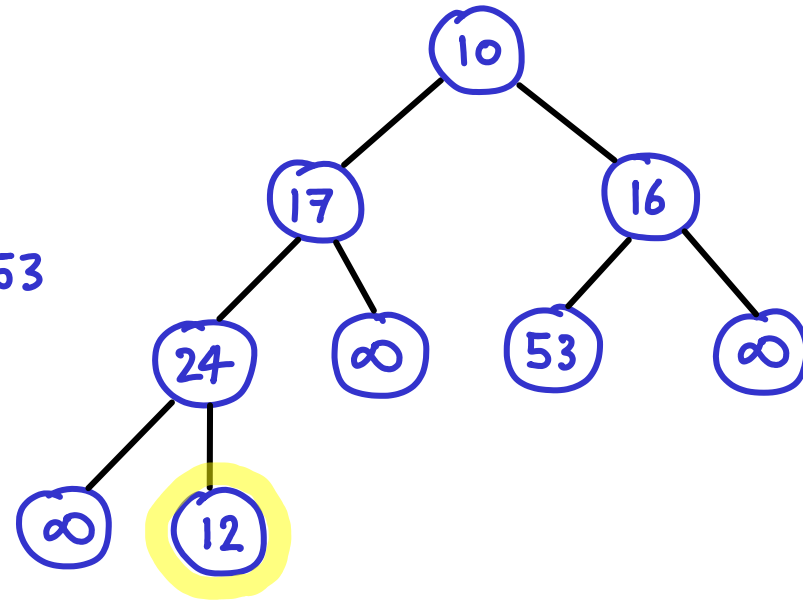
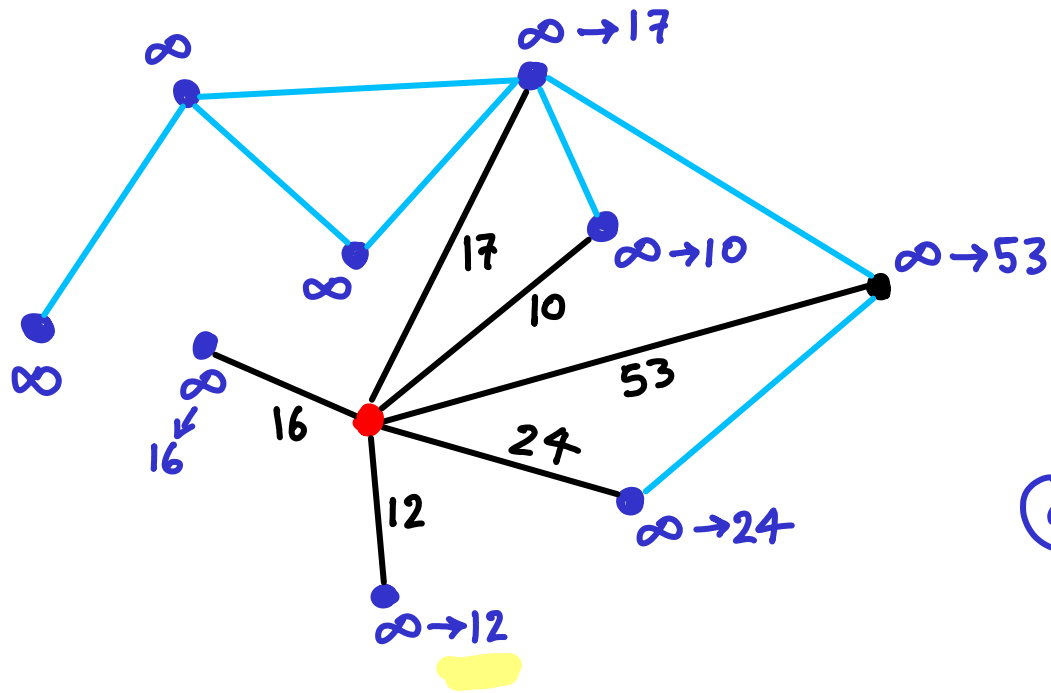
priority queue

# PRIM'S ALGORITHM for MST



priority queue

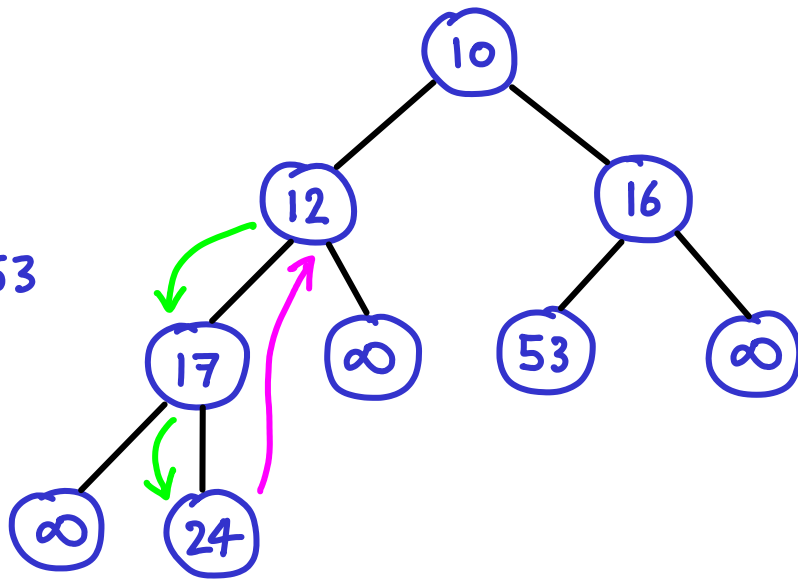
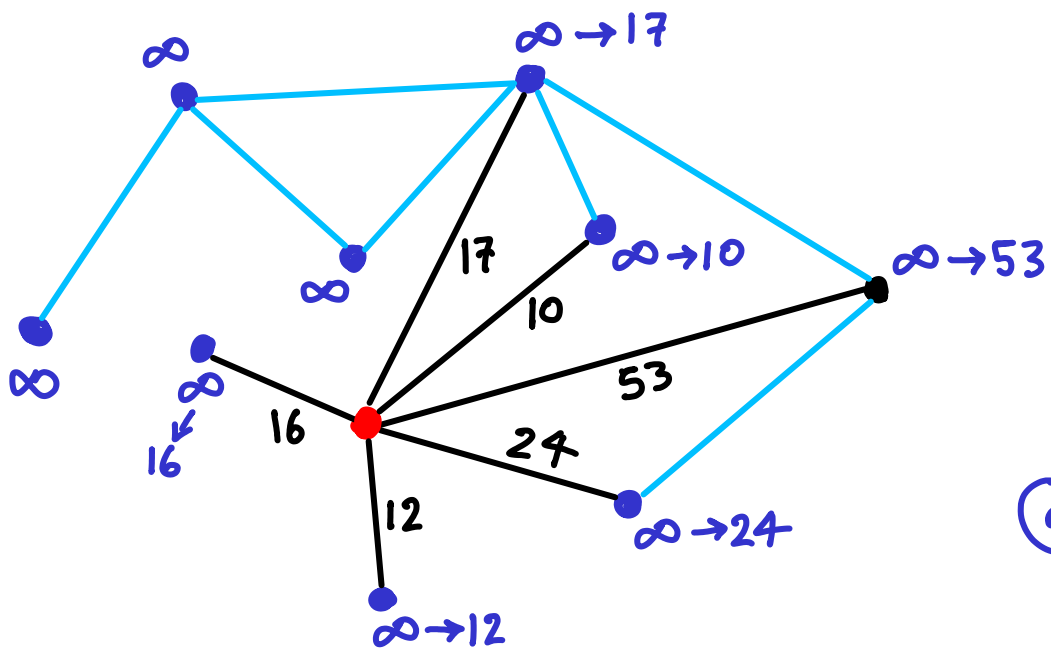
# PRIM'S ALGORITHM for MST



priority queue

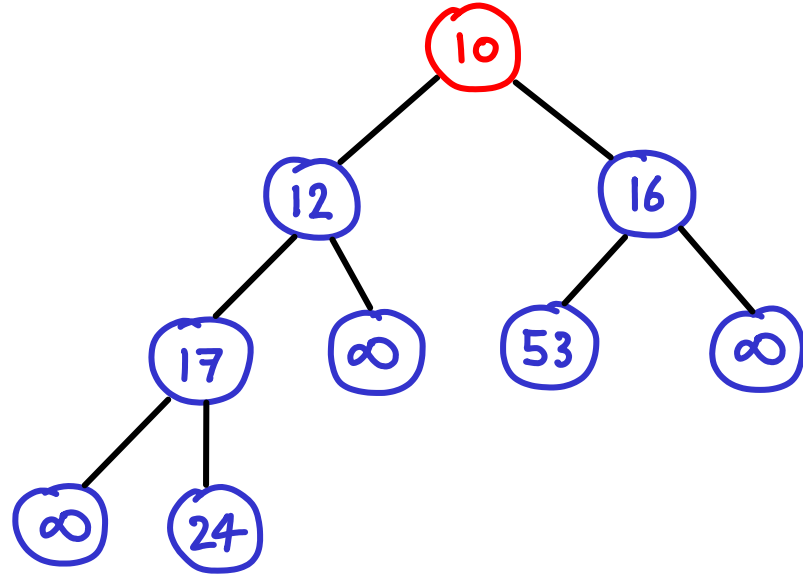
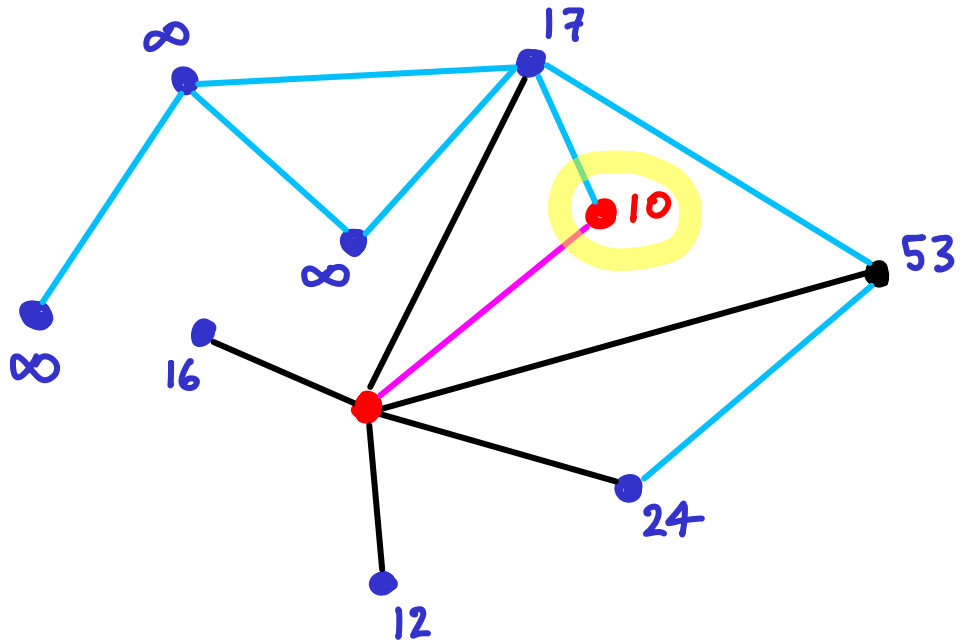


