Reduction of Stray Loss in Power Transformers Using Horizontal Magnetic Wall Shunts

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The use of a horizontal arrangement of wall shunts is proposed in this paper as a cost-effective way to reduce the stray losses in power transformers. This paper compares the performance of horizontal wall shunts with the available alternative (vertical shunts). A 3-D finite-element analysis (FEA) is used for the calculation of stray losses in tank walls, and other structural parts. A novel hybrid numerical/analytical method is proposed for the calculation of stray losses inside the magnetic shunts. The proposed method is based on the double Fourier series expansions of the magnetic field distribution at the surface of the shunts, which is determined using 3-D FEA. A 200 MVA power transformer is investigated as a case study where the stray losses are calculated with and without the vertical and horizontal shunts. A parametric FEA is carried out to find the optimal placement of the horizontal shunts on the tank walls. Results show that the proposed horizontal magnetic shunts arrangement are as effective as the conventional vertical shunts in reducing the stray losses while reducing the weight of the shields, therefore providing a cost-effective method for magnetic shielding of the transformer tank walls.

Index Terms—Finite-element method (FEM), magnetic shielding, power transformer, stray loss, wall shunts.

NOMENCLATURE

- A Magnetic vector potential (V \cdot s/m).
- H Magnetic field (A/m).
- *B* Magnetic flux density (Tesla).
- J Eddy-current density (A/m^2) .
- ω Frequency (rad/s).
- μ Magnetic permeability (H/m).
- v Magnetic reluctivity (m/H).
- σ Electrical conductivity (S/m).
- P Power loss (W).

I. INTRODUCTION

S TRAY load losses in transformer tanks and structural parts caused by flux escaping the core play a key role in the transformer overall performance and therefore, reducing these losses is of a great importance for manufacturers. Magnetic wall shunts in power transformers are frequently used to reduce stray losses and eliminate possible hot spots in the tank and structural parts [see Fig. 1(a)]. These types of shields create a low reluctance path for the stray flux and prevent it from reaching the tank. Magnetic shunts are built from laminated steel packets to reduce the losses due to the normal component of the magnetic field to the shunt surface [1].

The design of magnetic shunts is always a great challenge when designing large power transformers. Many studies on the 2-D and 3-D calculations of leakage magnetic field and eddy-current losses in power transformers have been performed [1]–[16]. For the calculation of stray fields in power transformers with magnetic wall shunts, 3-D modeling

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is needed to accurately compute the effect of different arrangements of magnetic shunts on the stray losses.

Different structures of magnetic shunts in power transformers are studied in [16]-[25], using the finite-element method (FEM) analysis. Horizontal magnetic shunts under the transformer yokes are studied in [20] and [21]. Also, the effect of the lobe-type magnetic shielding on the stray losses of power transformer using the 3-D FEM analysis is studied. In [10], a numerical method based on network approach is presented and it is used in [21] to model the effect of magnetic shunts on transformer stray flux. Many methods are proposed for nonlinear laminated steel modeling and calculation of its stray loss [26]–[36]. The homogenization method has been proposed in [26] and [27] to model the nonlinear laminated steel. In this method, the solution needs to be obtained twice which doubles the calculation time. No study has been performed to investigate the effectiveness of horizontal magnetic wall shunts on transformers stray losses. This type of magnetic shunt diverts the stray flux of the three phases to itself, and thus prevents the flux from entering the tank. Therefore, this technique can effectively reduce the stray losses in large power transformers.

In this paper, a horizontal wall shunt arrangement is proposed and its effectiveness is compared against conventional vertical magnetic wall shunts in reducing the stray losses of power transformers. The investigation is carried out using 3-D finite-element analysis (FEA) using COMSOL Multiphysics. Stray load losses on the tank walls and yoke beams are calculated using surface impedance boundary condition (IBC). Magnetic wall shunts are modeled with nonlinear anisotropic permeability and the corresponding losses are calculated using an analytical method. The presented analytical method uses the magnetic field distribution calculated with 3-D FEM, as boundary condition and Maxwell equations are solved inside the magnetic shunts using the double Fourier series expansion method. Fig. 1(b) shows the 200 MVA

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Fig. 1. Three-phase three-legged 200 MVA transformer. (a) Conventional vertical wall shunts. (b) Proposed horizontal wall shunts.

sample transformer with the new proposed horizontal wall shunts.

