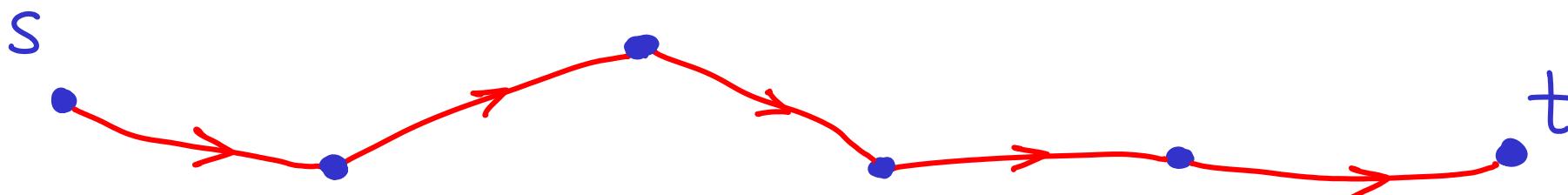


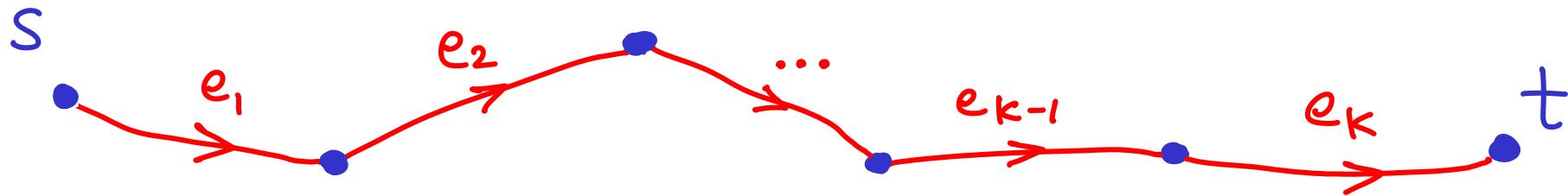
Assume this is a shortest path from s to t

unknown
but
exists

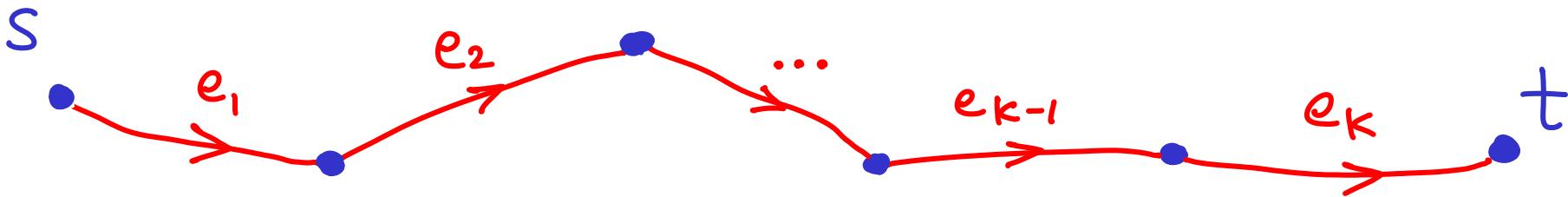


Assume this is a shortest path from s to t

unknown
but
exists

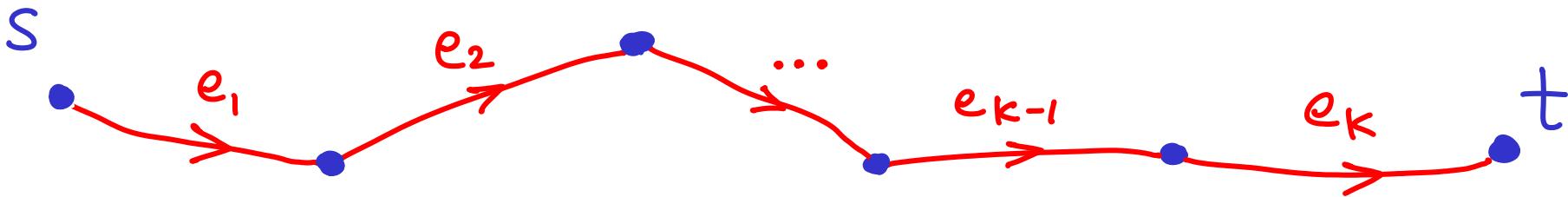


Assume this is a shortest path from s to t unknown but exists



Suppose we have an algorithm based on relaxing edges.

Assume this is a shortest path from s to t unknown but exists

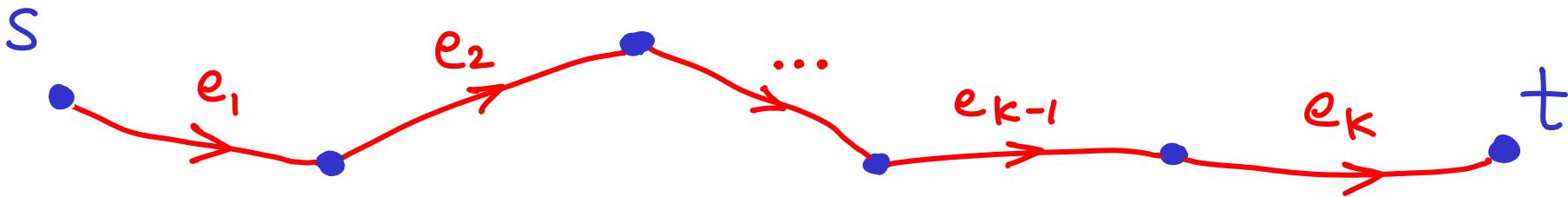


Suppose we have an algorithm based on relaxing edges.

If we relax e_1 before e_2 before ... before e_{k-1} before e_k

then ... ?

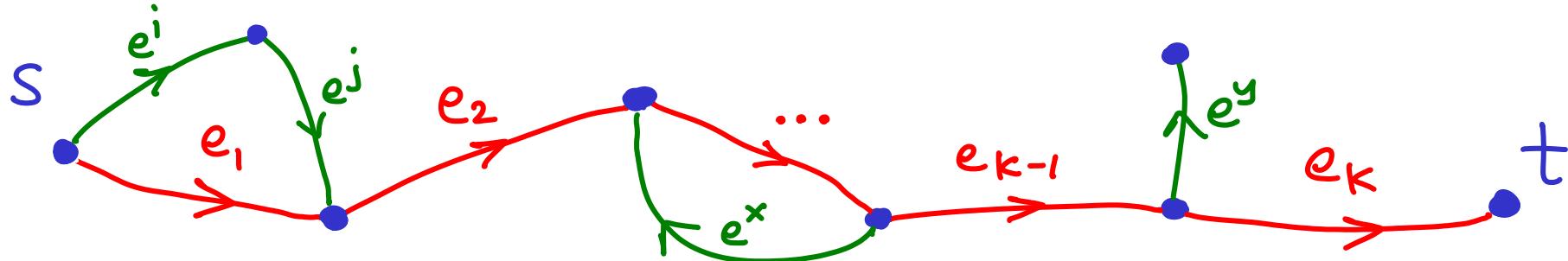
Assume this is a shortest path from s to t unknown but exists



Suppose we have an algorithm based on relaxing edges.

If we relax e_1 before e_2 before ... before e_{k-1} before e_k
then we will correctly compute $d(t)$

Assume this is a shortest path from s to t unknown but exists



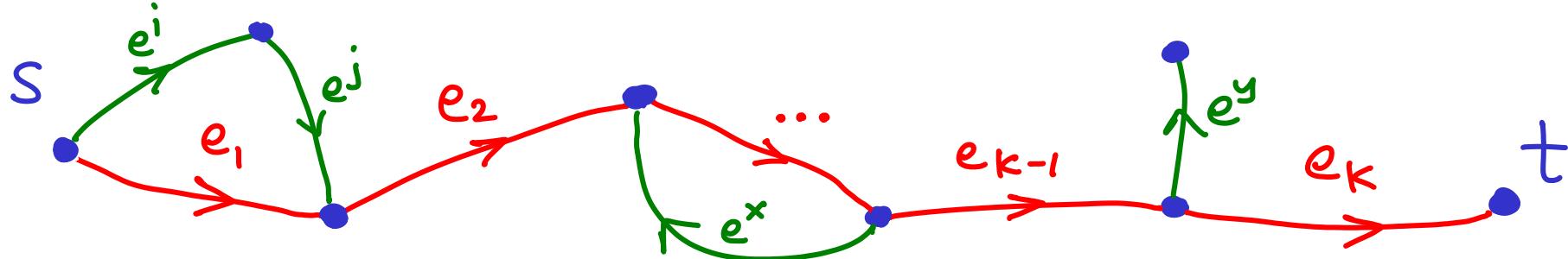
Suppose we have an algorithm based on relaxing edges.