# PRIM'S ALGORITHM for MST



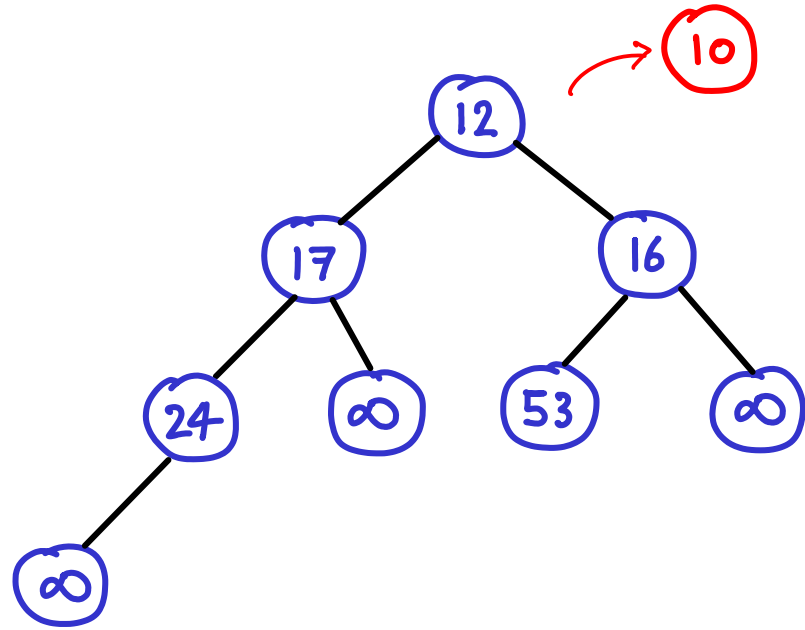
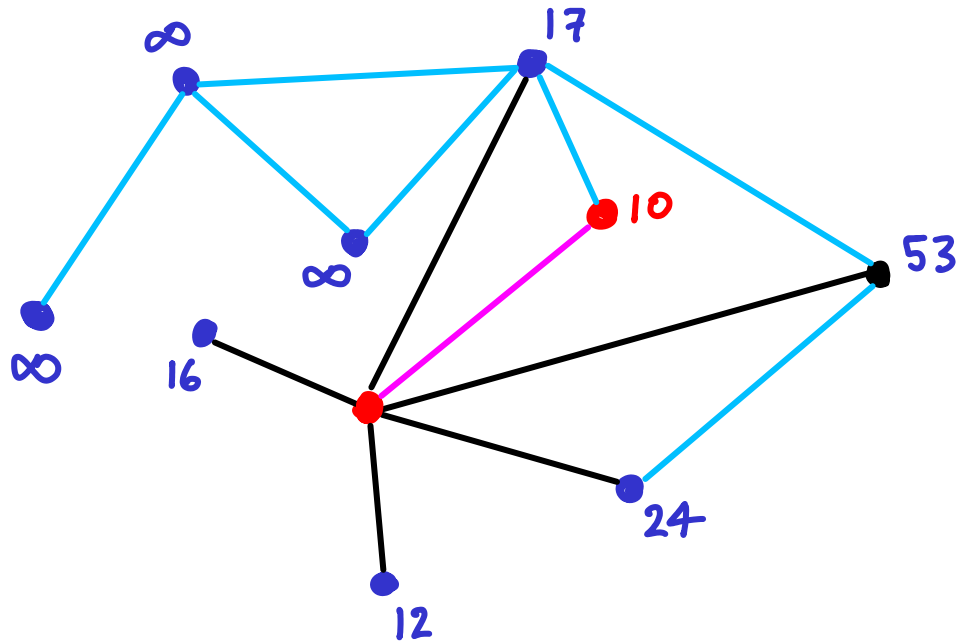
priority queue

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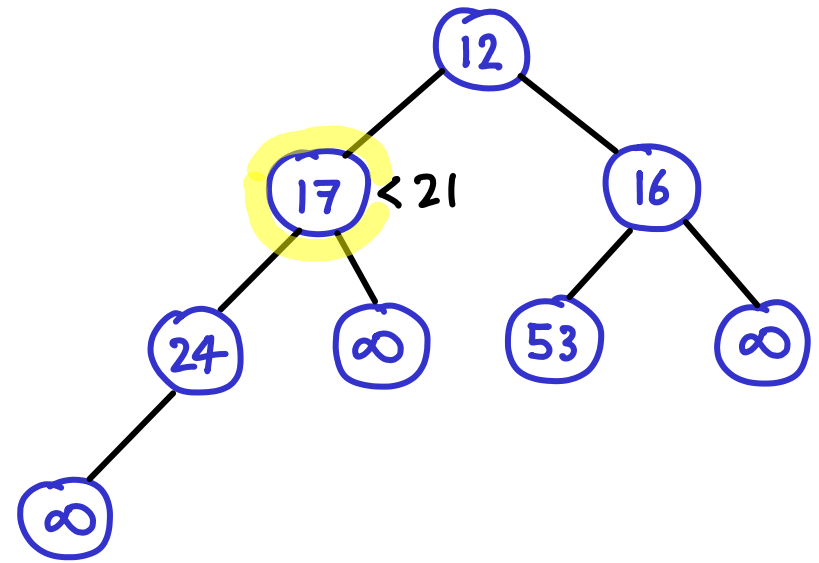
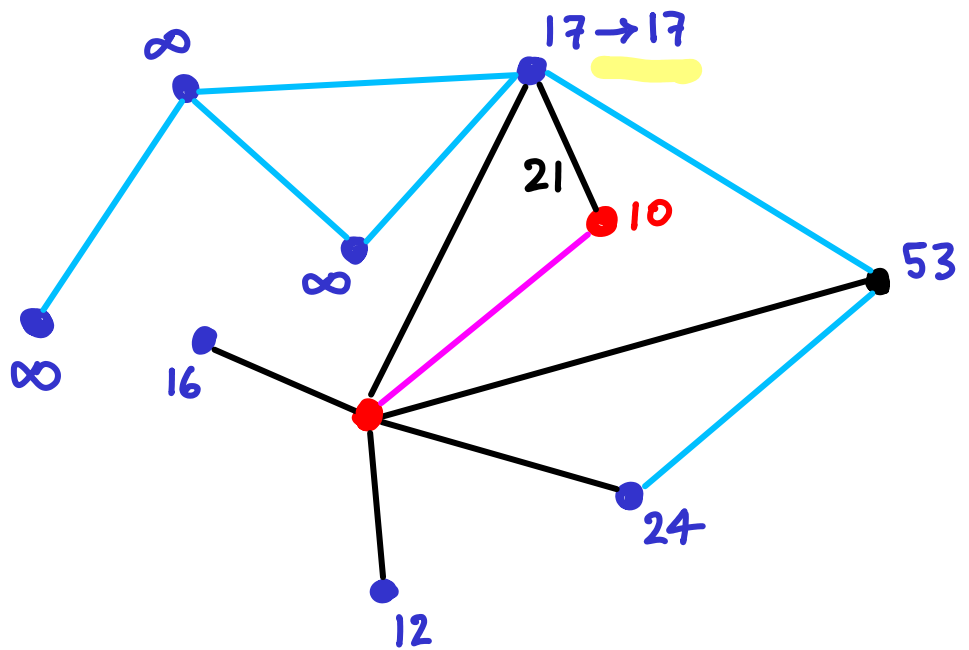
priority queue

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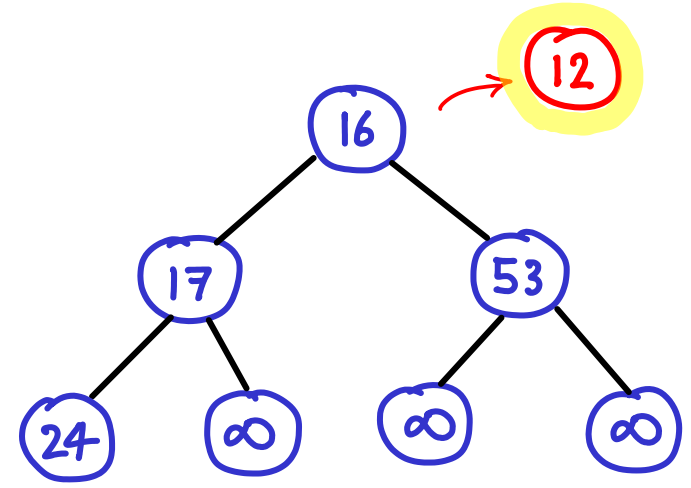
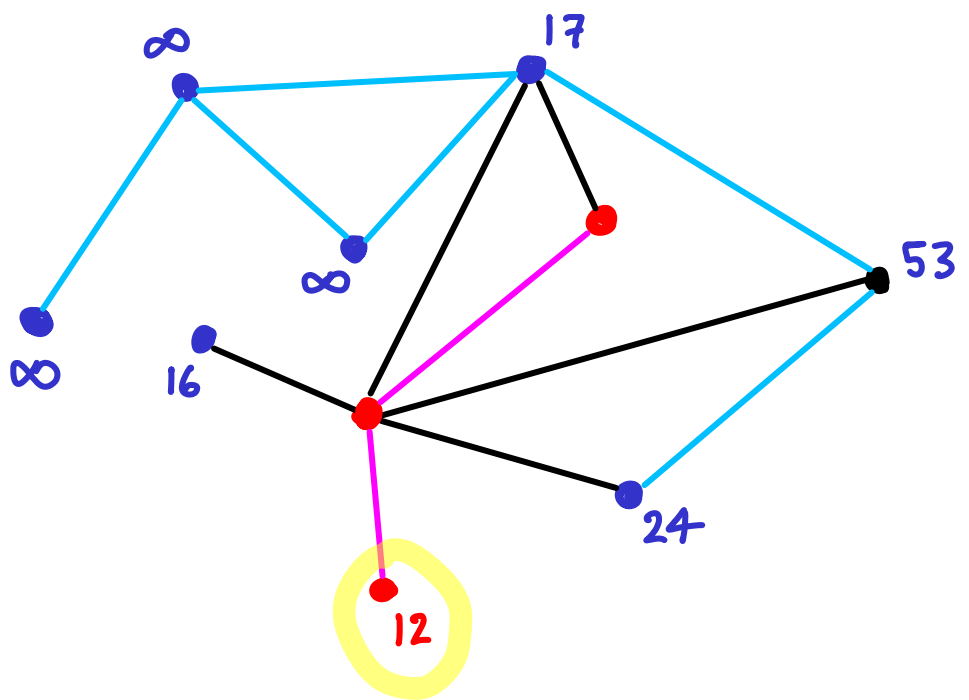
priority queue