II. 3-D FINITE-ELEMENT MODELING

The 3-D FEM for solving the eddy-current problem uses the quasi-static magnetic vector potential partial differential equation formulation given by

$$\nabla \times (v(\nabla \times A)) = J_e - j\omega\sigma A. \tag{1}$$

Three-phase full load current excitation is applied to windings. Since the distance between the tank walls and the outer windings is not equal in all directions, no symmetry boundary condition is applied to the 3-D model of the transformer to maximize the accuracy of the analysis.

A. Impedance Boundary Condition

At the boundaries where the magnetic field penetrates only a short distance into the boundary, the IBC is used for approximating the magnetic field penetration into the boundary. The IBC can be used to model a bounded domain as an unbounded region and is a valid approximation if the skin depth is small compared with the size of the conductor. The penetration depth δ is measured using the following equation:

$$\delta = \sqrt{\frac{2}{\omega\mu\sigma}}.$$
 (2)

The IBC boundary condition, which is a combination of the Dirichlet and Neumann boundary conditions, proposes a relationship between the value of magnetic vector potential *A* and its normal derivative at the boundary. This boundary condition can be written as the following equation:

$$\frac{\partial A}{\partial n} + cA = 0 \tag{3}$$

where c is a constant determined by the permeability and conductivity of the boundary material. Since in power transformers, tank walls and yoke beams are made of iron and the penetration depth at 60 Hz for iron is less than 1 mm, in the 3-D FEM model of the transformer, IBC is applied to the interior boundaries of the tank walls and the exterior boundaries of the yoke beams.

B. Magnetic Shunt Modeling

Magnetic shunts are constructed using laminated steel and therefore should be modeled with nonlinear anisotropic permeability. The magnetization characteristic of M-5 steel (shown in Fig. 3) is used for modeling the nonlinearities of the shunts. The conductivity of the shunts is set to zero in the FEM model, and then, the eddy-current losses are calculated with the analytical method described in Section III.

III. MAGNETIC SHUNT LOSS CALCULATION

The losses in the magnetic wall shunts can be calculated using a series expansion of eddy-current loss based on the 2-D spatial harmonics of current density inside a magnetic wall shunt. This series can be expressed as follows:

$$P = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} P_{mn} \tag{4}$$

where P_{mn} is the eddy-current loss due to the spatial current density harmonics. The current density harmonics in the magnetic shunt sheets can be calculated based on an analytical approach provided that the magnetic field distribution on the magnetic shunts surface is known. The analytical solution can be obtained by solving the quasi-static field equations, which are expressed as follows [2]:

$$\nabla^2 H = j\omega\mu\sigma H \tag{5}$$

$$\nabla \cdot H = 0 \tag{6}$$

$$J = \nabla \times H. \tag{7}$$

Fig. 3 shows a laminated magnetic shunt with dimensions of $W \times 2L \times d$. It is assumed that the spatial distribution of the normal component of the magnetic field (H_z) on the surface z = 0 could be written as a double Fourier series expansion as

$$H_{z0}(x, y) = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} H_{mn} \cos\left(\frac{m\pi x}{W}\right) \sin\left(\frac{n\pi y}{L}\right)$$
(8)



Fig. 2. Magnetization curve of the M-5 steel.



Fig. 3. Laminated magnetic shunt with dimensions of $W \times 2L \times d$.

where H_{mn} are the double Fourier series coefficients, which can be calculated as follows:

$$H_{mn} = \frac{2}{WL} \int_0^W \int_{-L}^L H_{z0}(x, y) \cos\left(\frac{m\pi x}{W}\right) \sin\left(\frac{n\pi y}{L}\right).$$
(9)

For the calculation of eddy-current loss of the magnetic shunt, first, the loss corresponding to each spatial harmonic is calculated, and then, the superposition is applied in order to calculate the total shunt loss. The spatial harmonic component of (8) could be written as

$$H_{z0}(x, y) = H_{mn} \cos\left(\frac{m\pi x}{W}\right) \sin\left(\frac{n\pi y}{L}\right).$$
(10)