If we relax e_i before e_2 before ... before e_{k-1} before e_k

arbitrary then we will correctly compute $d(t)$

Relax sequence : $e^x e_i e^j e^y e_2 e^x e^i \underline{e_k} e_{k-1} e_i e^x e_k e^y$

Assume this is a shortest path from s to t unknown but exists



Suppose we have an algorithm based on relaxing edges.

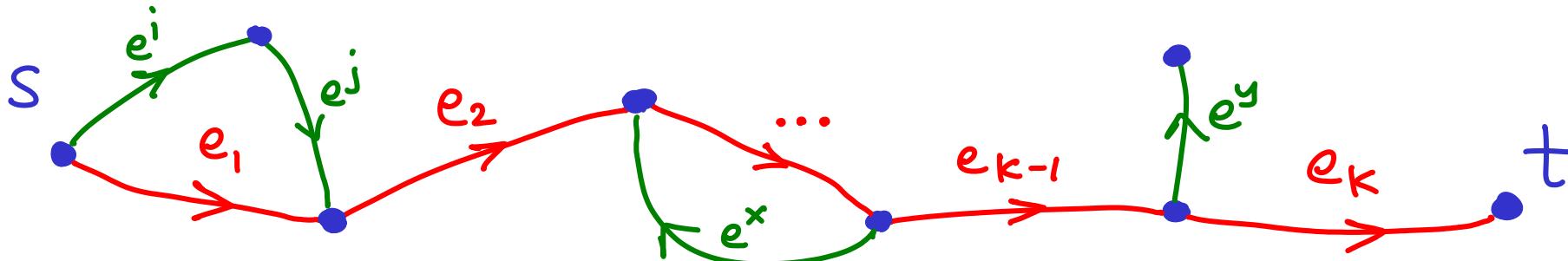
If we relax e_1 before e_2 before ... before e_{k-1} before e_k

then we will correctly compute $d(t)$

Relax sequence : $e^x e_1 e^j e^y e_2 e^x e^i e_k e_{k-1} e_1 e^x e_k e^y$: OK

(don't care if we relax other edges or the same ones repeatedly)

Assume this is a shortest path from s to t unknown but exists



Suppose we have an algorithm based on relaxing edges.

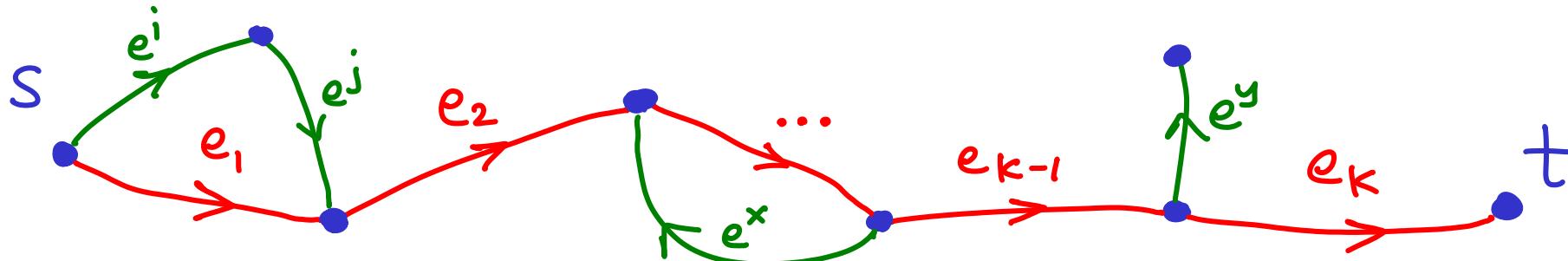
If we relax e_1 before e_2 before ... before e_{k-1} before e_k

then we will correctly compute $d(t)$ WHY?

Relax sequence : $e^x e_1 e^j e^y e_2 e^x e^i e_k e_{k-1} e_1 e^x e_k e^y$: OK

(don't care if we relax other edges or the same ones repeatedly)

Assume this is a shortest path from s to t unknown but exists



Suppose we have an algorithm based on relaxing edges.

If we relax e_1 before e_2 before ... before e_{k-1} before e_k

then we will correctly compute $d(t)$ by INDUCTION

Relax sequence : $e^x e_1 e^j e^y e_2 e^x e^i e_k e_{k-1} e_1 e^x e_k e^y$: OK

(don't care if we relax other edges or the same ones repeatedly)

BELLMAN-FORD ALGORITHM

simple, but made even simpler
(not identifying negative cycles)

Finds a shortest path from s to ALL vertices

BELLMAN-FORD ALGORITHM

simple, but made even simpler
(not identifying negative cycles)

L. Ford (1956) → slower variant

R. Bellman (1958)

Finds a shortest path from s to ALL vertices

BELLMAN-FORD ALGORITHM

simple, but made even simpler
(not identifying negative cycles)

A. Shimbel (1954) → slower variant

L. Ford (1956) → slower variant

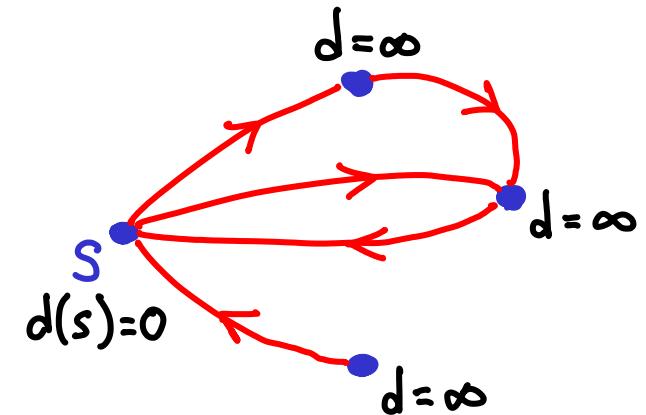
E. Moore (1957) → non-negative weights

R. Bellman (1958)

Finds a shortest path from s to ALL vertices

BELLMAN-FORD ALGORITHM

- i) set score of s : zero
- set score of $\neq s$: ∞
- set parent of $\neq s$: null



BELLMAN-FORD ALGORITHM

1) set score of s : zero

set score of $\neq s$: ∞

set parent of $\neq s$: null

2) for $i = 1$ to $V-1$

RELAX every edge in G

BELLMAN-FORD ALGORITHM

1) set score of s : zero

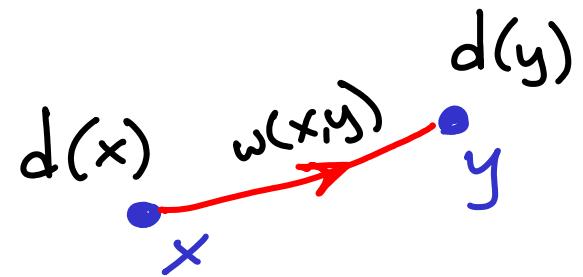
set score of $\neq s$: ∞

set parent of $\neq s$: null

2) for $i = 1$ to $V-1$

RELAX every edge in G

RELAX an edge $x \rightarrow y$
if $d(x) + w(x,y) < d(y)$
then $| d(y) = d(x) + w(x,y)$
 $| \text{parent}(y) = x$



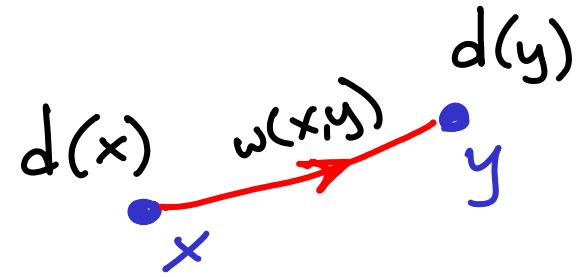
BELLMAN-FORD ALGORITHM time?