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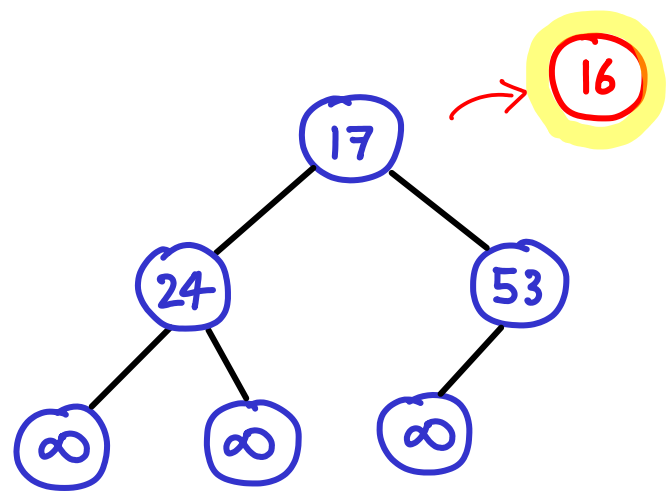
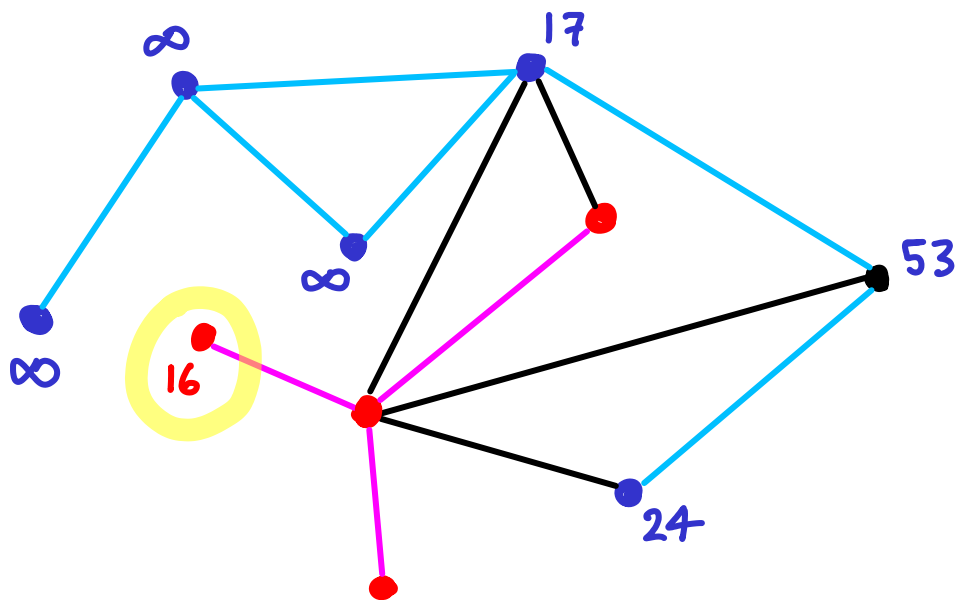
priority queue

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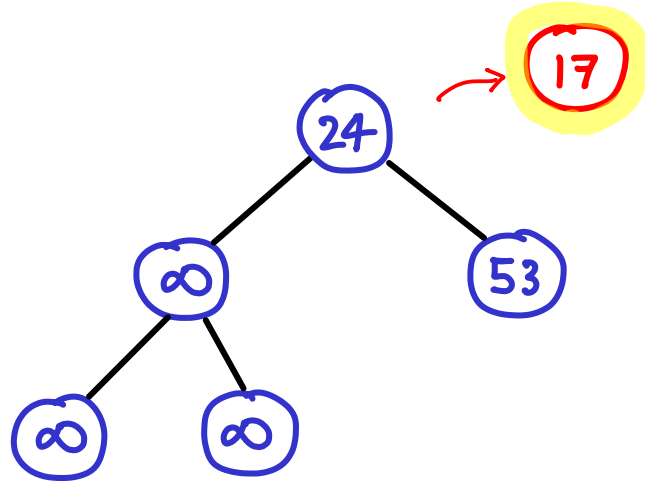
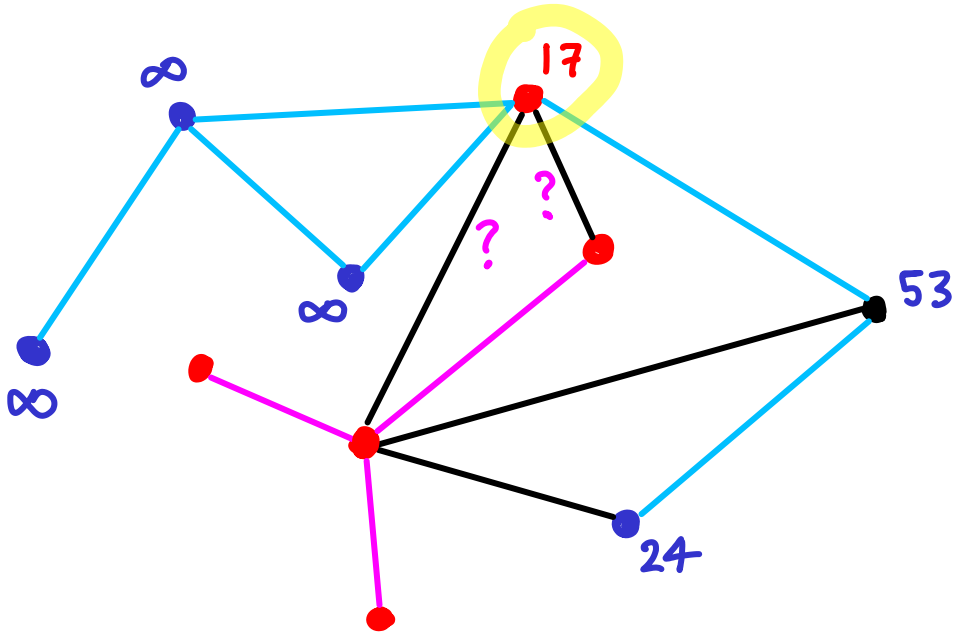
priority queue

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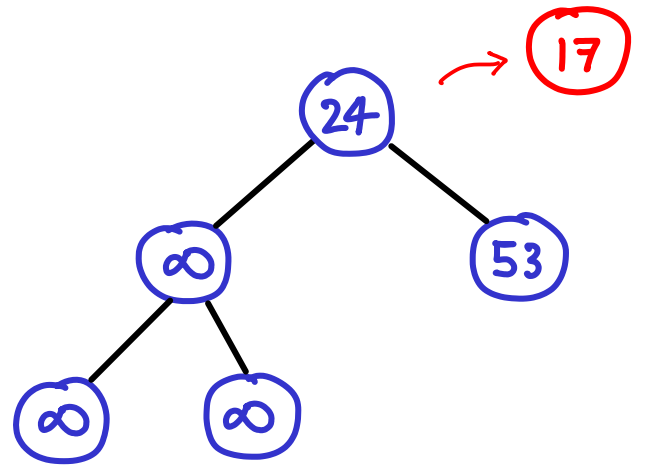
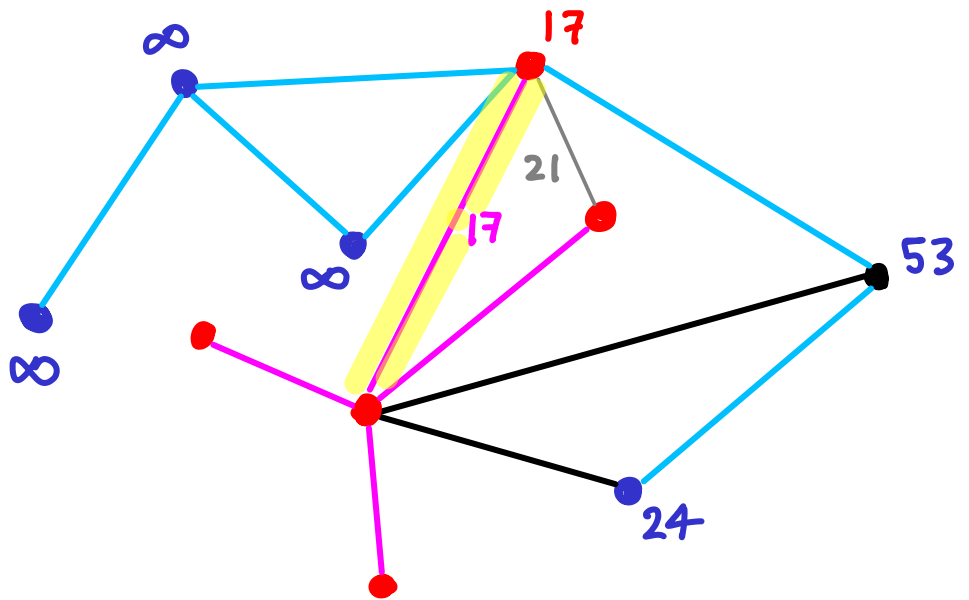
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# PRIM'S ALGORITHM for MST



priority  
queue

# PRIM'S ALGORITHM for MST

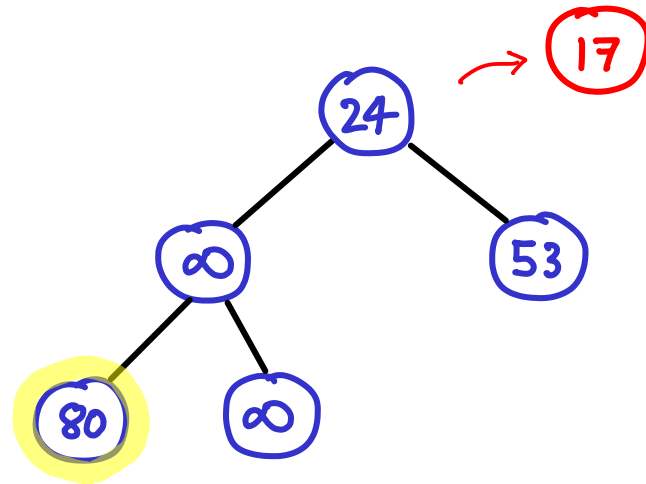
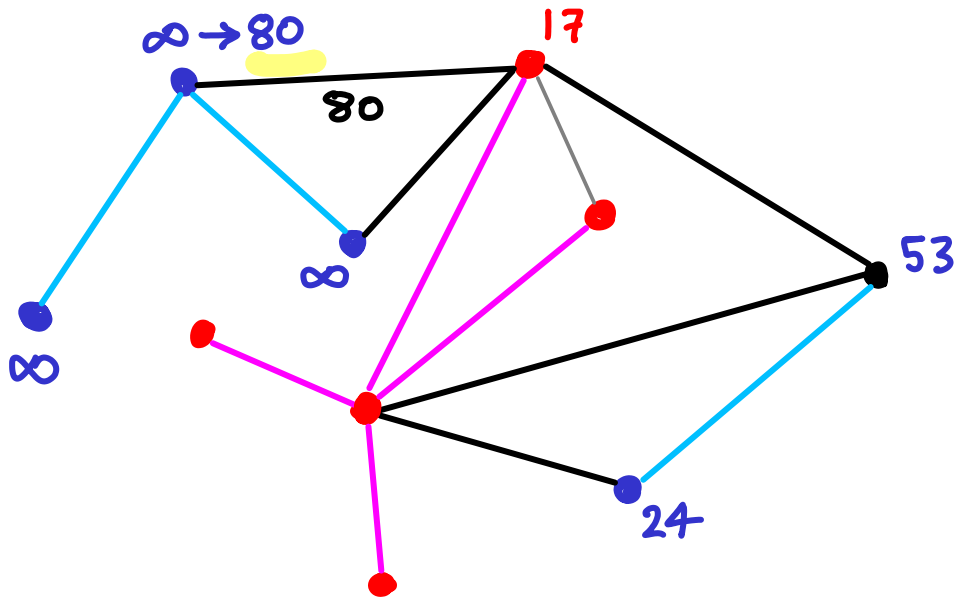