This equation can be used as a boundary condition for (5)–(7) in order to calculate magnetic field inside the shunt. By expanding (5) in the direction of the *z*-axis, the following equation is derived:

$$\frac{\partial^2 H_z}{\partial x^2} + \frac{\partial^2 H_z}{\partial y^2} + \frac{\partial^2 H_z}{\partial z^2} = j\omega\mu\sigma H_z.$$
 (11)

According to (10) and (11), H_z can be written as follows:

$$H_{z} = H_{mn}e^{\beta z}\cos\left(\frac{m\pi x}{W}\right)\sin\left(\frac{n\pi y}{L}\right)$$
$$\beta^{2} = j\omega\mu\sigma + \left(\frac{n\pi}{L}\right)^{2} + \left(\frac{m\pi}{W}\right)^{2}$$
(12)

where the permeability of μ is determined based on the magnetic flux density in each wall shunt, which is computed by the 3-D FEA, as well as the magnetization characteristic of the M-5 steel, which is shown in Fig. 2.

Using (6) and (12), the following equation can be derived:

$$\frac{\partial H_x}{\partial x} + \frac{\partial H_y}{\partial y} + \frac{\partial H_z}{\partial z} = 0$$
$$\frac{\partial H_x}{\partial x} + \frac{\partial H_y}{\partial y} = -H_{mn}\beta e^{\beta z}\cos\left(\frac{m\pi x}{W}\right)\sin\left(\frac{n\pi y}{L}\right).$$
(13)

Since the magnetic shunts are laminated, current cannot flow in the direction of the *z*-axis, based on (7) it can be expressed as the following equation:

$$J_z = \frac{\partial H_y}{\partial x} - \frac{\partial H_x}{\partial y} = 0.$$
(14)

It is assumed that the solution for H_x and H_y can be written as follows:

$$H_x = K_1 H_{mn} e^{\beta z} \sin\left(\frac{m\pi x}{W}\right) \sin\left(\frac{n\pi y}{L}\right)$$
$$H_y = K_2 H_{mn} e^{\beta z} \cos\left(\frac{m\pi x}{W}\right) \cos\left(\frac{n\pi y}{L}\right)$$
(15)

where K_1 and K_2 are unknown constants which can be calculated using (13) and (14) as follows:

$$K_{1} = -\frac{H_{mn}L^{2}mW\beta}{m^{2}\pi L^{2} + n^{2}\pi W^{2}}$$

$$K_{2} = \frac{H_{mn}LnW^{2}\beta}{m^{2}\pi L^{2} + n^{2}\pi W^{2}}.$$
(16)

Thus, the final solution of H_x and H_y can be expressed as following set of equations:

$$H_x = -\frac{H_{mn}L^2mW\beta}{m^2\pi L^2 + n^2\pi W^2} e^{\beta z} H_{mn} e^{\beta z} \sin\left(\frac{m\pi x}{W}\right) \sin\left(\frac{n\pi y}{L}\right)$$
$$H_y = \frac{H_{mn}LnW^2\beta}{m^2\pi L^2 + n^2\pi W^2} e^{\beta z} H_{mn} e^{\beta z} \cos\left(\frac{m\pi x}{W}\right) \cos\left(\frac{n\pi y}{L}\right).$$
(17)

Using solutions for magnetic field components (17) current density distribution can be calculated using (7) and the following equations can be deducted for the current density components J_x and J_y :

$$J_{x} = \frac{nH_{mn}[n^{2}\pi^{2}W^{2} + L^{2}(m^{2}\pi^{2} + W^{2}\beta^{2})]}{L\pi(L^{2}m^{2} + n^{2}W^{2})}$$
$$\times e^{\beta z}\cos\left(\frac{m\pi x}{W}\right)\cos\left(\frac{n\pi y}{L}\right)$$
$$J_{y} = \frac{mH_{mn}[n^{2}\pi^{2}W^{2} + L^{2}(m^{2}\pi^{2} + W^{2}\beta^{2})]}{W\pi(L^{2}m^{2} + n^{2}W^{2})}$$
$$\times e^{\beta z}\sin\left(\frac{m\pi x}{W}\right)\sin\left(\frac{n\pi y}{L}\right).$$
(18)