- 1) set score of s : zero
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BELLMAN-FORD ALGORITHM

$O(V \cdot E)$

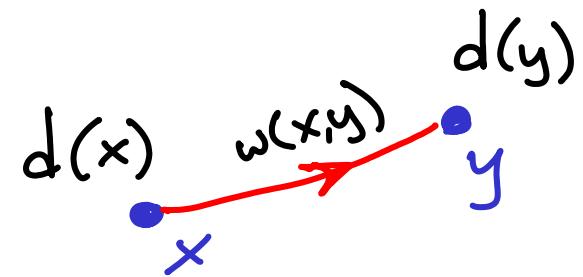
1) set score of s : zero

set score of $\neq s$: ∞

set parent of $\neq s$: null

2) for $i = 1$ to $V-1$

RELAX every edge in G

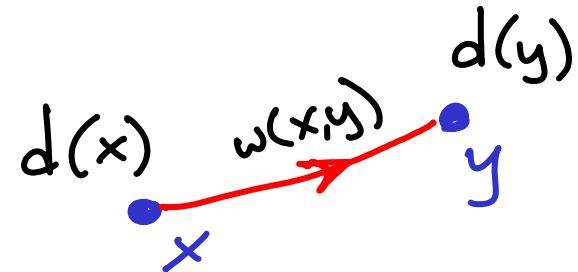


RELAX an edge $x \rightarrow y$
 if $d(x) + w(x,y) < d(y)$
 then $| d(y) = d(x) + w(x,y)$
 $| \text{parent}(y) = x$

BELLMAN-FORD ALGORITHM

$O(V \cdot E)$

- 1) set score of s : zero
set score of $\neq s$: ∞
set parent of $\neq s$: null



Why does this work?

- 2) for $i = 1$ to $V-1$
RELAX every edge in G

RELAX an edge $x \rightarrow y$

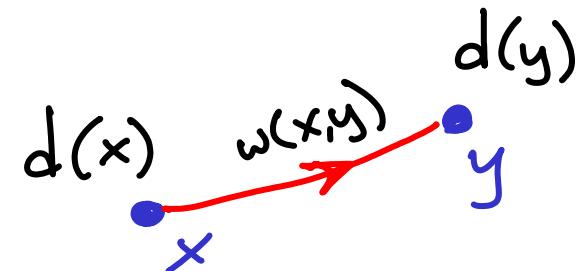
if $d(x) + w(x,y) < d(y)$

then | $d(y) = d(x) + w(x,y)$
| $\text{parent}(y) = x$

BELLMAN-FORD ALGORITHM

$O(V \cdot E)$

- 1) set score of s : zero
set score of $\neq s$: ∞
set parent of $\neq s$: null



- 2) for $i=1$ to $V-1$
RELAX every edge in G

RELAX an edge $x \rightarrow y$

if $d(x) + w(x,y) < d(y)$

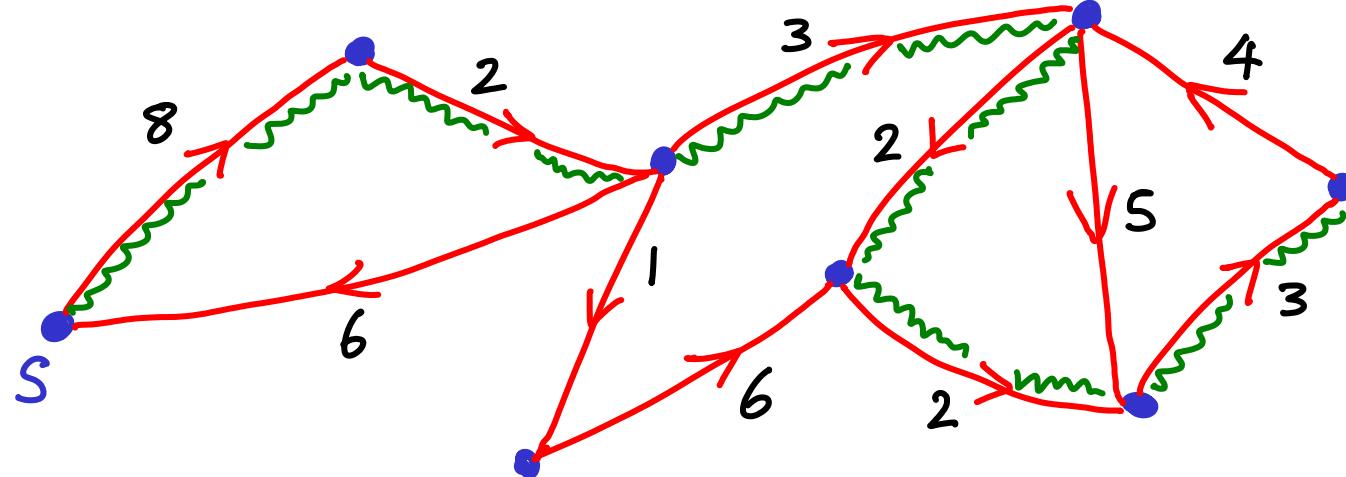
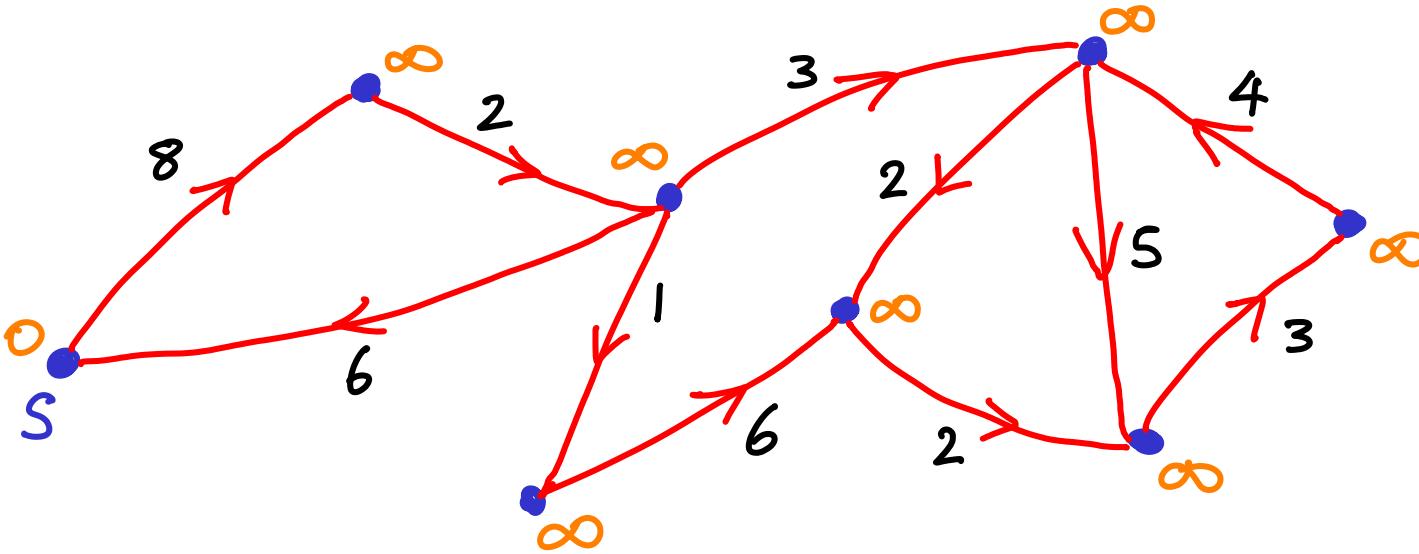
then | $d(y) = d(x) + w(x,y)$
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Why does this work?