priority queue



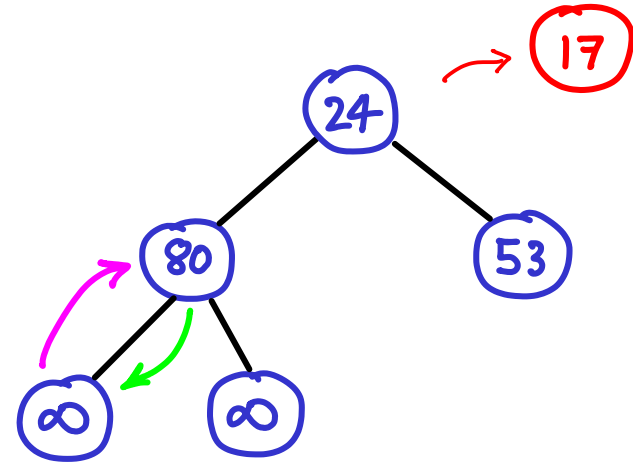
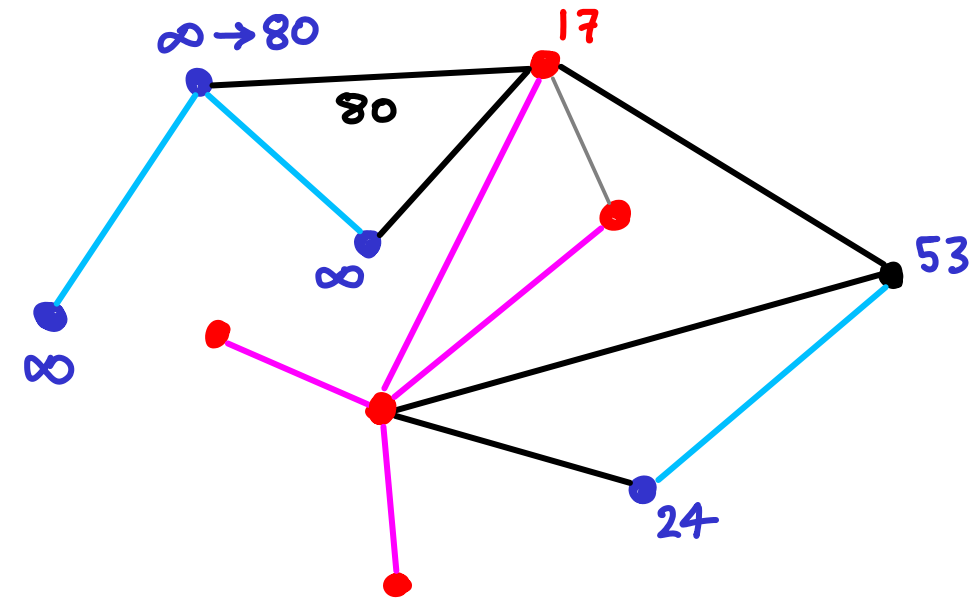


# PRIM'S ALGORITHM for MST



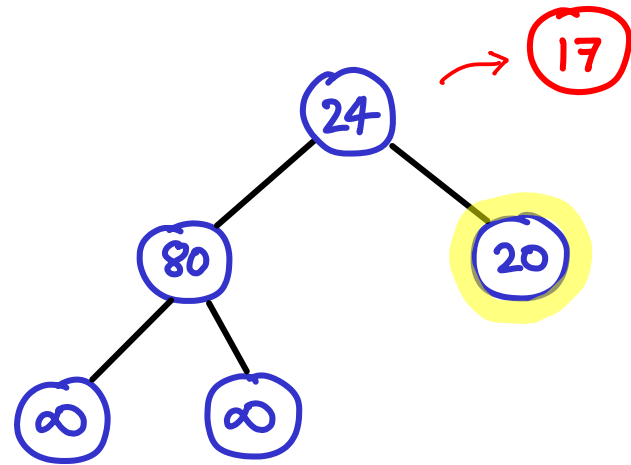
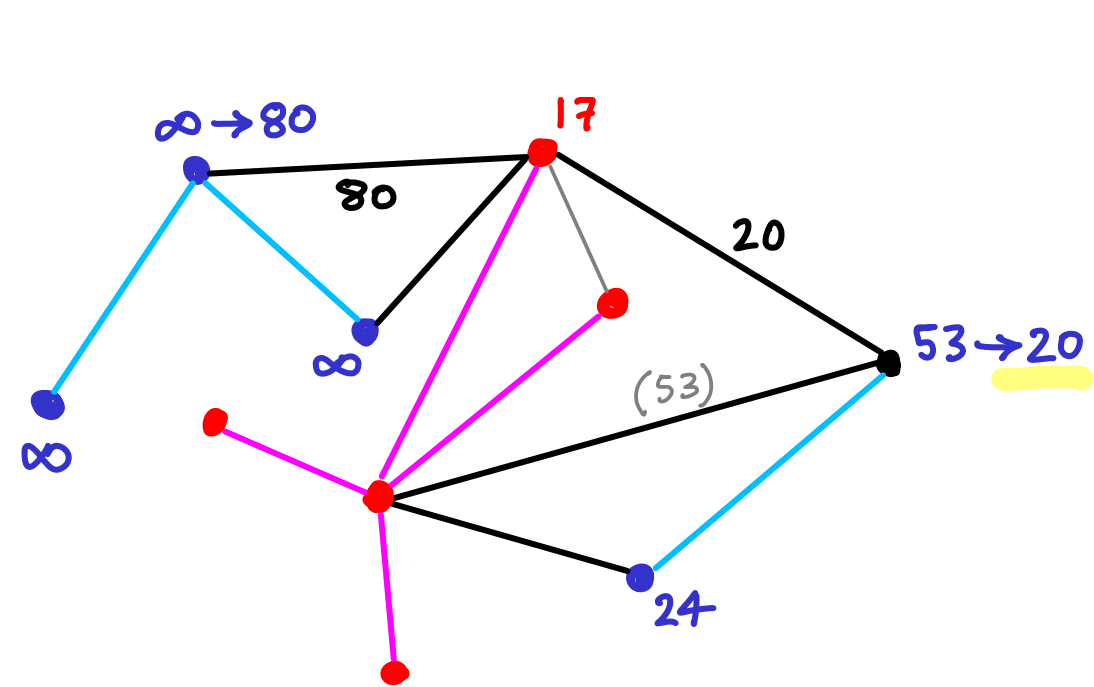
priority queue

# PRIM'S ALGORITHM for MST



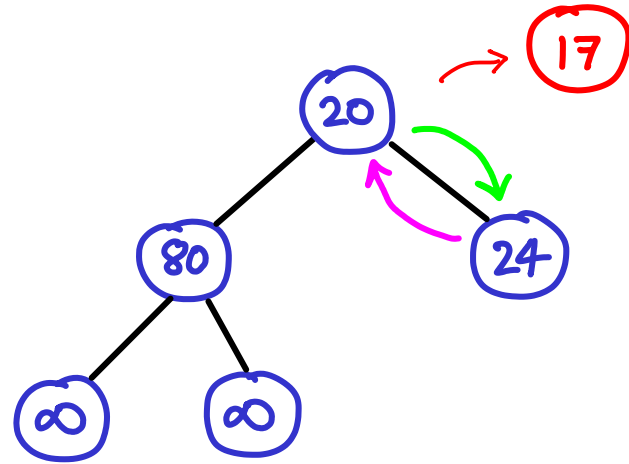
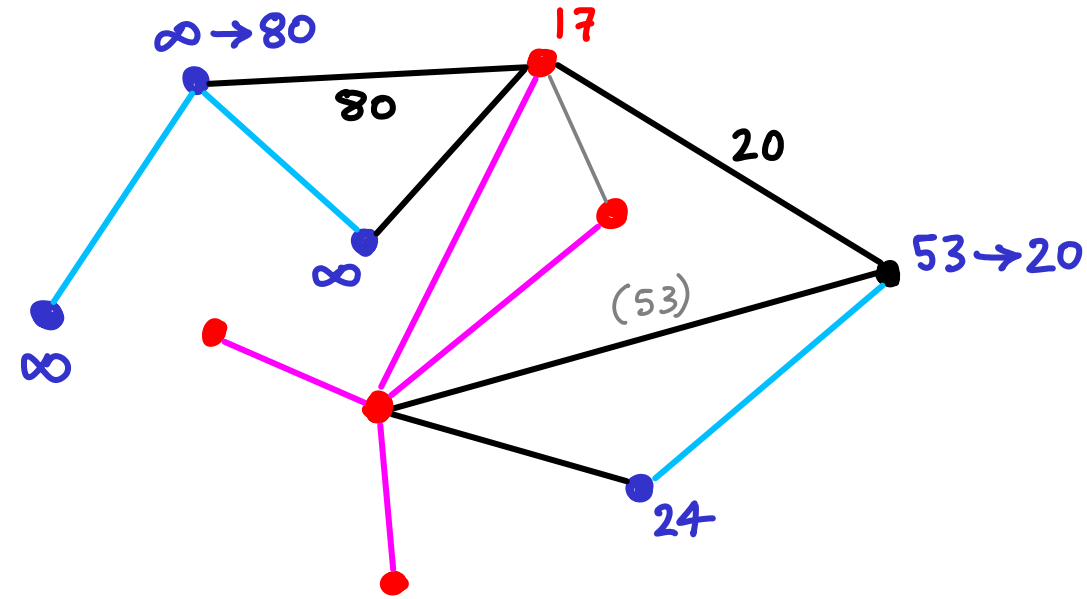
priority  
queue