Using (18), spatial distribution of eddy-current loss density can be expressed as follows:

$$P_{v} = \frac{J.J^{*}}{2\sigma} = \frac{H_{mn}^{2}L^{2}W^{2}\mu^{2}\sigma\omega^{2}}{2\pi^{2}(L^{2}m^{2} + n^{2}W^{2})^{2}}e^{-2\text{Real}(\beta)} \\ \times \left[n^{2}W^{2}\cos^{2}\left(\frac{m\pi x}{W}\right)\cos^{2}\left(\frac{n\pi y}{L}\right) \\ + m^{2}L^{2}\sin^{2}\left(\frac{m\pi x}{W}\right)\sin^{2}\left(\frac{n\pi y}{L}\right)\right].$$
(19)



Fig. 4. Convergence of the eddy-current loss series expansion presented in (4) for the case study transformer.



Fig. 5. Mesh of the case study transformer model without wall shunts consisting of 817155 elements.

And the solution for the calculation of loss due to the normal component of magnetic field at z = 0 surface can be derived as follows:

$$P_{mn} = \int_{-\infty}^{0} \int_{-L}^{L} \int_{-W/2}^{W/2} P_{\nu} dx dy dz$$

= $\frac{H_{mn}^2 L^3 W^3 \mu^2 \sigma \omega^2}{8\pi^2 (L^2 m^2 + n^2 W^2) \text{Real}(\beta)}.$ (20)

Using (4) and (20), the total eddy-current loss of the magnetic shunt shown in Fig. 3 can be written as follows:

$$P = \frac{\mu^2 \sigma \omega^2}{8\pi^2} \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} \frac{L^3 W^3 H_{mn}^2}{(L^2 m^2 + n^2 W^2) \text{Real}(\beta)}.$$
 (21)

Equation (21) presents the series expansion of the eddycurrent losses of a magnetic shunt based on the Fourier series expansion of magnetic field on its surface.

For the calculation of magnetic shunts losses based on the presented analytical method, magnetic field distribution on the shunts surface is calculated with 3-D FEA using



Fig. 6. Eddy-current loss density (W/m^2) distribution on transformers tank without any magnetic shunts.

TABLE I Comparison of Stray Losses in Different Wall Shunt Arrangements

| Parameter | Without Shunts | Vertical Shunts | Horizontal Shunts |
|---------------------------|-------------------|--------------------|----------------------|
| Tank Loss (W) | 58993 | 5981 | 5458 |
| Yoke-Beam Loss (W) | 17893 | 5439 | 5368 |
| Shunt Loss (W) | _ | 1740 | 2236 |
| Total Loss (W) | 76886 | 13160 | 13062 |
| Total Loss Reduction (%) | _ | 82.88 | 83.01 |
| Total Shunt Weight (kg) | _ | 2671 | 2009 |

COMSOL Multiphysics. The calculated magnetic field distribution is exported into MATLAB and the double Fourier series coefficients of (8) are calculated using (21), and thus, the total loss of the magnetic shunt can be obtained. Fig. 4 shows the convergence of (21) for a sample vertical magnetic shunt. Fig. 4 shows that by expanding this equation up to the 15th component in both the x and y axes, the convergence error would be less than 0.1%.

IV. RESULTS AND DISCUSSION

In this section, the 200 MVA transformer shown in Fig. 1(a) and (b) is considered as a case study to compute the stray losses of tank, yoke beams, and magnetic shunts for three scenarios: transformer without magnetic shunts, transformer with the vertical magnetic shunts, and transformer with the horizontal magnetic shunts. In Sections IV-A–IV-C, the results are presented and comparisons are made.

A. Transformer Without Magnetic Shunts

In this case, the transformer carrying full load is considered and the stray losses in tank walls and yoke beams are calculated. The mesh of the 3-D model consists of 817 155 elements and is shown in Fig. 5. The total stray loss is 76.89 kW. The results are presented in Table I. Fig. 6 shows the loss density distribution in W/m² on tank walls. As it can be seen the loss density on the tank walls in the area between adjacent



Fig. 7. Magnetic leakage flux lines diverted by the vertical magnetic shunts.