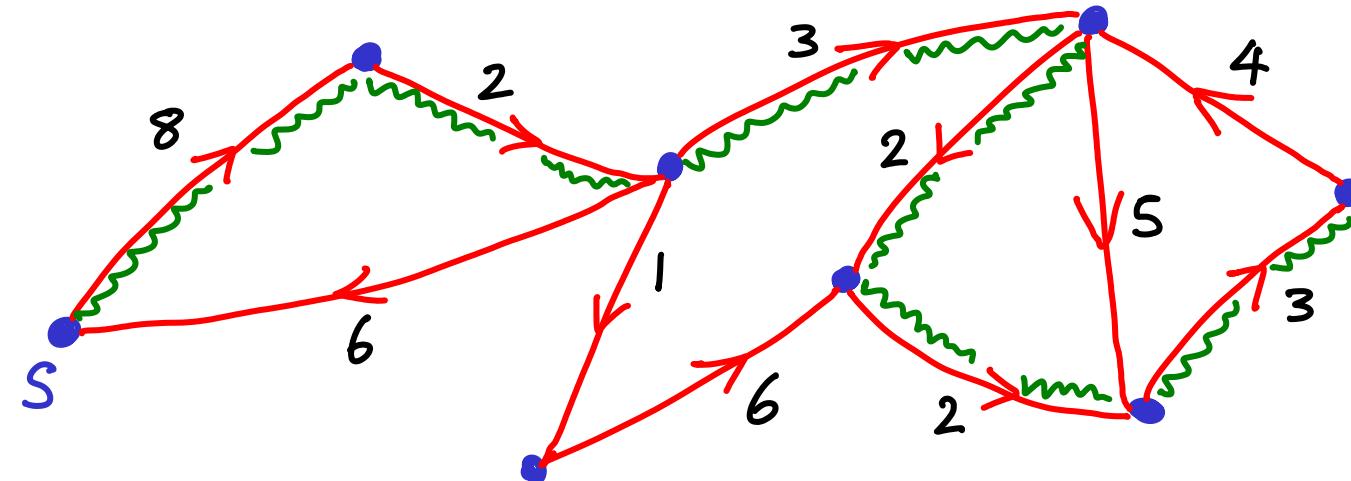
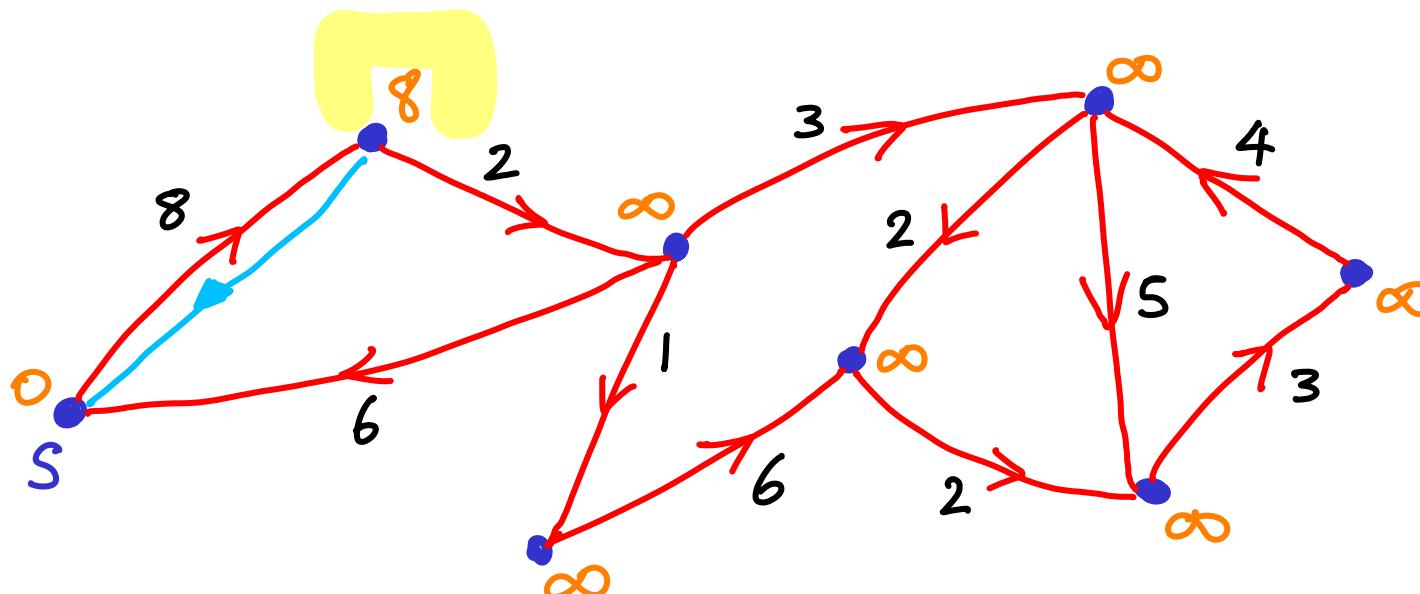


FOR ANY t

In iteration i
we will get $d(p_i^t)$
on some shortest path p^t
 $= \{p_1^t, p_2^t, p_3^t, \dots, p_k^t = t\}$
from $s \rightarrow t$



$i = 1$

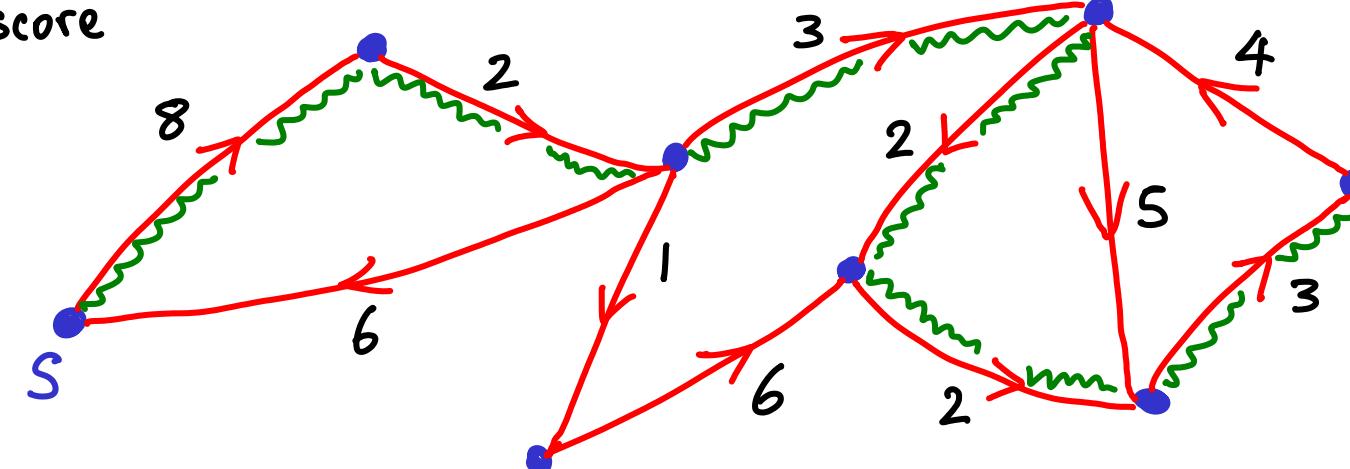
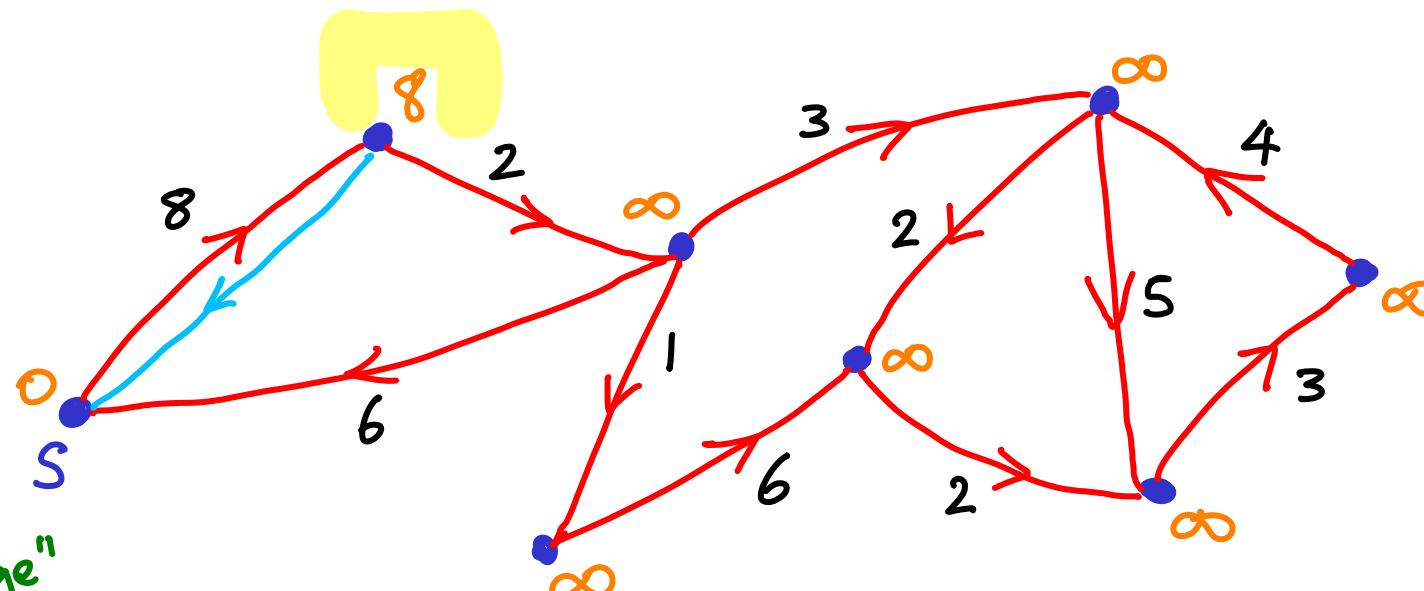