# PRIM'S ALGORITHM for MST



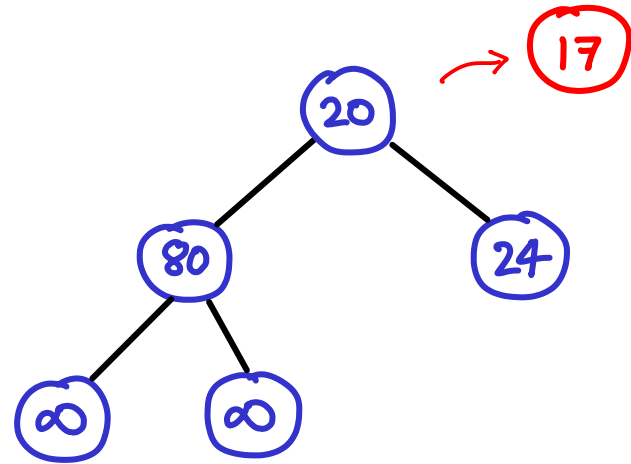
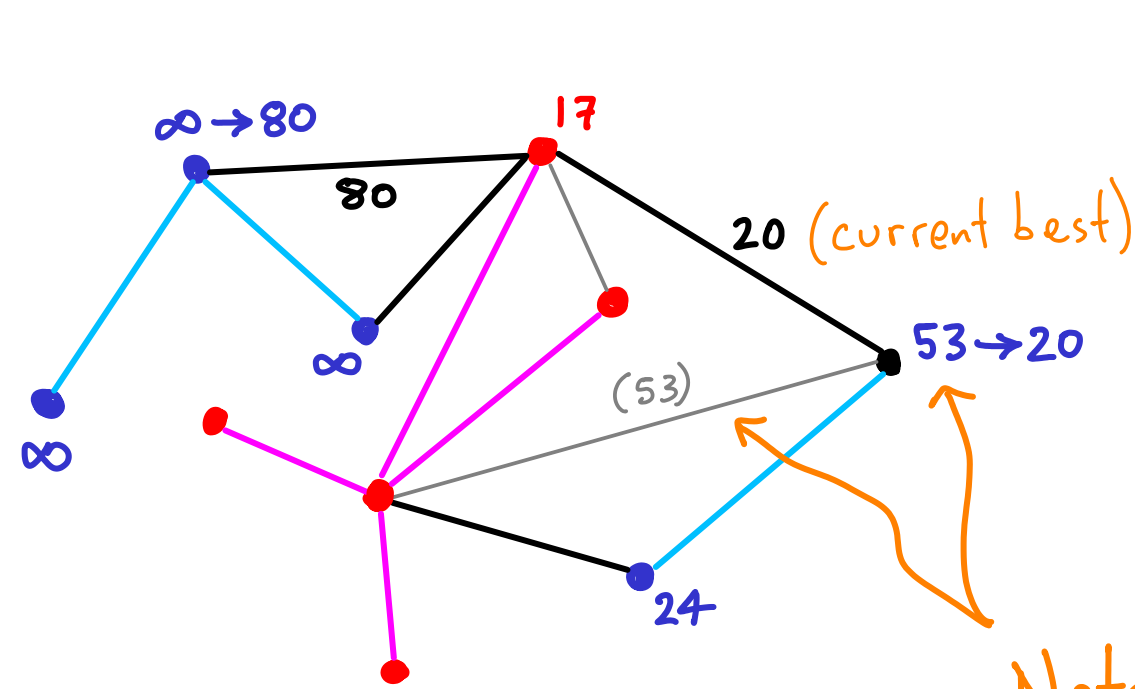
priority queue

# PRIM'S ALGORITHM for MST



priority queue

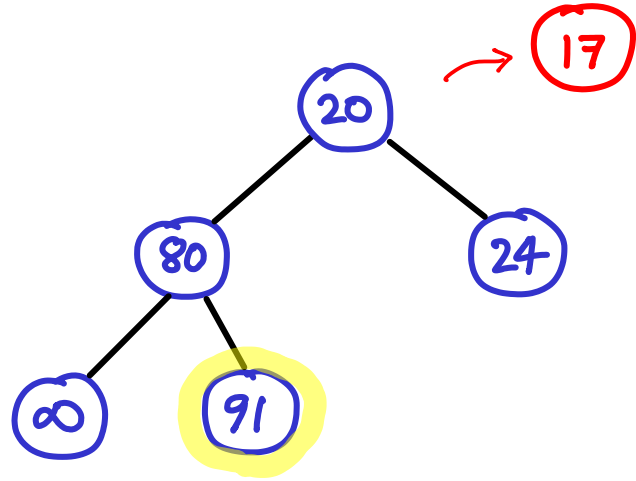
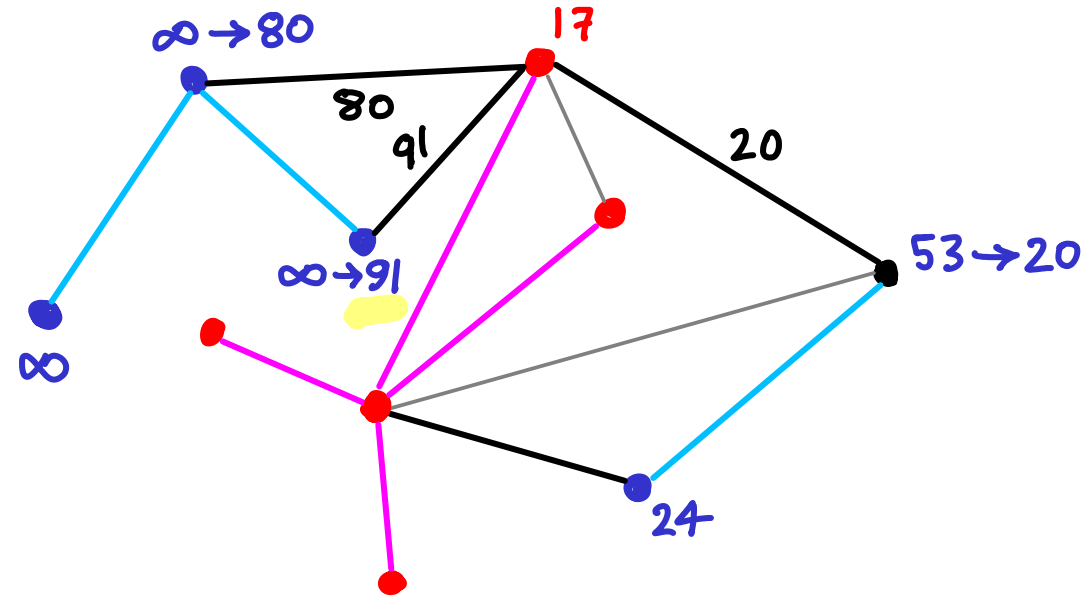
# PRIM'S ALGORITHM for MST



priority queue

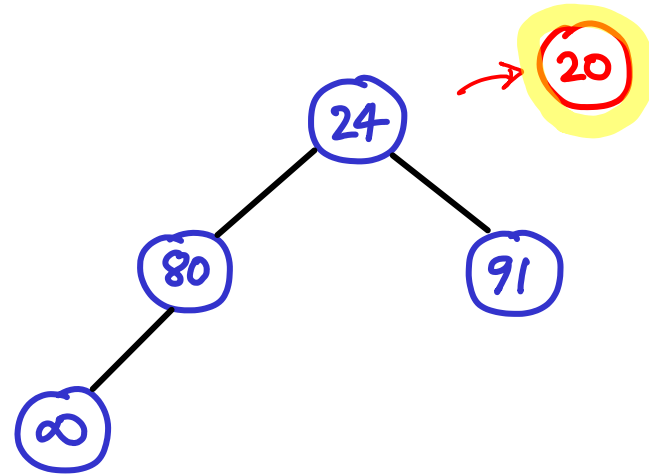
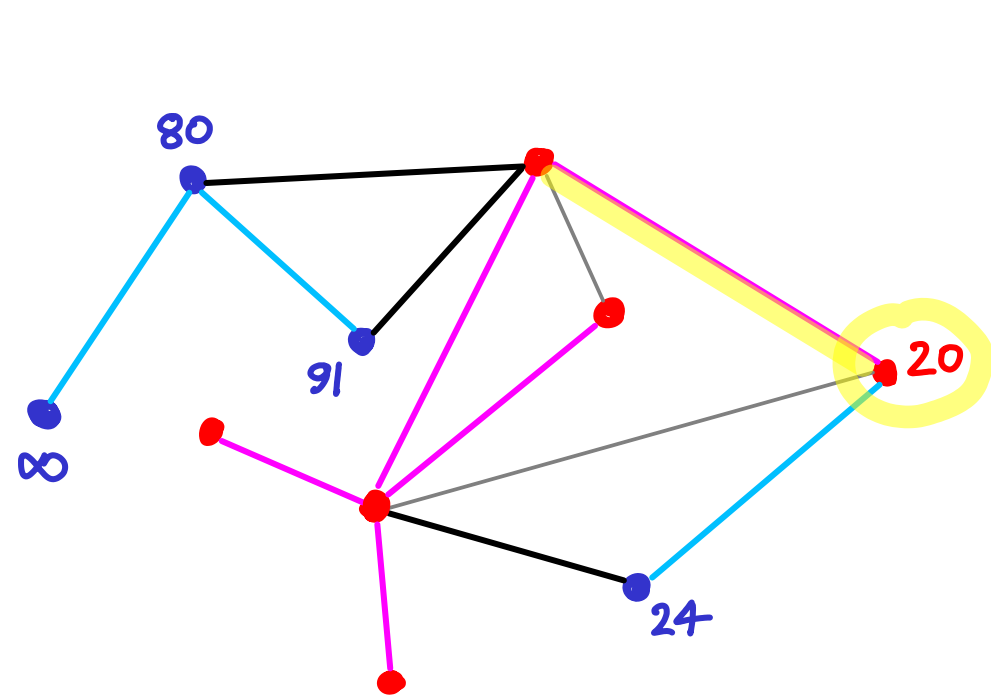
Note: a vertex can keep track of its "best" edge, so when it is added to  $T$ , we don't need to find min.

# PRIM'S ALGORITHM for MST



priority queue

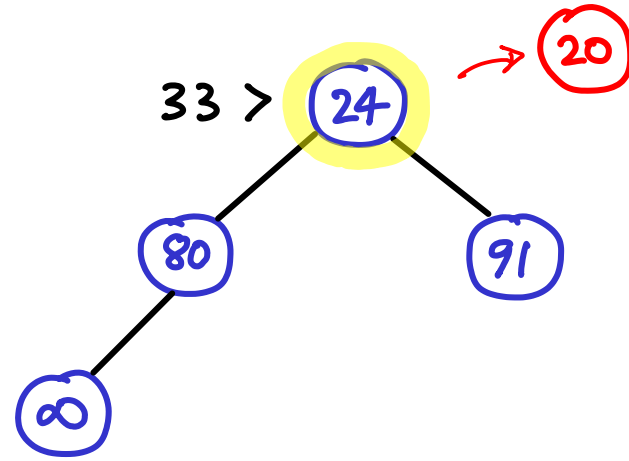
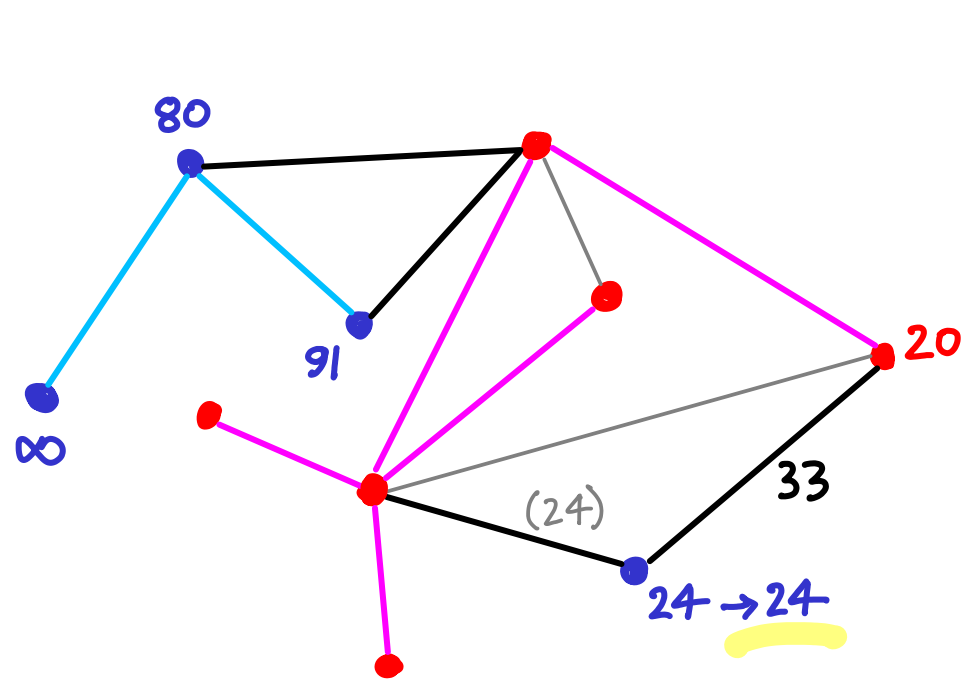
# PRIM'S ALGORITHM for MST