Fig. 8. Magnetic flux distribution (Tesla) in the vertical magnetic shunts.

windings is lower than the other areas of the tank walls, which is the cause of leakage flux cancelation of adjacent windings. On the other hand, the maximum loss density occurs on the side tank wall. Also, the loss density distribution has a completely different pattern on main tank walls compared with side tank wall.

B. Transformer With Vertical Magnetic Shunts

In this case, vertical magnetic wall shunts are used to reduce stray losses. In front of windings on each limb of the transformer, five laminated shunts are placed on the tank walls. Shunts are not placed on tap-changer side of the tank due to its low stray loss. The mesh of the 3-D model consists of 2182 302 elements. The calculation results are presented in Table I. Fig. 7 shows the magnetic leakage flux lines. Fig. 7 shows that the flux lines are completely diverted by magnetic shunts and as a result, the eddy-current losses in the tank walls and the yoke beams are reduced 82.88% when compared with the transformer without wall shunts. The magnetic flux distribution in the vertical magnetic shunts is shown in Fig. 8.



Fig. 9. Induced current density streamlines on vertical shunt packets surfaces.



Fig. 10. Magnetic leakage flux lines diverted by the horizontal magnetic shunts.

Fig. 8 shows that the flux is not distributed uniformly in the shunt packets and it is higher on the side shunt packets. Also, it can be seen that wall shunts in the center phase have a lower flux density. Therefore, the thickness of these shunts can be reduced. Fig. 9 shows the induced current density streamlines on vertical shunt packet surfaces of one phase.

C. Transformer With Horizontal Magnetic Shunts

In this case, the horizontal and vertical magnetic wall shunts are used to reduce stray losses. In front of the three phases of the transformer, six horizontal laminated shunts are placed on the tank walls (three shunts at top and three shunts at bottom). The mesh of the 3-D model consists of 1853022 elements. The calculation results are presented in Table I. Fig. 10 shows the magnetic leakage flux lines. Fig. 10 shows that the flux lines are completely diverted by the horizontal



Fig. 11. Magnetic flux distribution (Tesla) in the horizontal and vertical magnetic shunts.



Fig. 12. Parametric FEA results on the vertical position of horizontal shunts. (a) Losses in tank walls, yoke beams, and magnetic shunts. (b) Total losses.

magnetic shunts, and as a result, the total eddy-current losses in the tank walls and the yoke beams are reduced by 83.01% compared with the transformer without wall shunts. Based on Table I, it can be seen that by using the horizontal shunts the total weight of the shunts is reduced by 25% when compared with the vertical shunts while stray losses are almost the same. Thus using horizontal shunt walls would be very cost effective. The magnetic flux distribution in the horizontal and vertical magnetic shunts is shown in Fig. 11. Comparing Figs. 8 and 11 it can be concluded that the flux density in the horizontal arrangements of shunts is higher than vertical arrangements and as a result, the loss density in the horizontal shunts will be higher. Also, it can be seen in Table I that although the total shunt weight with the horizontal shunts is 25% lower compared with the vertical shunts, the shunt losses is 28.5% higher.

Also, parametric FEA was carried out to find the optimal position of the horizontal magnetic shunts for maximum performance. In Fig. 12, the losses versus the gap between yoke beams and the horizontal magnetic shunts are presented. Fig. 12 shows that with 150 mm overlap of the horizontal shunts and yoke beams, the transformer will have the minimum stray losses.

V. CONCLUSION

A new method for magnetic shielding of the tank walls in large power transformers has been proposed in this paper. The presented method is based on a horizontal arrangement of magnetic shunts on tank walls. It is shown that the horizontal shunts are as effective as the vertical shunts in reducing stray load losses. However, the horizontal shunts weigh 25% less than the vertical shunts. Hence, the proposed horizontal magnetic shunts arrangement is very cost effective. The proposed combined FEM and analytical method provides an effective and accurate method for the calculation of induced current densities and corresponding eddy-current losses in magnetic wall shunts. It is shown that the flux is not uniformly distributed in the shunt packets; it is higher in the side packets. Also, wall shunt packets in front of the center limb have lower flux densities. Consequently, the thickness of these shunts can be reduced. Furthermore, parametric FEA can be used to find the optimal placement of the magnetic shunts on the tank walls.

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