$i=1$

depending on
order of
processing
edges in

"RELAX every edge"

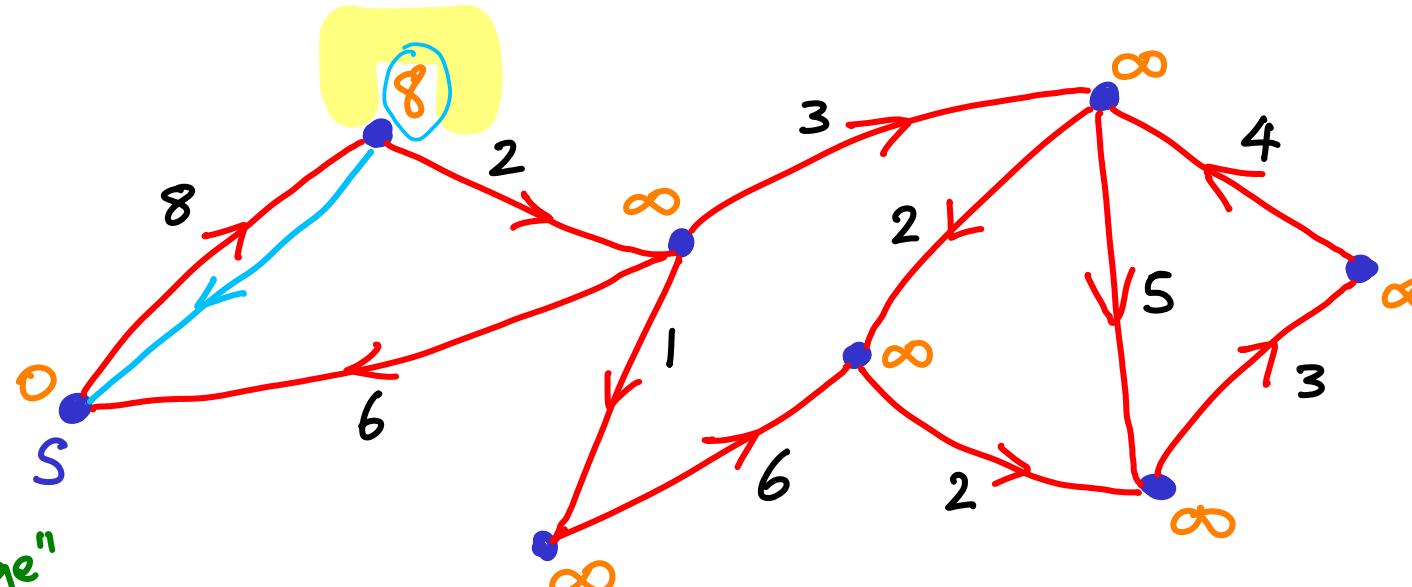
we might get
only 1 finite score
or actually
be done.



$i=1$

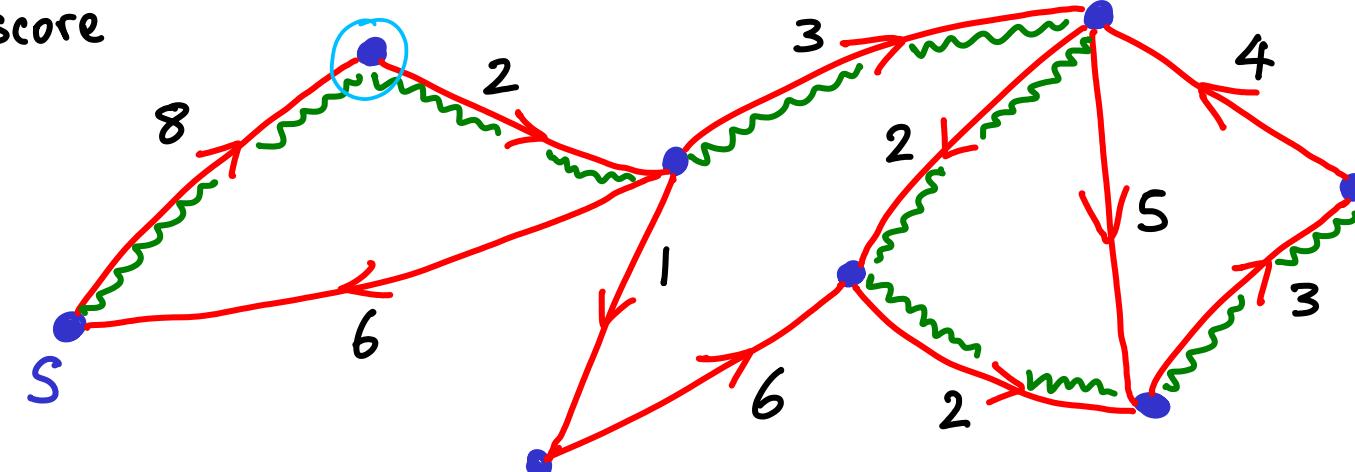
depending on
order of
processing
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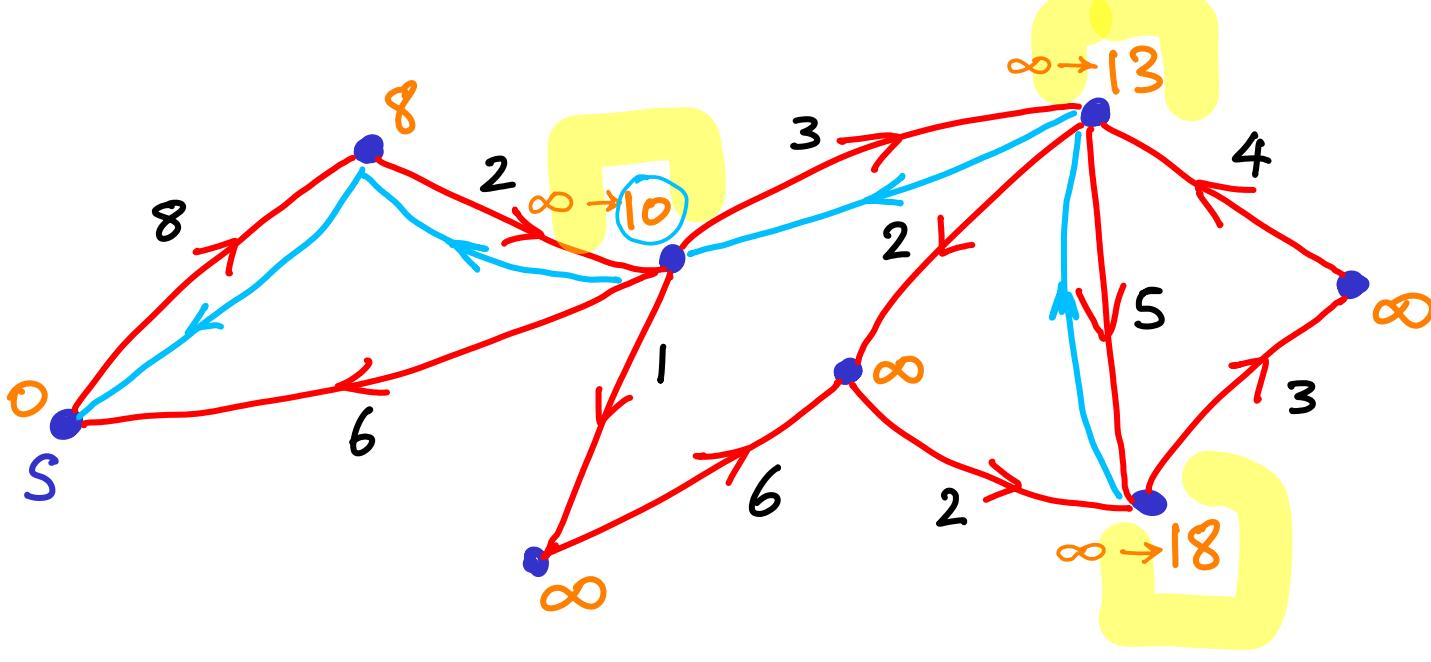