priority  
queue

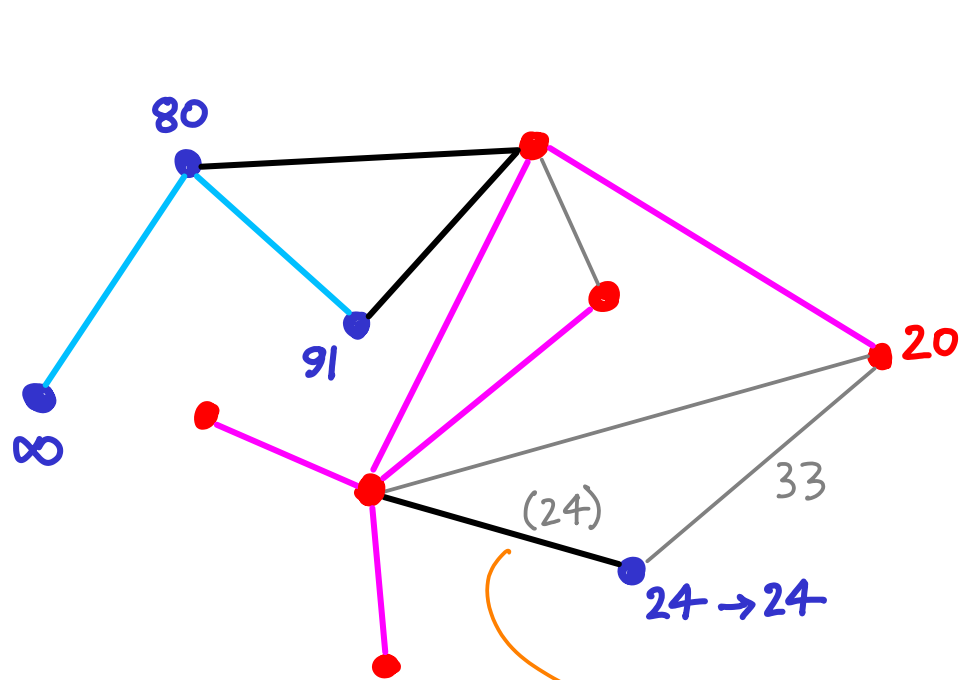


# PRIM'S ALGORITHM for MST

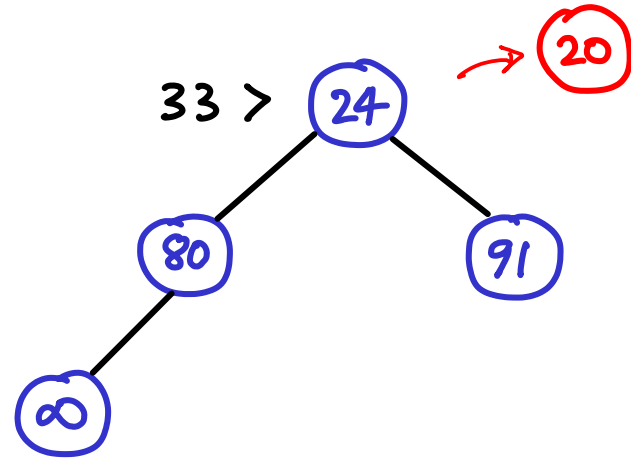


priority  
queue

# PRIM'S ALGORITHM for MST

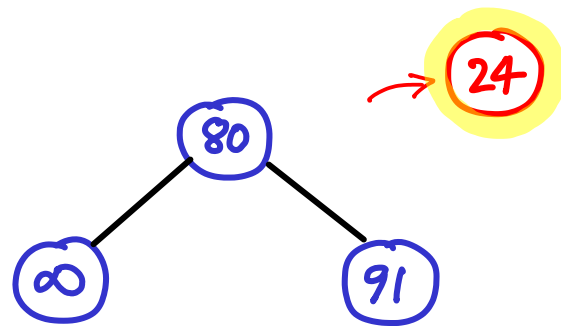
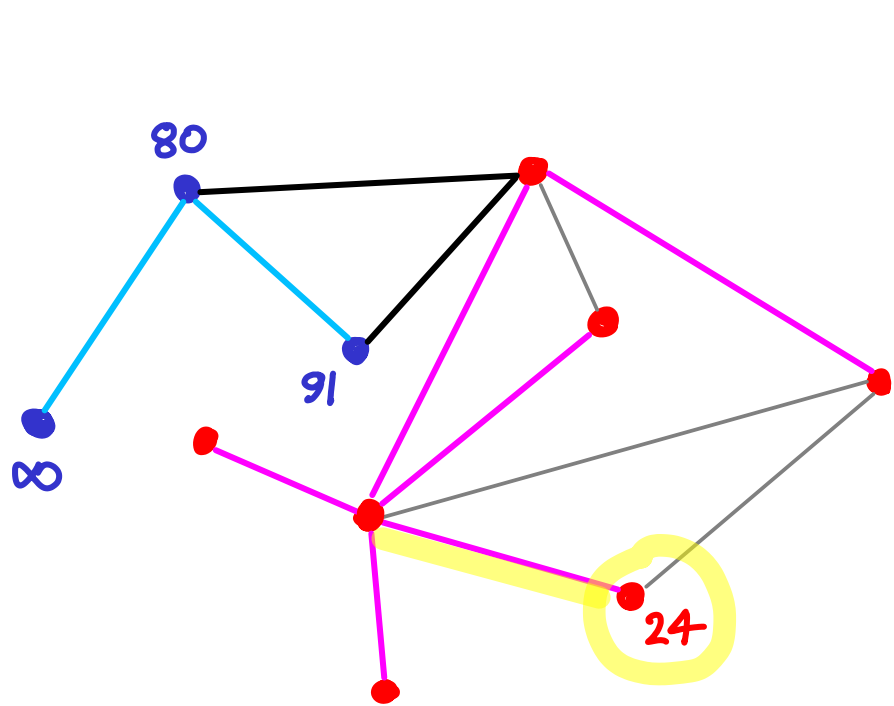


current best for vertex 24



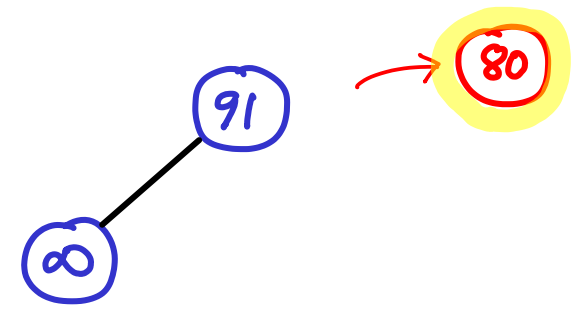
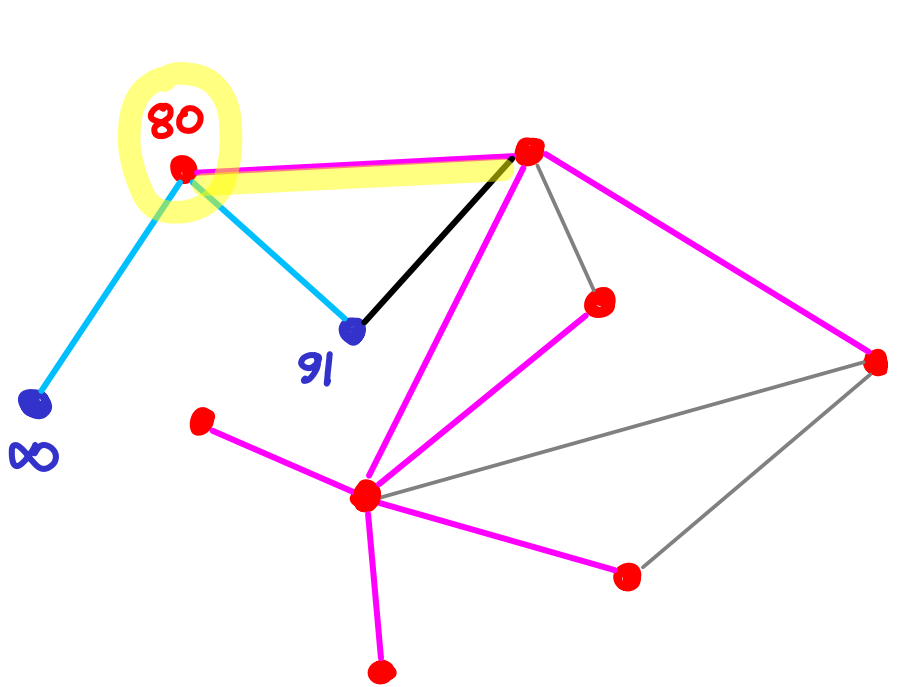
priority queue

# PRIM'S ALGORITHM for MST



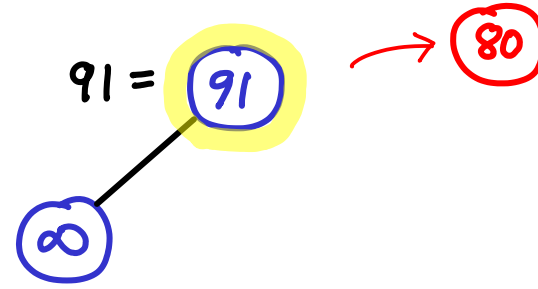
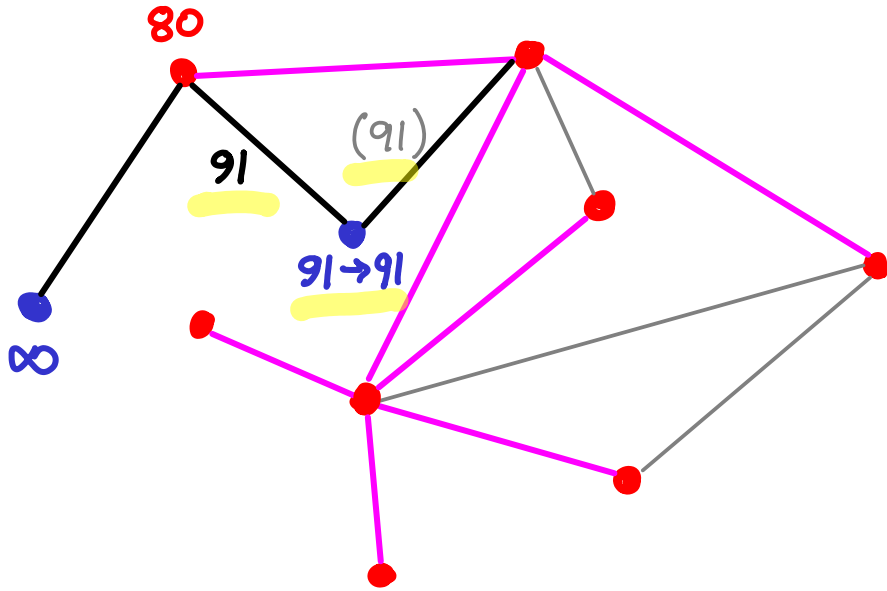
priority  
queue

# PRIM'S ALGORITHM for MST



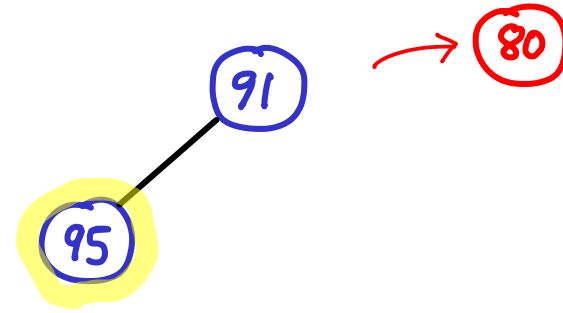
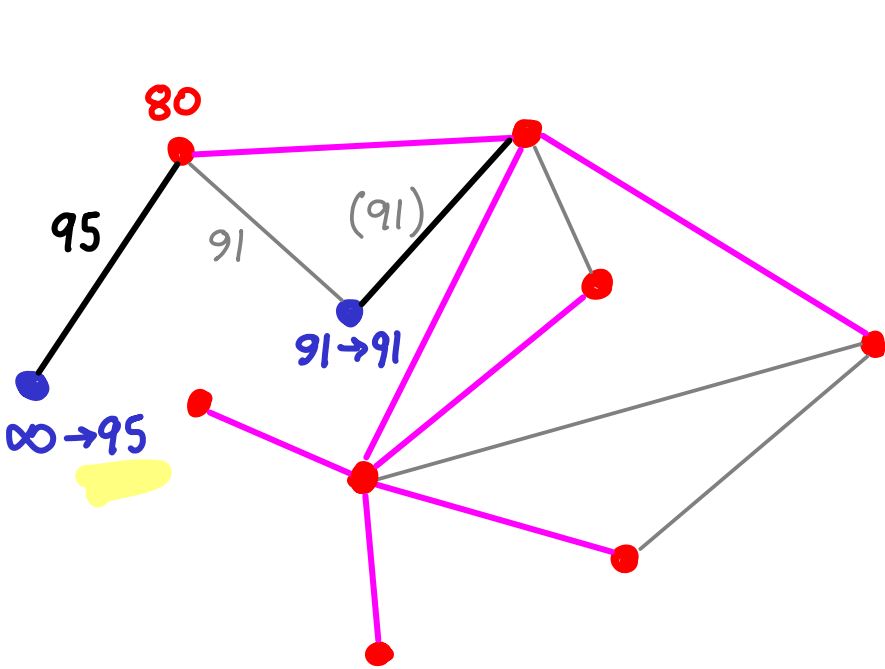
priority queue

# PRIM'S ALGORITHM for MST



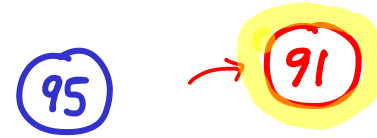
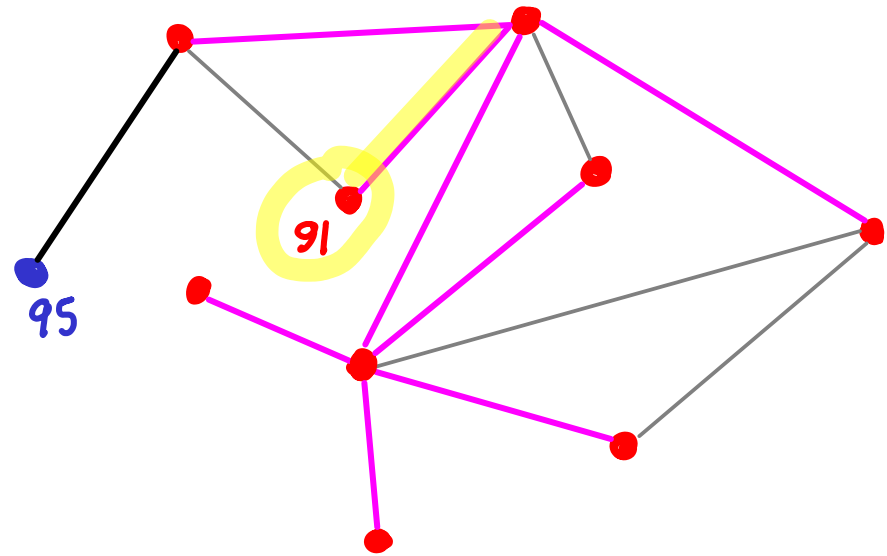
priority  
queue