What matters
is that we
get final
score of
a vertex on
shortest path
to target

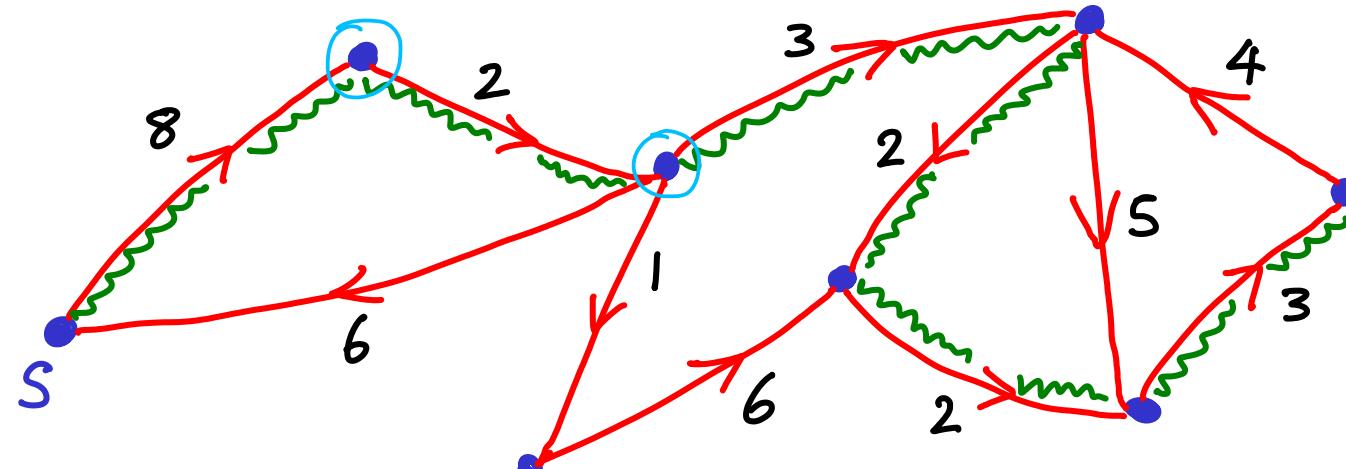
& in fact
we extend a
chain of
such vertices.



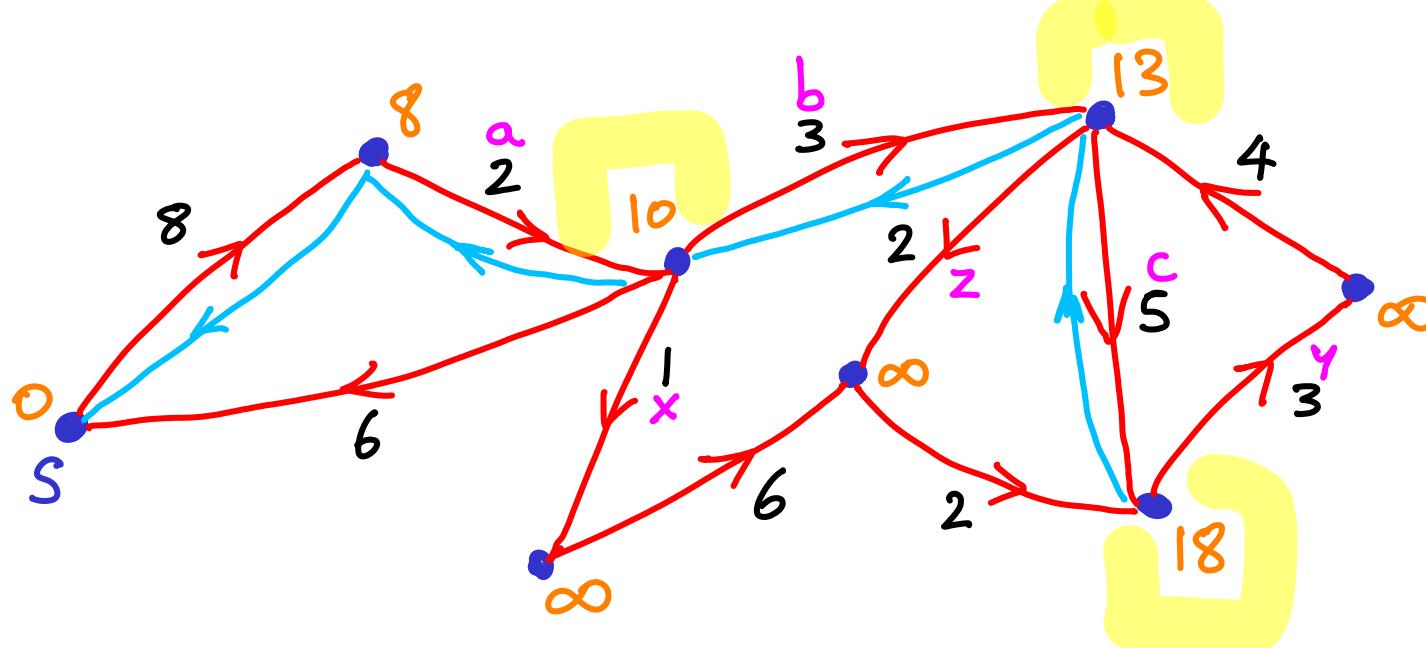
$i = 2$



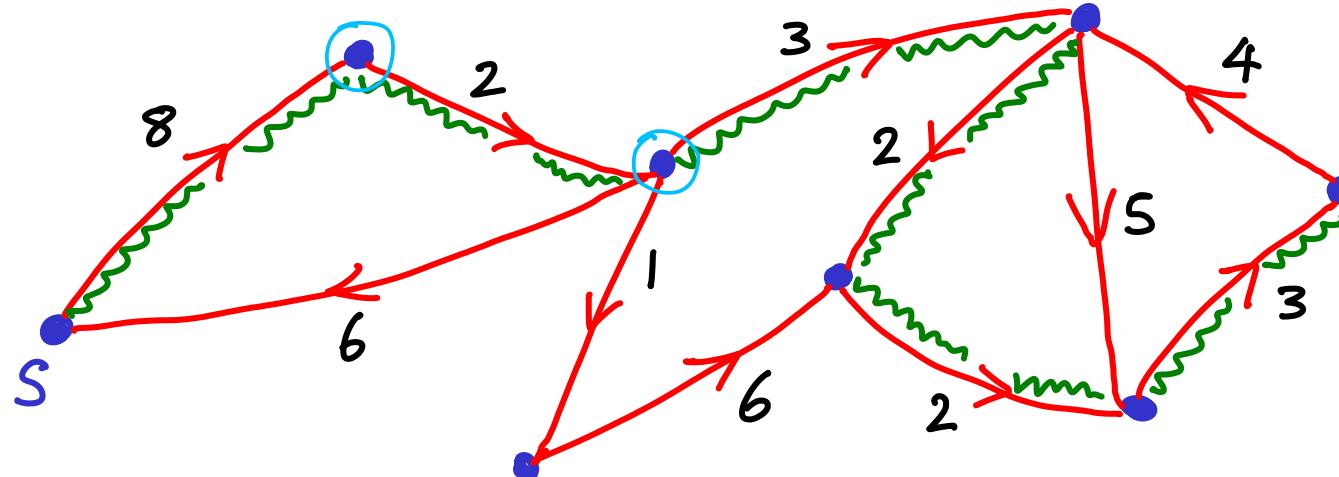
order of
relaxing?



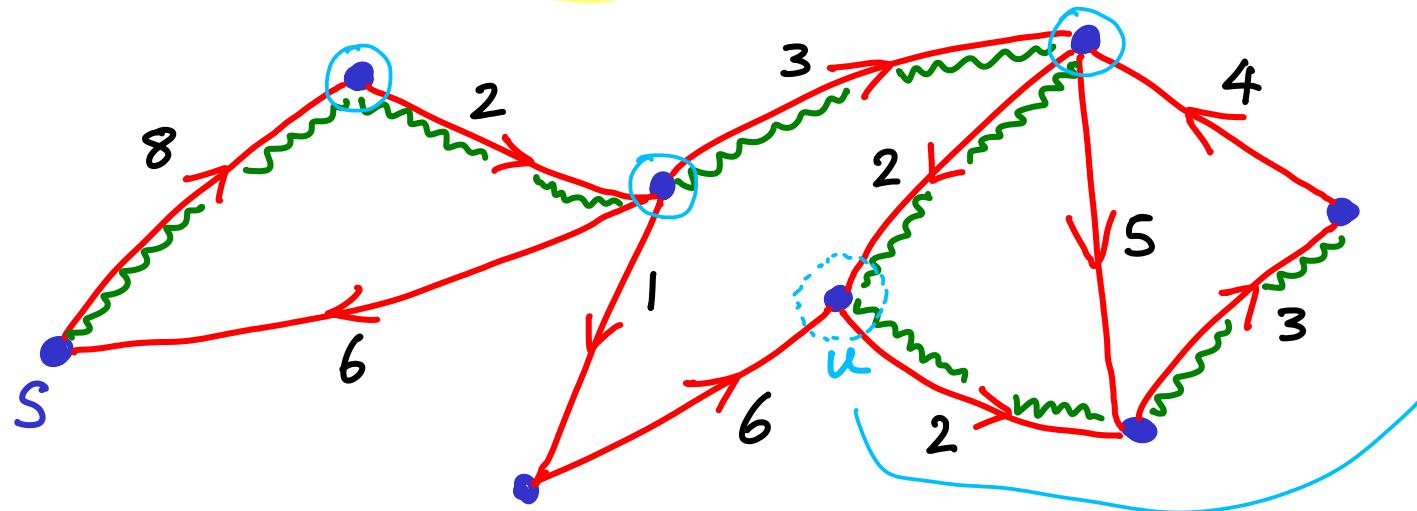
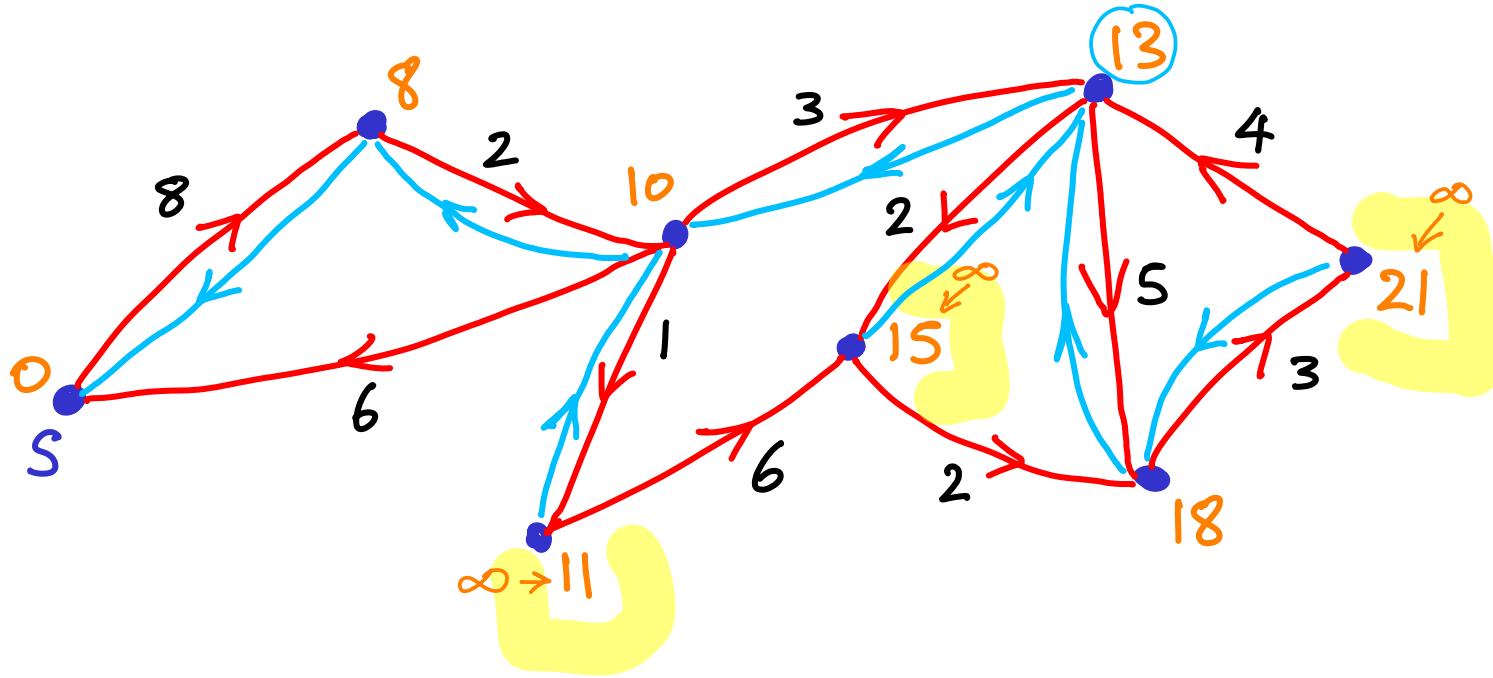
$i = 2$