# PRIM'S ALGORITHM for MST



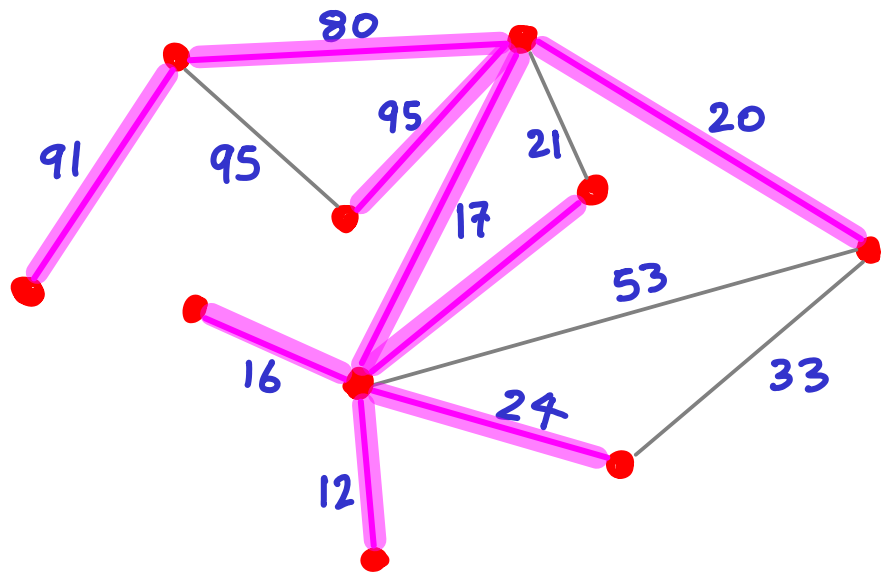
priority  
queue

# PRIM'S ALGORITHM for MST



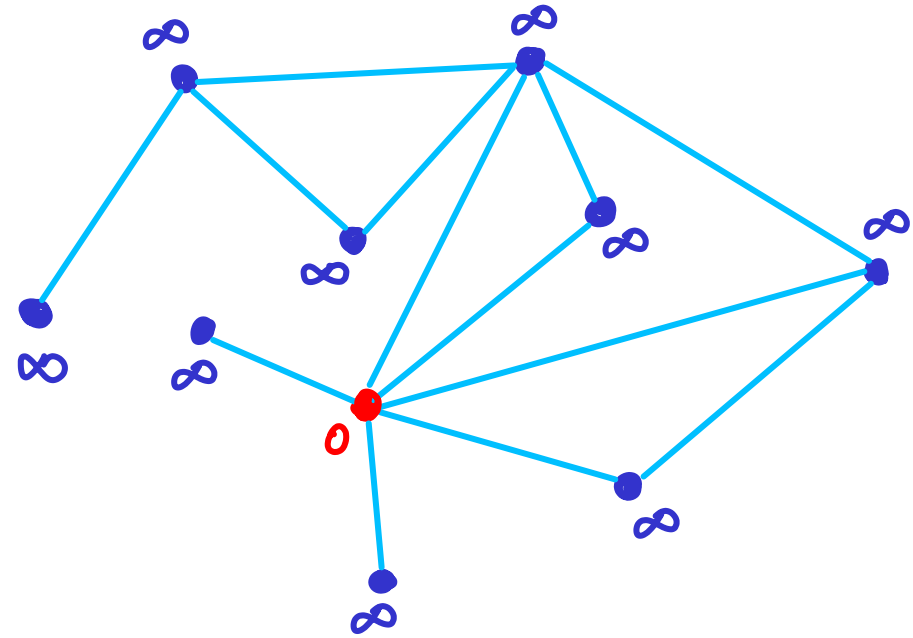
priority  
queue

# PRIM'S ALGORITHM for MST



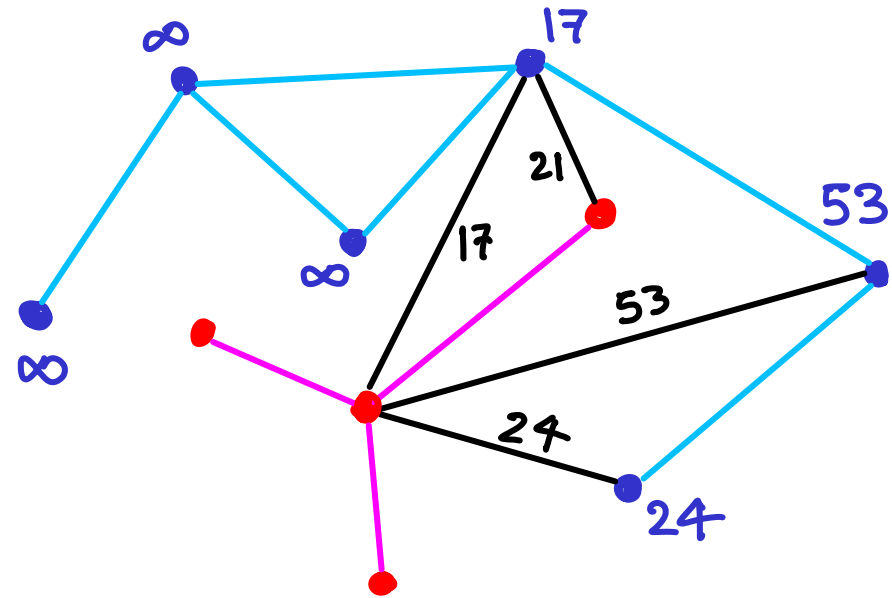


# PRIM'S ALGORITHM for MST



- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue

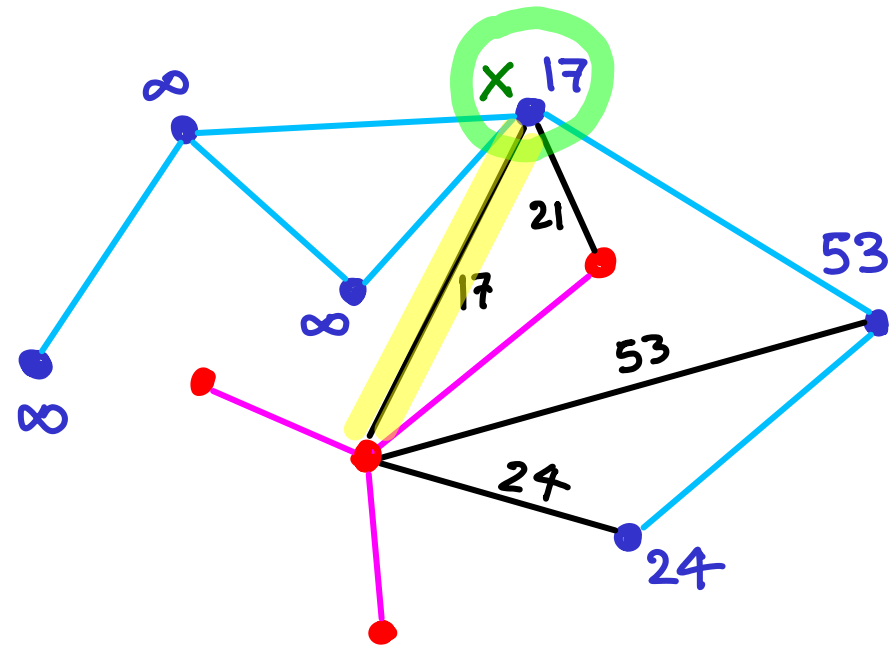
# PRIM'S ALGORITHM for MST



- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

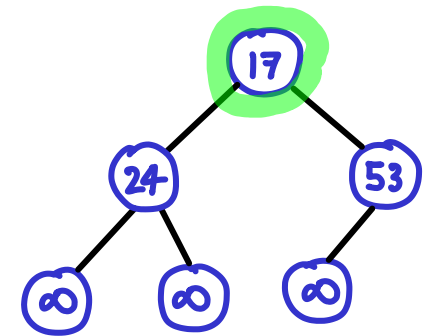
→  $|V|$  rounds

# PRIM'S ALGORITHM for MST



- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

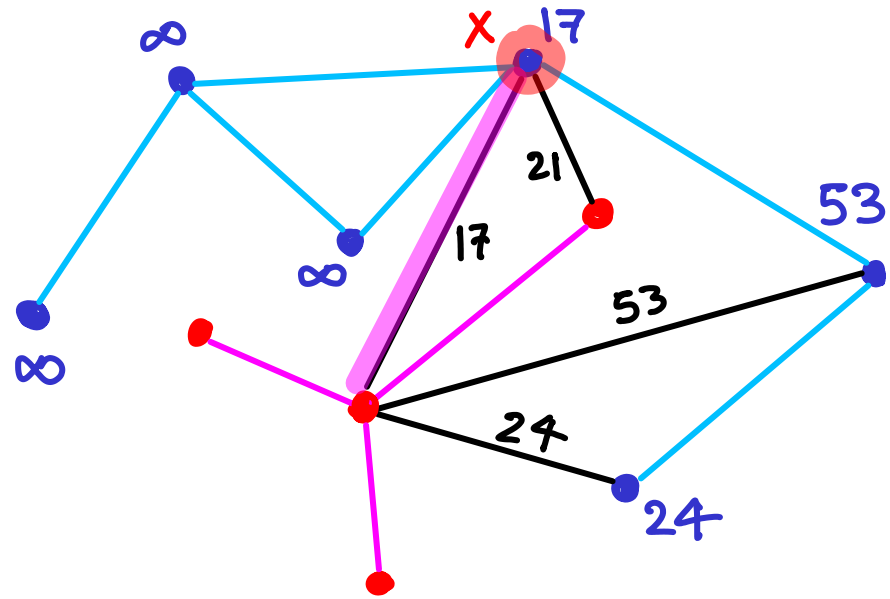
**x**: extract-min & add edge to  $T$   
mark  $x \rightarrow$  in  $T$ .



("add edge"  $\rightarrow$  find an edge from  $x$  to  $T$ , w/ min weight)

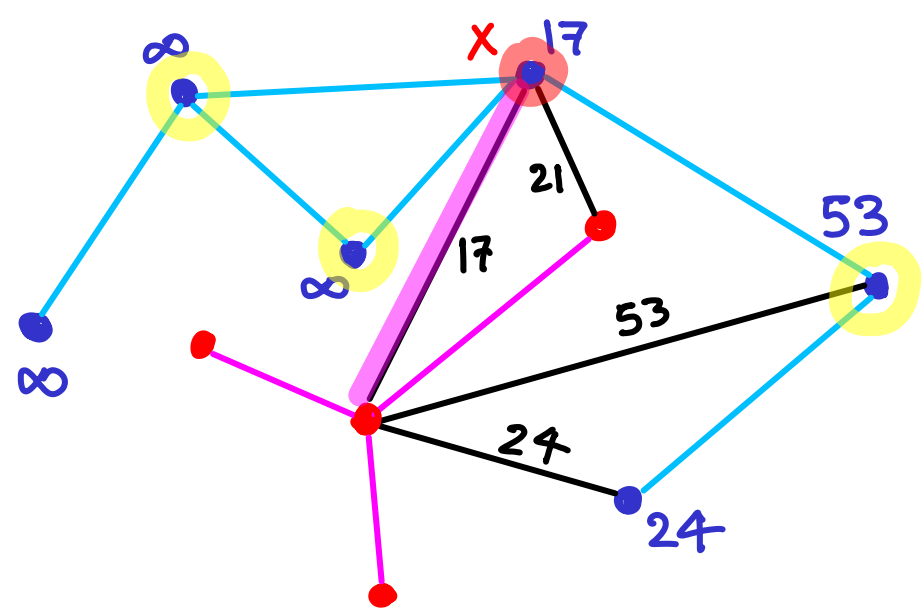
(if  $x=s$ , no edge to add)

# PRIM'S ALGORITHM for MST



- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty  
x: extract-min & add edge to  $T$   
mark  $x \rightarrow$  in  $T$ .

# PRIM'S ALGORITHM for MST



- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$x$ : extract-min & add edge to  $T$   
mark  $x \rightarrow$  in  $T$ .

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q, x)$  then decrease.

# PRIM'S ALGORITHM for MST

1) start w/ any vertex  $s$ ; set  $w(s)=0$   
2) set  $w(\neq s) = \infty$  & put all in pr.queue

$|V|$  rounds

3) while pr.queue not empty

x: extract-min & add edge to  $T$   
mark  $x \rightarrow$  in  $T$ .

for each unmarked neighbor  $q$  of  $x$   
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# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue

$|V|$  rounds

- 3) while pr.queue not empty

$x$ : extract-min & add edge to T

mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

cost for one round?

# PRIM'S ALGORITHM for MST

1) start w/ any vertex  $s$ ; set  $w(s)=0$   
2) set  $w(\neq s) = \infty$  & put all in pr.queue

$|V|$  rounds

$O(\log V) + O(\text{degree}(x))$

3) while pr.queue not empty

$x$ : extract-min & add edge to T  
mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q, x)$  then decrease.



# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$|V|$  rounds

$\sum_{x \in V} (O(\log V) + O(\text{degree}(x)))$

= ?

x: extract-min & add edge to T  
mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q, x)$  then decrease.

# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$|V|$  rounds

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x)))$$
$$= O(V \log V) + O(E)$$

adjacency list

x: extract-min & add edge to T  
mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q, x)$  then decrease.

# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$|V|$  rounds

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x)))$$
$$= O(V \log V) + O(E)$$

cost? ←

$x$ : extract-min & add edge to T  
mark  $x \rightarrow$  in  $T$ .

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q, x)$  then decrease.

# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$|V|$  rounds

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x)))$$
$$= O(V \log V) + O(E)$$

---

$$O(\text{degree}(x)) \cdot O(\log V)$$

$x$ : extract-min & add edge to T  
mark  $x \rightarrow$  in  $T$ .

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q, x)$  then decrease.

# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$x$ : extract-min & add edge to T  
mark  $x \rightarrow$  in  $T$ .

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

$|V|$  rounds

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x))) \\ = O(V \log V) + O(E)$$

$$\sum_{x \in V} O(\text{degree}(x)) \cdot O(\log V) \\ = ?$$

# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$x$ : extract-min & add edge to T  
mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

$|V|$  rounds

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x))) \\ = O(V \log V) + O(E)$$

$$\sum_{x \in V} O(\text{degree}(x)) \cdot O(\log V) \\ = O(E) \cdot O(\log V)$$

TOTAL COST ?

# PRIM'S ALGORITHM for MST

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$x$ : extract-min & add edge to T

mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

$|V|$  rounds

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x))) \\ = O(V \log V) + O(E)$$

$$\sum_{x \in V} O(\text{degree}(x)) \cdot O(\log V) \\ = O(E) \cdot O(\log V)$$

dominates

Using adjacency list

$$\text{TOTAL} = O(E \log V)$$

# PRIM'S ALGORITHM for MST

with Fibonacci heap  
(beyond scope of COMP160)

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty

$x$ : extract-min & add edge to T  
mark  $x \rightarrow$  in T.

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

$O(1)$  amortized

Using adjacency list

TOTAL =  $O(E + V \log V)$

$|V|$  rounds <sup>amortized</sup>

$$\sum_{x \in V} (O(\log V) + O(\text{degree}(x)))$$
$$= O(V \log V) + O(E)$$

$$\sum_{x \in V} O(\text{degree}(x)) \cdot \cancel{O(\log V)}$$
$$= O(E) \cdot \cancel{O(\log V)}$$



# PRIM'S ALGORITHM for MST

What if graph is  
in adjacency matrix?

- 1) start w/ any vertex  $s$ ; set  $w(s)=0$
- 2) set  $w(\neq s) = \infty$  & put all in pr.queue
- 3) while pr.queue not empty
  - x: extract-min & add edge to  $T$
  - mark  $x \rightarrow$  in  $T$ .
  - for each unmarked neighbor  $q$  of  $x$ 
    - if  $w(q) > w(q,x)$  then decrease.

# PRIM'S ALGORITHM for MST

Using adj. matrix  
w/ weighted entries

& no pr. queue

1) start w/ any vertex  $s$ ; set  $w(s)=0$   
2) set  $w(\neq s) = \infty$  & put all in ~~pr.queue~~ <sup>array</sup>

3) while ~~pr.queue not empty~~  $\exists v$  not in  $T$

scan array

scan row( $x$ )  
in matrix

$x$ : extract-min & add edge to  $T$   
mark  $x \rightarrow$  in  $T$ .

for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

# PRIM'S ALGORITHM for MST

Using adj. matrix  
w/ weighted entries

& no pr. queue

$|V|$  rounds

1) start w/ any vertex  $s$ ; set  $w(s)=0$   
2) set  $w(\neq s) = \infty$  & put all in ~~pr.queue~~ <sup>array</sup>

3) while ~~pr.queue not empty~~  $\exists v$  not in  $T$   
 $O(V)$  { scan array |  $x$ : extract-min & add edge to  $T$   
mark  $x \rightarrow$  in  $T$ .  
 $O(V)$  { scan row( $x$ ) in matrix | for each unmarked neighbor  $q$  of  $x$   
if  $w(q) > w(q,x)$  then decrease.

$O(V^2)$  time & space