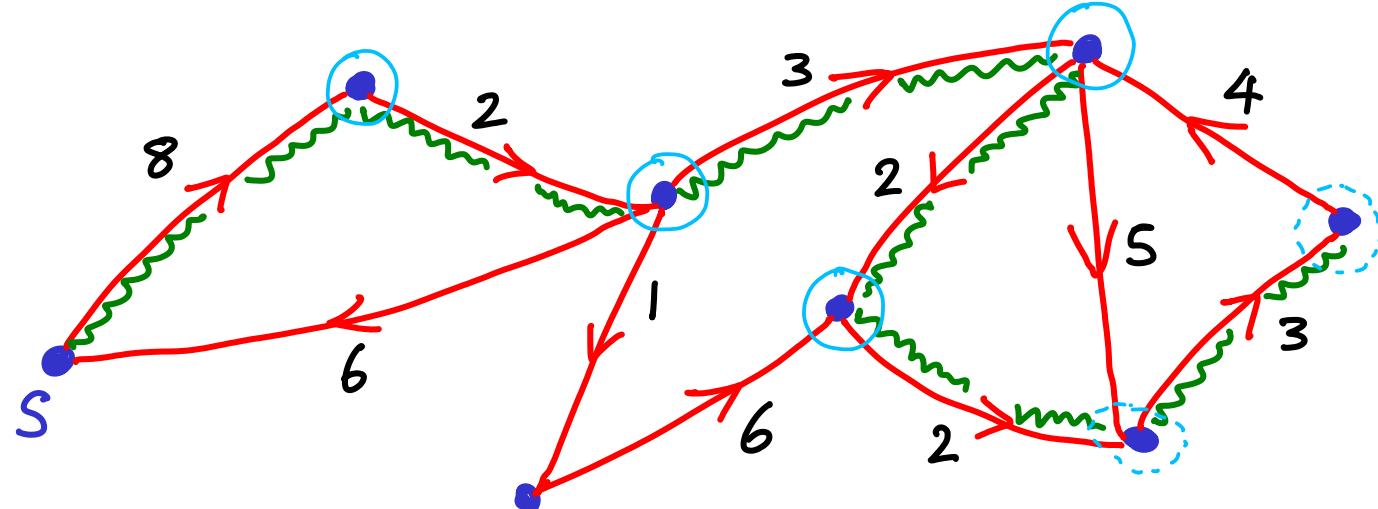
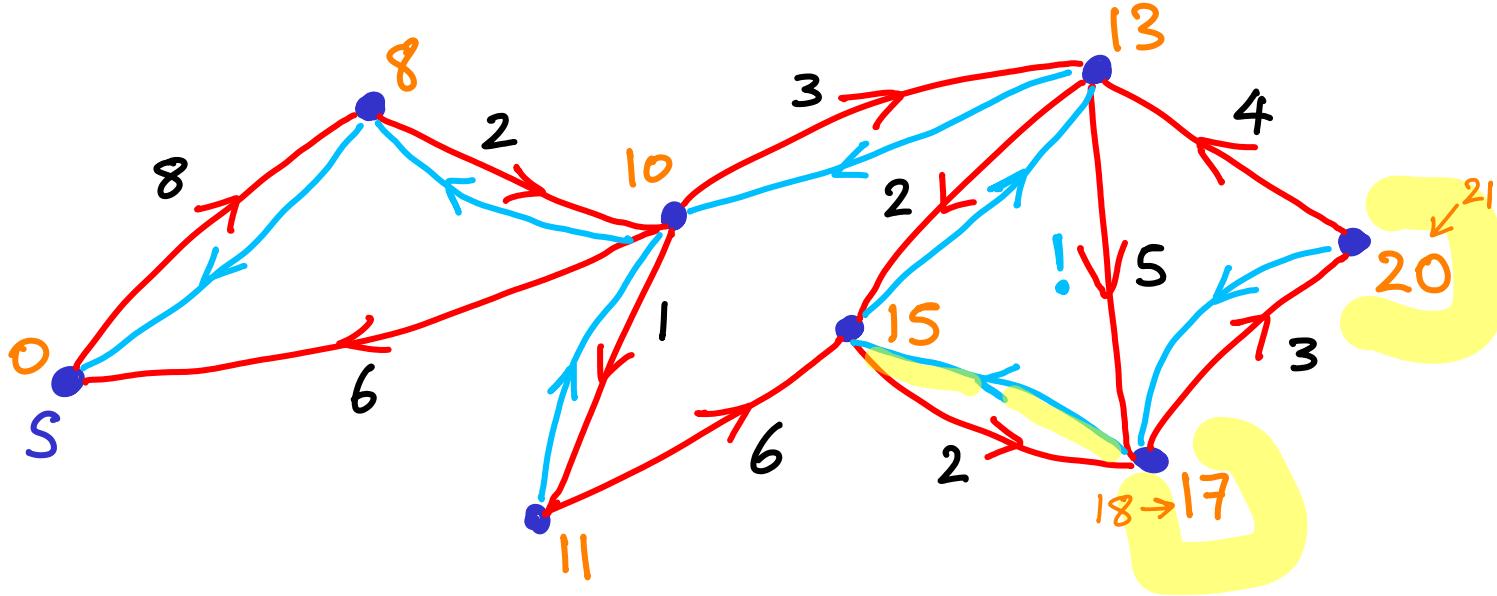
order of
relaxing?
x...a...b...c
y...c
z...b



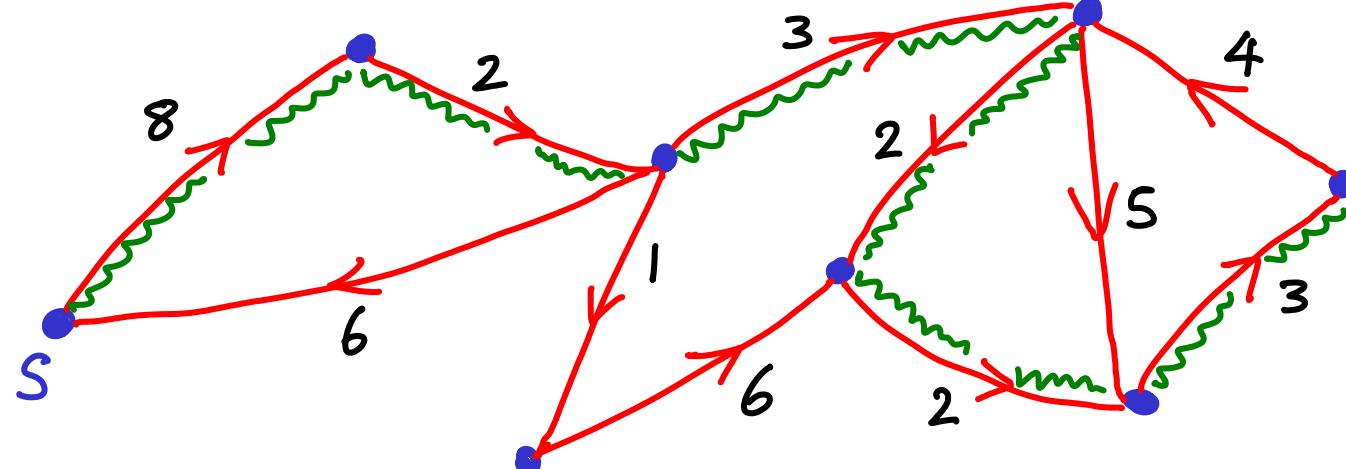
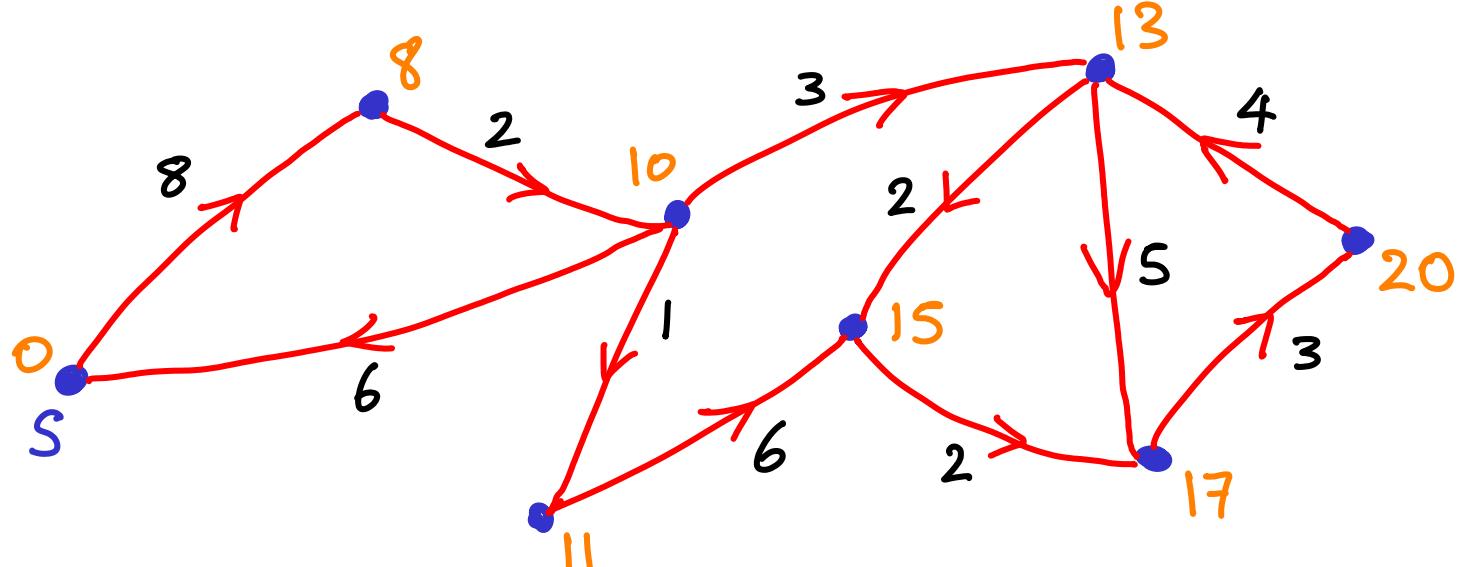
$i = 3$



$i=4$



$i = 5, 6, 7$
↳ redundant



BELLMAN-FORD ALGORITHM

Works for negative weights

& can detect negative cycles. (how?)

(see CLRS)

BELLMAN-FORD ALGORITHM

Works for negative weights

& can detect negative cycles.

scores will still
be changing
after $i = V-1$

(see CLRS)